Digraphs

Version 0.15.2

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Abstract

The Digraphs package is a GAP package containing methods for graphs, digraphs, and multidigraphs.

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Acknowledgements

We would like to thank Christopher Jefferson for his help in including bliss in Digraphs. This package's methods for computing digraph homomorphisms are based on work by Max Neunhöffer, and independently Artur Schäfer.

Contents

Chapter 1

The Digraphs package

1.1 Introduction

This is the manual for the Digraphs package version 0.15.2. This package was developed at the University of St Andrews by:

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- Wilf A. Wilson.

Additional contributions were made by:

- Stuart Burrell,
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- Christopher Jefferson,
- Markus Pfeiffer,
- Chris Russell, and
- Finn Smith.

The Digraphs package contains a variety of methods for efficiently creating and storing digraphs and computing information about them. Full explanations of all the functions contained in the package are provided below.

If the Grape package is available, it will be loaded automatically. Digraphs created with the Digraphs package can be converted to Grape graphs with `Graph` (3.2.3), and conversely Grape graphs can be converted to Digraphs objects with `Digraph` (3.1.5). Grape is not required for Digraphs to run.

The bliss tool [JK07] is included in this package. It is an open-source tool for computing automorphism groups and canonical forms of graphs, written by Tommi Junttila and Petteri Kaski. Several

of the methods in the Digraphs package rely on bliss. If the NautyTracesInterface package for GAP is available then it is also possible to use nauty [MP14] for computing automorphism groups and canonical forms in Digraphs. See Section 7.2 for more details.

1.1.1 Definitions

For the purposes of this package and its documentation, the following definitions apply:

A *digraph* $E = (E^0, E^1, r, s)$, also known as a *directed graph*, consists of a set of vertices E^0 and a set of edges E^1 together with functions $s, r : E^1 \to E^0$, called the *source* and *range*, respectively. The source and range of an edge is respectively the values of s, r at that edge. An edge is called a *loop* if its source and range are the same. A digraph is called a *multidigraph* if there exist two or more edges with the same source and the same range.

A *directed walk* on a digraph is a sequence of alternating vertices and edges $(v_1, e_1, v_2, e_2, ..., e_{n-1}, v_n)$ such that each edge e_i has source v_i and range v_{i+1}. A *directed path* is a directed walk where no vertex (and hence no edge) is repeated. A *directed circuit* is a directed walk where $v_1 = v_n$, and a *directed cycle* is a directed circuit where where no vertex is repeated, except for $v_1 = v_n$.

The *length* of a directed walk $(v_1, e_1, v_2, e_2, ..., e_{n-1}, v_n)$ is equal to $n-1$, the number of edges it contains. A directed walk (or path) $(v_1, e_1, v_2, e_2, ..., e_{n-1}, v_n)$ is sometimes called a directed walk (or path) *from vertex* v_1 *to vertex* v_n. A directed walk of zero length, i.e. a sequence (v) for some vertex v, is called *trivial*. A trivial directed walk is considered to be both a circuit and a cycle, as is the empty directed walk $()$. A *simple circuit* is another name for a non-trivial and non-empty directed cycle.

Chapter 2

Installing Digraphs

2.1 For those in a hurry

In this section we give a brief description of how to start using Digraphs.

It is assumed that you have a working copy of GAP with version number 4.9.0 or higher. The most up-to-date version of GAP and instructions on how to install it can be obtained from the main GAP webpage http://www.gap-system.org.

The following is a summary of the steps that should lead to a successful installation of Digraphs:

- ensure that the IO package version 4.5.1 or higher is available. IO must be compiled before Digraphs can be loaded.
- ensure that the Orb package version 4.8.2 or higher is available. Orb has better performance when compiled, but although compilation is recommended, it is not required to be compiled for Digraphs to be loaded.
- THIS STEP IS OPTIONAL: certain functions in Digraphs require the Grape package to be available; see Section 2.2.1 for full details. To use these functions make sure that the Grape package version 4.8.1 or higher is available. If Grape is not available, then Digraphs can be used as normal with the exception that the functions listed in Subsection 2.2.1 will not work.
- download the package archive `digraphs-0.15.2.tar.gz` from the Digraph package webpage.
- unzip and untar the file, this should create a directory called `digraphs-0.15.2`.
- locate the `pkg` directory of your GAP directory, which contains the directories `lib`, `doc` and so on. Move the directory `digraphs-0.15.2` into the `pkg` directory.
- it is necessary to compile the Digraphs package. Inside the `pkg/digraphs-0.15.2` directory, type

```
./configure
make
```

  Further information about this step can be found in Section 2.3.

- start GAP in the usual way (i.e. type `gap` at the command line).

- type `LoadPackage("digraphs");`

If you want to check that the package is working correctly, you should run some of the tests described in Section 2.5.

2.2 Optional package dependencies

The Digraphs package is written in GAP and C code and requires the IO package. The IO package is used to read and write transformations, partial permutations, and bipartitions to a file.

2.2.1 The Grape package

The Grape package must be available for the following operations to be available:

- `Graph` (3.2.3) with a digraph argument
- `AsGraph` (3.2.4) with a digraph argument
- `Digraph` (3.1.5) with a Grape graph argument

If Grape is not available, then Digraphs can be used as normal with the exception that the functions above will not work.

2.3 Compiling the kernel module

The Digraphs package has a GAP kernel component in C which should be compiled. This component contains certain low-level functions required by Digraphs.

It is not possible to use the Digraphs package without compiling it.

To compile the kernel component inside the `pkg/digraphs-0.15.2` directory, type

```
./configure
make
```

If you installed the package in another 'pkg' directory than the standard 'pkg' directory in your GAP installation, then you have to do two things. Firstly during compilation you have to use the option '–with-gaproot=PATH' of the 'configure' script where 'PATH' is a path to the main GAP root directory (if not given the default '../..' is assumed).

If you installed GAP on several architectures, you must execute the configure/make step for each of the architectures. You can either do this immediately after configuring and compiling GAP itself on this architecture, or alternatively (when using version 4.5 of GAP or newer) set the environment variable 'CONFIGNAME' to the name of the configuration you used when compiling GAP before running './configure'. Note however that your compiler choice and flags (environment variables 'CC' and 'CFLAGS') need to be chosen to match the setup of the original GAP compilation. For example you have to specify 32-bit or 64-bit mode correctly!

2.4 Rebuilding the documentation

The Digraphs package comes complete with pdf, html, and text versions of the documentation. However, you might find it necessary, at some point, to rebuild the documentation. To rebuild the documentation use the `DigraphsMakeDoc` (2.4.1).

2.4.1 DigraphsMakeDoc

▷ `DigraphsMakeDoc()` (function)

Returns: Nothing

This function should be called with no argument to compile the Digraphs documentation.

2.5 Testing your installation

In this section we describe how to test that Digraphs is working as intended. To test that Digraphs is installed correctly use `DigraphsTestInstall` (2.5.1) or for more extensive tests use `DigraphsTestStandard` (2.5.2).

If something goes wrong, then please review the instructions in Section 2.1 and ensure that Digraphs has been properly installed. If you continue having problems, please use the issue tracker to report the issues you are having.

2.5.1 DigraphsTestInstall

▷ `DigraphsTestInstall()` (function)

Returns: `true` or `false`.

This function should be called with no argument to test your installation of Digraphs is working correctly. These tests should take no more than a fraction of a second to complete. To test more comprehensively that Digraphs is working correctly, use `DigraphsTestStandard` (2.5.2).

2.5.2 DigraphsTestStandard

▷ `DigraphsTestStandard()` (function)

Returns: `true` or `false`.

This function should be called to test all the methods included in Digraphs. These tests should take only a few seconds to complete.

To quickly test that Digraphs is installed correctly use `DigraphsTestInstall` (2.5.1). For a more thorough test, use `DigraphsTestStandard`.

Chapter 3

Creating digraphs

In this chapter we describe how to create digraphs.

3.1 Creating digraphs

3.1.1 IsDigraph

▷ `IsDigraph` (Category)

Every digraph in Digraphs belongs to the category `IsDigraph`. Basic attributes and operations for digraphs are: `DigraphVertices` (5.1.1), `DigraphRange` (5.2.5), `DigraphSource` (5.2.5), `OutNeighbours` (5.2.6), and `DigraphEdges` (5.1.3).

3.1.2 IsCayleyDigraph

▷ `IsCayleyDigraph` (Category)

`IsCayleyDigraph` is a subcategory of `IsDigraph`. Digraphs that are Cayley digraphs of a group and that are constructed by the operation `CayleyDigraph` (3.1.10) are constructed in this category.

3.1.3 IsDigraphWithAdjacencyFunction

▷ `IsDigraphWithAdjacencyFunction` (Category)

`IsDigraphWithAdjacencyFunction` is a subcategory of `IsDigraph`. Digraphs that are *created* using an adjacency function are constructed in this category.

3.1.4 DigraphType

▷ `DigraphType` (global variable)
▷ `DigraphFamily` (family)

The type of all digraphs is `DigraphType`. The family of all digraphs is `DigraphFamily`.

3.1.5 Digraph

▷ Digraph(*obj*[, *source*, *range*]) (operation)
▷ Digraph(*list*, *func*) (operation)
▷ Digraph(*G*, *list*, *act*, *adj*) (operation)

Returns: A digraph.

for a list (i.e. an adjacency list)

if *obj* is a list of lists of positive integers in the range from 1 to Length(*obj*), then this function returns the digraph with vertices E^0 = [1 .. Length(*obj*)], and edges corresponding to the entries of *obj*.

More precisely, there is an edge from vertex i to j if and only if j is in *obj*[i]; the source of this edge is i and the range is j. If j occurs in *obj*[i] with multiplicity k, then there are k edges from i to j.

for three lists

if *obj* is a duplicate-free list, and *source* and *range* are lists of equal length consisting of positive integers in the list [1 .. Length(*obj*)], then this function returns a digraph with vertices E^0 = [1 .. Length(*obj*)], and Length(*source*) edges. For each i in [1 .. Length(*source*)] there exists an edge with source vertex source[i] and range vertex range[i]. See DigraphSource (5.2.5) and DigraphRange (5.2.5).

The vertices of the digraph will be labelled by the elements of *obj*.

for an integer, and two lists

if *obj* is an integer, and *source* and *range* are lists of equal length consisting of positive integers in the list [1 .. *obj*], then this function returns a digraph with vertices E^0 = [1 .. *obj*], and Length(*source*) edges. For each i in [1 .. Length(*source*)] there exists an edge with source vertex source[i] and range vertex range[i]. See DigraphSource (5.2.5) and DigraphRange (5.2.5).

for a list and a function

if *list* is a list and *func* is a function taking 2 arguments that are elements of *list*, and *func* returns true or false, then this operation creates a digraph with vertices [1 .. Length(*list*)] and an edge from vertex i to vertex j if and only if *func*(*list*[i], *list*[j]) returns true.

for a group, a list, and two functions

The arguments will be *G*, *list*, *act*, *adj*.

Let *G* be a group acting on the objects in *list* via the action *act*, and let *adj* be a function taking two objects from *list* as arguments and returning true or false. The function *adj* will describe the adjacency between objects from *list*, which is invariant under the action of *G*. This variant of the constructor returns a digraph with vertices the objects of *list* and directed edges [x, y] when f(x, y) is true.

The action of the group *G* on the objects in *list* is stored in the attribute DigraphGroup (7.2.9), and is used to speed up operations like DigraphDiameter (5.3.1).

for a Grape package graph

if *obj* is a Grape package graph (i.e. a record for which the function IsGraph returns true), then this function returns a digraph isomorphic to *obj*.

for a binary relation

if *obj* is a binary relation on the points [1 .. n] for some posititve integer *n*, then this function returns the digraph defined by *obj*. Specifically, this function returns a digraph which has *n* vertices, and which has an edge with source i and range j if and only if [i,j] is a pair in the binary relation *obj*.

Example

```
gap> gr := Digraph([
> [2, 5, 8, 10], [2, 3, 4, 2, 5, 6, 8, 9, 10], [1],
> [3, 5, 7, 8, 10], [2, 5, 7], [3, 6, 7, 9, 10], [1, 4],
> [1, 5, 9], [1, 2, 7, 8], [3, 5]]);
<multidigraph with 10 vertices, 38 edges>
gap> gr := Digraph(["a", "b", "c"], ["a"], ["b"]);
<digraph with 3 vertices, 1 edge>
gap> gr := Digraph(5, [1, 2, 2, 4, 1, 1], [2, 3, 5, 5, 1, 1]);
<multidigraph with 5 vertices, 6 edges>
gap> Petersen := Graph(SymmetricGroup(5), [[1, 2]], OnSets,
> function(x, y) return Intersection(x, y) = []; end);;
gap> Digraph(Petersen);
<digraph with 10 vertices, 30 edges>
gap> b := BinaryRelationOnPoints(
> [[3], [1, 3, 5], [1], [1, 2, 4], [2, 3, 5]]);
Binary Relation on 5 points
gap> gr := Digraph(b);
<digraph with 5 vertices, 11 edges>
gap> gr := Digraph([1 .. 10], ReturnTrue);
<digraph with 10 vertices, 100 edges>
```

The next example illustrates the uses of the fourth and fifth variants of this constructor. The resulting digraph is a strongly regular graph, and it is actually the point graph of the van Lint-Schrijver partial geometry, [vLS81]. The algebraic description is taken from the seminal paper of Calderbank and Kantor [CK86].

Example

```
gap> f := GF(3 ^ 4);
GF(3^4)
gap> gamma := First(f, x -> Order(x) = 5);
Z(3^4)^64
gap> L := Union([Zero(f)], List(Group(gamma)));
[ 0*Z(3), Z(3)^0, Z(3^4)^16, Z(3^4)^32, Z(3^4)^48, Z(3^4)^64 ]
gap> omega := Union(List(L, x -> List(Difference(L, [x]), y -> x - y)));
[ Z(3)^0, Z(3), Z(3^4)^5, Z(3^4)^7, Z(3^4)^8, Z(3^4)^13, Z(3^4)^15,
  Z(3^4)^16, Z(3^4)^21, Z(3^4)^23, Z(3^4)^24, Z(3^4)^29, Z(3^4)^31,
  Z(3^4)^32, Z(3^4)^37, Z(3^4)^39, Z(3^4)^45, Z(3^4)^47, Z(3^4)^48,
  Z(3^4)^53, Z(3^4)^55, Z(3^4)^56, Z(3^4)^61, Z(3^4)^63, Z(3^4)^64,
  Z(3^4)^69, Z(3^4)^71, Z(3^4)^72, Z(3^4)^77, Z(3^4)^79 ]
gap> adj := function(x, y)
>   return x - y in omega;
> end;
function( x, y ) ... end
gap> digraph := Digraph(AsList(f), adj);
<digraph with 81 vertices, 2430 edges>
gap> group := Group(Z(3));
```

```
<group with 1 generators>
gap> act := \*;
<Operation "*">
gap> digraph := Digraph(group, List(f), act, adj);
<digraph with 81 vertices, 2430 edges>
```

3.1.6 DigraphByAdjacencyMatrix

▷ `DigraphByAdjacencyMatrix(`*adj*`)` (operation)

Returns: A digraph.

If *adj* is the adjacency matrix of a digraph in the sense of `AdjacencyMatrix` (5.2.1), then this operation returns the digraph which is defined by *adj*.

Alternatively, if *adj* is a square boolean matrix, then this operation returns the digraph with `Length(`*adj*`)` vertices which has the edge `[i,j]` if and only if *adj*`[i][j]` is `true`.

Example

```
gap> DigraphByAdjacencyMatrix([
> [0, 1, 0, 2, 0],
> [1, 1, 1, 0, 1],
> [0, 3, 2, 1, 1],
> [0, 0, 1, 0, 1],
> [2, 0, 0, 0, 0]]);
<multidigraph with 5 vertices, 18 edges>
gap> gr := DigraphByAdjacencyMatrix([
> [true, false, true],
> [false, false, true],
> [false, true, false]]);
<digraph with 3 vertices, 4 edges>
gap> OutNeighbours(gr);
[ [ 1, 3 ], [ 3 ], [ 2 ] ]
```

3.1.7 DigraphByEdges

▷ `DigraphByEdges(`*edges*`[, `*n*`])` (operation)

Returns: A digraph.

If *edges* is list of pairs of positive integers, then this function returns the digraph with the minimum number of vertices `m` such that its edges equal *edges*.

If the optional second argument *n* is a positive integer with *n* `>= m` (with `m` defined as above), then this function returns the digraph with *n* vertices and edges *edges*.

See `DigraphEdges` (5.1.3).

Example

```
gap> DigraphByEdges(
> [[1, 3], [2, 1], [2, 3], [2, 5], [3, 6],
>  [4, 6], [5, 2], [5, 4], [5, 6], [6, 6]]);
<digraph with 6 vertices, 10 edges>
gap> DigraphByEdges(
> [[1, 3], [2, 1], [2, 3], [2, 5], [3, 6],
>  [4, 6], [5, 2], [5, 4], [5, 6], [6, 6]], 12);
<digraph with 12 vertices, 10 edges>
```

3.1.8 EdgeOrbitsDigraph

▷ EdgeOrbitsDigraph(*G, edges[, n]*) (operation)

Returns: A new digraph.

If *G* is a permutation group, *edges* is an edge or list of edges, and *n* is a non-negative integer such that *G* fixes [1 .. *n*] setwise, then this operation returns a new digraph with *n* vertices and the union of the orbits of the edges in *edges* under the action of the permutation group *G*. An edge in this context is simply a pair of positive integers.

If the optional third argument *n* is not present, then the largest moved point of the permutation group *G* is used by default.

Example

```
gap> digraph := EdgeOrbitsDigraph(Group((1, 3), (1, 2)(3, 4)),
>                                 [[1, 2], [4, 5]], 5);
<digraph with 5 vertices, 12 edges>
gap> OutNeighbours(digraph);
[ [ 2, 4, 5 ], [ 1, 3, 5 ], [ 2, 4, 5 ], [ 1, 3, 5 ], [  ] ]
gap> RepresentativeOutNeighbours(digraph);
[ [ 2, 4, 5 ], [  ] ]
```

3.1.9 DigraphByInNeighbours

▷ DigraphByInNeighbours(*in*) (operation)

▷ DigraphByInNeighbors(*in*) (operation)

Returns: A digraph.

If *in* is a list of lists of positive integers in the range [1 .. Length(*in*)], then this function returns the digraph with vertices $E^0 =$ [1 .. Length(*in*)], and edges corresponding to the entries of *in*. More precisely, there is an edge with source vertex i and range vertex j if i is in *in*[j].

If i occurs in *in*[j] with multiplicity k, then there are k multiple edges from i to j.

See InNeighbours (5.2.7).

Example

```
gap> gr := DigraphByInNeighbours([
> [2, 5, 8, 10], [2, 3, 4, 5, 6, 8, 9, 10],
> [1], [3, 5, 7, 8, 10], [2, 5, 7], [3, 6, 7, 9, 10], [1, 4],
> [1, 5, 9], [1, 2, 7, 8], [3, 5]]);
<digraph with 10 vertices, 37 edges>
gap> gr := DigraphByInNeighbours([[2, 3, 2], [1], [1, 2, 3]]);
<multidigraph with 3 vertices, 7 edges>
```

3.1.10 CayleyDigraph

▷ CayleyDigraph(*G[, gens]*) (operation)

Returns: A digraph.

Let *G* be any group and let *gens* be a list of elements of *G*. This function returns the Cayley graph of the group with respect *gens*. The vertices are the elements of *G*. There exists an edge from the vertex u to the vertex v if and only if there exists a generator g in *gens* such that x * g = y.

If the optional second argument *gens* is not present, then the generators of *G* are used by default. The digraph created by this operation belongs to the category IsCayleyDigraph (3.1.2), the group *G* can be recovered from the digraph using GroupOfCayleyDigraph (5.4.1), and the generators *gens* can be obtained using GeneratorsOfCayleyDigraph (5.4.2).

Example

```
gap> G := DihedralGroup(8);
<pc group of size 8 with 3 generators>
gap> CayleyDigraph(G);
<digraph with 8 vertices, 24 edges>
gap> G := DihedralGroup(IsPermGroup, 8);
Group([ (1,2,3,4), (2,4) ])
gap> CayleyDigraph(G);
<digraph with 8 vertices, 16 edges>
gap> digraph := CayleyDigraph(G, [()]);
<digraph with 8 vertices, 8 edges>
gap> GroupOfCayleyDigraph(digraph) = G;
true
gap> GeneratorsOfCayleyDigraph(digraph);
[ () ]
```

3.2 Changing representations

3.2.1 AsBinaryRelation

▷ AsBinaryRelation(*digraph*) (operation)

Returns: A binary relation.

If *digraph* is a digraph with a positive number of vertices *n*, and no multiple edges, then this operation returns a binary relation on the points [1..n]. The pair [i,j] is in the binary relation if and only if [i,j] is an edge in *digraph*.

Example

```
gap> gr := Digraph([[3, 2], [1, 2], [2], [3, 4]]);
<digraph with 4 vertices, 7 edges>
gap> AsBinaryRelation(gr);
Binary Relation on 4 points
```

3.2.2 AsDigraph

▷ AsDigraph(*trans*[, *n*]) (operation)

Returns: A digraph, or fail.

If *trans* is a transformation, and *n* is a non-negative integer such that the restriction of *trans* to [1 .. *n*] defines a transformation of [1 .. *n*], then AsDigraph returns the functional digraph with *n* vertices defined by *trans*. See IsFunctionalDigraph (6.1.7).

Specifically, the digraph returned by AsDigraph has *n* edges: for each vertex x in [1 .. *n*], there is a unique edge with source x; this edge has range x^*trans*.

If the optional second argument *n* is not supplied, then the degree of the transformation *trans* is used by default. If the restriction of *trans* to [1 .. *n*] does not define a transformation of [1 .. *n*], then AsDigraph(*trans*, *n*) returns fail.

Example

```
gap> f := Transformation([4, 3, 3, 1, 7, 9, 10, 4, 2, 3]);
Transformation( [ 4, 3, 3, 1, 7, 9, 10, 4, 2, 3 ] )
gap> AsDigraph(f);
<digraph with 10 vertices, 10 edges>
gap> AsDigraph(f, 4);
```

```
<digraph with 4 vertices, 4 edges>
gap> AsDigraph(f, 5);
fail
```

3.2.3 Graph

▷ Graph(*digraph*) (operation)

Returns: A Grape package graph.

If *digraph* is a digraph without multiple edges, then this operation returns a Grape package graph that is isomorphic to *digraph*.

If *digraph* is a multidigraph, then since Grape does not support multiple edges, the multiple edges will be reduced to a single edge in the result. In order words, for a multidigraph this operation will return the same as Graph(DigraphRemoveAllMultipleEdges(*digraph*)).

Example

```
gap> Petersen := Graph(SymmetricGroup(5), [[1, 2]], OnSets,
> function(x, y) return Intersection(x, y) = []; end);
rec( adjacencies := [ [ 3, 5, 8 ] ], group := Group([ (1,2,3,5,7)
  (4,6,8,9,10), (2,4)(6,9)(7,10) ]), isGraph := true,
  names := [ [ 1, 2 ], [ 2, 3 ], [ 3, 4 ], [ 1, 3 ], [ 4, 5 ],
      [ 2, 4 ], [ 1, 5 ], [ 3, 5 ], [ 1, 4 ], [ 2, 5 ] ],
  order := 10, representatives := [ 1 ],
  schreierVector := [ -1, 1, 1, 2, 1, 1, 1, 1, 2, 2 ] )
gap> Digraph(Petersen);
<digraph with 10 vertices, 30 edges>
gap> Graph(last);
rec( adjacencies := [ [ 3, 5, 8 ] ], group := Group([ (1,2,3,5,7)
  (4,6,8,9,10), (2,4)(6,9)(7,10) ]), isGraph := true,
  names := [ [ 1, 2 ], [ 2, 3 ], [ 3, 4 ], [ 1, 3 ], [ 4, 5 ],
      [ 2, 4 ], [ 1, 5 ], [ 3, 5 ], [ 1, 4 ], [ 2, 5 ] ],
  order := 10, representatives := [ 1 ],
  schreierVector := [ -1, 1, 1, 2, 1, 1, 1, 1, 2, 2 ] )
```

3.2.4 AsGraph

▷ AsGraph(*digraph*) (attribute)

Returns: A Grape package graph.

If *digraph* is a digraph, then this method returns the same as Graph (3.2.3), except that the result will be stored as a mutable attribute of *digraph*.

If AsGraph(*digraph*) is called subsequently, then the same GAP object will be returned as before.

Example

```
gap> d := Digraph([[1, 2], [3], []]);
<digraph with 3 vertices, 3 edges>
gap> g := AsGraph(d);
rec( adjacencies := [ [ 1, 2 ], [ 3 ], [  ] ], group := Group(()),
  isGraph := true, names := [ 1 .. 3 ], order := 3,
  representatives := [ 1, 2, 3 ], schreierVector := [ -1, -2, -3 ] )
```

3.2.5 AsTransformation

▷ `AsTransformation(`*digraph*`)` (attribute)

Returns: A transformation, or `fail`

If *digraph* is a functional digraph, then `AsTransformation` returns the transformation which is defined by *digraph*. See `IsFunctionalDigraph` (6.1.7). Otherwise, `AsTransformation(`*digraph*`)` returns `fail`.

If *digraph* is a functional digraph with n vertices, then `AsTransformation(`*digraph*`)` will return the transformation `f` of degree at most n where for each $1 \leq i \leq n$, `i ^ f` is equal to the unique out-neighbour of vertex `i` in *digraph*.

Example

```
gap> gr := Digraph([[1], [3], [2]]);
<digraph with 3 vertices, 3 edges>
gap> gr := CycleDigraph(3);
<digraph with 3 vertices, 3 edges>
gap> AsTransformation(gr);
Transformation( [ 2, 3, 1 ] )
gap> AsPermutation(last);
(1,2,3)
gap> gr := Digraph([[2, 3], [], []]);
<digraph with 3 vertices, 2 edges>
gap> AsTransformation(gr);
fail
```

3.3 New digraphs from old

3.3.1 DigraphCopy

▷ `DigraphCopy(`*digraph*`)` (operation)

Returns: A digraph.

This function returns a new copy of *digraph*, retaining none of the attributes or properties of *digraph*.

Example

```
gap> gr := CycleDigraph(10);
<digraph with 10 vertices, 10 edges>
gap> DigraphCopy(gr) = gr;
true
```

3.3.2 InducedSubdigraph

▷ `InducedSubdigraph(`*digraph*`, `*verts*`)` (operation)

Returns: A digraph.

If *digraph* is a digraph, and *verts* is a subset of the vertices of *digraph*, then this operation returns a digraph constructed from *digraph* by retaining precisely those vertices in *verts*, and those edges whose source and range vertices are both contained in *verts*.

The vertices of the induced subdigraph are `[1..Length(verts)]` but the original vertex labels can be accessed via `DigraphVertexLabels` (5.1.9).

Example

```
gap> gr := Digraph([[1, 1, 2, 3, 4, 4], [1, 3, 4], [3, 1], [1, 1]]);
<multidigraph with 4 vertices, 13 edges>
gap> InducedSubdigraph(gr, [1, 3, 4]);
<multidigraph with 3 vertices, 9 edges>
gap> DigraphVertices(last);
[ 1 .. 3 ]
```

3.3.3 ReducedDigraph

▷ `ReducedDigraph(`*digraph*`)` (attribute)

Returns: A digraph.

This function returns a digraph isomorphic to the subdigraph of *digraph* induced by the set of non-isolated vertices, i.e. the set of those vertices of *digraph* which are the source or range of some edge in *digraph*. See `InducedSubdigraph` (3.3.2).

The vertex and edge labels of the graph are preserved. A vertex in the new digraph can be matched to the corresponding vertex in *digraph* by using the label.

The ordering of the vertices is preserved.

Example

```
gap> d := Digraph([[1, 2], [], [], [1, 4], []]);
<digraph with 5 vertices, 4 edges>
gap> r := ReducedDigraph(d);
<digraph with 3 vertices, 4 edges>
gap> OutNeighbours(r);
[ [ 1, 2 ], [  ], [ 1, 3 ] ]
gap> DigraphEdges(d);
[ [ 1, 1 ], [ 1, 2 ], [ 4, 1 ], [ 4, 4 ] ]
gap> DigraphEdges(r);
[ [ 1, 1 ], [ 1, 2 ], [ 3, 1 ], [ 3, 3 ] ]
gap> DigraphVertexLabel(r, 3);
4
gap> DigraphVertexLabel(r, 2);
2
```

3.3.4 MaximalSymmetricSubdigraph

▷ `MaximalSymmetricSubdigraph(`*digraph*`)` (attribute)

▷ `MaximalSymmetricSubdigraphWithoutLoops(`*digraph*`)` (attribute)

Returns: A digraph.

If *digraph* is a digraph, then `MaximalSymmetricSubdigraph` returns a symmetric digraph without multiple edges which has the same vertex set as *digraph*, and whose edge list is formed from *digraph* by ignoring the multiplicity of edges, and by ignoring edges `[u,v]` for which there does not exist an edge `[v,u]`.

The digraph returned by `MaximalSymmetricSubdigraphWithoutLoops` is the same, except that loops are removed.

See `IsSymmetricDigraph` (6.1.10), `IsMultiDigraph` (6.1.8), and `DigraphHasLoops` (6.1.1) for more information.

Example

```
gap> gr := Digraph([[2, 2], [1, 3], [4], [3, 1]]);
<multidigraph with 4 vertices, 7 edges>
```

```
gap> not IsSymmetricDigraph(gr) and IsMultiDigraph(gr);
true
gap> OutNeighbours(gr);
[ [ 2, 2 ], [ 1, 3 ], [ 4 ], [ 3, 1 ] ]
gap> sym := MaximalSymmetricSubdigraph(gr);
<digraph with 4 vertices, 4 edges>
gap> IsSymmetricDigraph(sym) and not IsMultiDigraph(sym);
true
gap> OutNeighbours(sym);
[ [ 2 ], [ 1 ], [ 4 ], [ 3 ] ]
```

3.3.5 MaximalAntiSymmetricSubdigraph

▷ MaximalAntiSymmetricSubdigraph(*digraph*) (attribute)

Returns: A digraph.

If *digraph* is a digraph, then MaximalAntiSymmetricSubdigraph returns a anti-symmetric subdigraph of *digraph* which does not have multiple edges, has the same vertex set as *digraph*, and whose edge list is formed from *digraph* by ignoring the multiplicity of edges, and by having either an edge from the vertex u to the vertex v, or the edge from v to u (but not both) whenever both edges belong to *digraph*.

See IsAntisymmetricDigraph (6.1.2) for more information.

Example

```
gap> D := Digraph([[2, 2], [1, 3], [4], [3, 1]]);
<multidigraph with 4 vertices, 7 edges>
gap> not IsAntiSymmetricDigraph(D) and IsMultiDigraph(D);
true
gap> OutNeighbours(D);
[ [ 2, 2 ], [ 1, 3 ], [ 4 ], [ 3, 1 ] ]
gap> D := MaximalAntiSymmetricSubdigraph(D);
<digraph with 4 vertices, 4 edges>
gap> IsAntiSymmetricDigraph(D) and not IsMultiDigraph(D);
true
gap> OutNeighbours(D);
[ [ 2 ], [ 3 ], [ 4 ], [ 1 ] ]
```

3.3.6 UndirectedSpanningTree

▷ UndirectedSpanningTree(*digraph*) (attribute)

▷ UndirectedSpanningForest(*digraph*) (attribute)

Returns: A digraph, or fail.

If *digraph* is a digraph with at least one vertex, then UndirectedSpanningForest returns an undirected spanning forest of *digraph*, otherwise this attribute returns fail. See IsUndirectedSpanningForest (4.1.2) for the definition of an undirected spanning forest.

If *digraph* is a digraph with at least one vertex and whose MaximalSymmetricSubdigraph (3.3.4) is connected (see IsConnectedDigraph (6.3.3)), then UndirectedSpanningTree returns an undirected spanning tree of *digraph*, otherwise this attribute returns fail. See IsUndirectedSpanningTree (4.1.2) for the definition of an undirected spanning tree.

Note that for a digraph that has an undirected spanning tree, the attribute UndirectedSpanningTree returns the same digraph as the attribute UndirectedSpanningForest.

Example

```
gap> gr := Digraph([[1, 2, 1, 3], [1], [4], [3, 4, 3]]);
<multidigraph with 4 vertices, 9 edges>
gap> UndirectedSpanningTree(gr);
fail
gap> forest := UndirectedSpanningForest(gr);
<digraph with 4 vertices, 4 edges>
gap> OutNeighbours(forest);
[ [ 2 ], [ 1 ], [ 4 ], [ 3 ] ]
gap> IsUndirectedSpanningForest(gr, forest);
true
gap> DigraphConnectedComponents(forest).comps;
[ [ 1, 2 ], [ 3, 4 ] ]
gap> DigraphConnectedComponents(MaximalSymmetricSubdigraph(gr)).comps;
[ [ 1, 2 ], [ 3, 4 ] ]
gap> UndirectedSpanningForest(MaximalSymmetricSubdigraph(gr))
> = forest;
true
gap> gr := CompleteDigraph(4);
<digraph with 4 vertices, 12 edges>
gap> tree := UndirectedSpanningTree(gr);
<digraph with 4 vertices, 6 edges>
gap> IsUndirectedSpanningTree(gr, tree);
true
gap> tree = UndirectedSpanningForest(gr);
true
gap> UndirectedSpanningForest(EmptyDigraph(0));
fail
```

3.3.7 QuotientDigraph

▷ QuotientDigraph(*digraph*, *p*) (operation)

Returns: A digraph.

If *digraph* is a digraph, and *p* is a partition of the vertices of *digraph*, then this operation returns a new digraph constructed by amalgamating all vertices of *digraph* which lie in the same part of *p*.

A partition of the vertices of *digraph* is a list of non-empty disjoint lists, such that the union of all the sub-lists is equal to the vertex set of *digraph*. In particular, each vertex must appear in precisely one sub-list.

The vertices of *digraph* in part `i` of *p* will become vertex `i` in the quotient, and every edge of *digraph* with source in part `i` and range in part `j` becomes an edge from `i` to `j` in the quotient. In particular, this means that the quotient of a digraph without multiple edges can have multiple edges.

Example

```
gap> gr := Digraph([[2, 1], [4], [1], [1, 3, 4]]);
<digraph with 4 vertices, 7 edges>
gap> DigraphVertices(gr);
[ 1 .. 4 ]
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 1, 1 ], [ 2, 4 ], [ 3, 1 ], [ 4, 1 ], [ 4, 3 ],
  [ 4, 4 ] ]
gap> p := [[1], [2, 4], [3]];
[ [ 1 ], [ 2, 4 ], [ 3 ] ]
```

```
gap> qr := QuotientDigraph(gr, p);
<multidigraph with 3 vertices, 7 edges>
gap> DigraphVertices(qr);
[ 1 .. 3 ]
gap> DigraphEdges(qr);
[ [ 1, 2 ], [ 1, 1 ], [ 2, 2 ], [ 2, 1 ], [ 2, 3 ], [ 2, 2 ],
  [ 3, 1 ] ]
gap> QuotientDigraph(EmptyDigraph(0), []);
<digraph with 0 vertices, 0 edges>
```

3.3.8 DigraphReverse

▷ `DigraphReverse(`*`digraph`*`)` (operation)

Returns: A digraph.

If *`digraph`* is a digraph, then this operation returns a digraph constructed from *`digraph`* by reversing the orientation of every edge.

Example

```
gap> gr := Digraph([[3], [1, 3, 5], [1], [1, 2, 4], [2, 3, 5]]);
<digraph with 5 vertices, 11 edges>
gap> DigraphReverse(gr);
<digraph with 5 vertices, 11 edges>
gap> OutNeighbours(last);
[ [ 2, 3, 4 ], [ 4, 5 ], [ 1, 2, 5 ], [ 4 ], [ 2, 5 ] ]
gap> gr := Digraph([[2, 4], [1], [4], [3, 4]]);
<digraph with 4 vertices, 6 edges>
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 1, 4 ], [ 2, 1 ], [ 3, 4 ], [ 4, 3 ], [ 4, 4 ] ]
gap> DigraphEdges(DigraphReverse(gr));
[ [ 1, 2 ], [ 2, 1 ], [ 3, 4 ], [ 4, 1 ], [ 4, 3 ], [ 4, 4 ] ]
```

3.3.9 DigraphDual

▷ `DigraphDual(`*`digraph`*`)` (attribute)

Returns: A digraph.

If *`digraph`* is a digraph without multiple edges, then this returns the *dual* of *`digraph`*. The *dual* is sometimes called the *complement*.

The *dual* of *`digraph`* has the same vertices as *`digraph`*, and there is an edge in the dual from `i` to `j` whenever there is no edge from `i` to `j` in *`digraph`*.

Example

```
gap> gr := Digraph([[2, 3], [], [4, 6], [5], [],
> [7, 8, 9], [], [], []]);
<digraph with 9 vertices, 8 edges>
gap> DigraphDual(gr);
<digraph with 9 vertices, 73 edges>
```

3.3.10 DigraphSymmetricClosure

▷ `DigraphSymmetricClosure(`*`digraph`*`)` (attribute)

Returns: A digraph.

If *digraph* is a digraph, then this attribute gives the minimal symmetric digraph which has the same vertices and contains all the edges of *digraph*.

A digraph is *symmetric* if its adjacency matrix AdjacencyMatrix (5.2.1) is symmetric. For a digraph with multiple edges this means that there are the same number of edges from a vertex u to a vertex v as there are from v to u; see IsSymmetricDigraph (6.1.10).

Example

```
gap> gr := Digraph([[1, 2, 3], [2, 4], [1], [3, 4]]);
<digraph with 4 vertices, 8 edges>
gap> gr1 := DigraphSymmetricClosure(gr);
<digraph with 4 vertices, 11 edges>
gap> IsSymmetricDigraph(gr1);
true
gap> List(OutNeighbours(gr1), AsSet);
[ [ 1, 2, 3 ], [ 1, 2, 4 ], [ 1, 4 ], [ 2, 3, 4 ] ]
gap> gr := Digraph([[2, 2], [1]]);
<multidigraph with 2 vertices, 3 edges>
gap> gr1 := DigraphSymmetricClosure(gr);
<multidigraph with 2 vertices, 4 edges>
gap> OutNeighbours(gr1);
[ [ 2, 2 ], [ 1, 1 ] ]
```

3.3.11 DigraphReflexiveTransitiveClosure

▷ DigraphReflexiveTransitiveClosure(*digraph*) (attribute)

▷ DigraphTransitiveClosure(*digraph*) (attribute)

Returns: A digraph.

If *digraph* is a digraph with no multiple edges, then these attributes return the (reflexive) transitive closure of *digraph*.

A digraph is *reflexive* if it has a loop at every vertex, and it is *transitive* if whenever [i,j] and [j,k] are edges of *digraph*, [i,k] is also an edge. The *(reflexive) transitive closure* of a digraph *digraph* is the least (reflexive and) transitive digraph containing *digraph*.

Let n be the number of vertices of *digraph*, and let m be the number of edges. For an arbitrary digraph, these attributes will use a version of the Floyd-Warshall algorithm, with complexity $O(n^3)$. However, for a topologically sortable digraph [see DigraphTopologicalSort (5.1.7)], these attributes will use methods with complexity $O(m+n+m\cdot n)$ when this is faster.

Example

```
gap> gr := DigraphFromDiSparse6String(".H‘eOWR‘Ul^");
<digraph with 9 vertices, 8 edges>
gap> IsReflexiveDigraph(gr) or IsTransitiveDigraph(gr);
false
gap> OutNeighbours(gr);
[ [ 4, 6 ], [ 1, 3 ], [  ], [ 5 ], [  ], [ 7, 8, 9 ], [  ], [  ],
  [  ] ]
gap> trans := DigraphTransitiveClosure(gr);
<digraph with 9 vertices, 18 edges>
gap> OutNeighbours(trans);
[ [ 4, 5, 6, 7, 8, 9 ], [ 1, 3, 4, 5, 6, 7, 8, 9 ], [  ], [ 5 ],
  [  ], [ 7, 8, 9 ], [  ], [  ], [  ] ]
gap> reflextrans := DigraphReflexiveTransitiveClosure(gr);
<digraph with 9 vertices, 27 edges>
```

```
gap> OutNeighbours(reflextrans);
[ [ 1, 4, 5, 6, 7, 8, 9 ], [ 1, 2, 3, 4, 5, 6, 7, 8, 9 ], [ 3 ],
  [ 4, 5 ], [ 5 ], [ 6, 7, 8, 9 ], [ 7 ], [ 8 ], [ 9 ] ]
```

3.3.12 DigraphReflexiveTransitiveReduction

▷ DigraphReflexiveTransitiveReduction(*digraph*) (operation)
▷ DigraphTransitiveReduction(*digraph*) (operation)

Returns: A digraph.

If *digraph* is a topologically sortable digraph [see DigraphTopologicalSort (5.1.7)] with no multiple edges, then these operations return the (reflexive) transitive reduction of *digraph*.

The (reflexive) transitive reduction of such a digraph is the unique least subgraph such that the (reflexive) transitive closure of the subgraph is equal to the (reflexive) transitive closure of *digraph* [see DigraphReflexiveTransitiveClosure (3.3.11)]. In order words, it is the least subgraph of *digraph* which retains the same reachability as *digraph*.

Let n be the number of vertices of an arbitrary digraph, and let m be the number of edges. Then these operations use methods with complexity $O(m+n+m\cdot n)$.

Example

```
gap> gr := Digraph([[1, 2, 3], [3], [3]]);;
gap> DigraphHasLoops(gr);
true
gap> gr1 := DigraphReflexiveTransitiveReduction(gr);
<digraph with 3 vertices, 2 edges>
gap> DigraphHasLoops(gr1);
false
gap> OutNeighbours(gr1);
[ [ 2 ], [ 3 ], [  ] ]
gap> gr2 := DigraphTransitiveReduction(gr);
<digraph with 3 vertices, 4 edges>
gap> DigraphHasLoops(gr2);
true
gap> OutNeighbours(gr2);
[ [ 2, 1 ], [ 3 ], [ 3 ] ]
gap> DigraphReflexiveTransitiveClosure(gr)
>  = DigraphReflexiveTransitiveClosure(gr1);
true
gap> DigraphTransitiveClosure(gr)
>  = DigraphTransitiveClosure(gr2);
true
```

3.3.13 DigraphAddVertex

▷ DigraphAddVertex(*digraph*[, *label*]) (operation)

Returns: A digraph.

The operation returns a new digraph constructed from *digraph* by adding a single new vertex.

If the optional second argument *label* is a GAP object, then the new vertex will be labelled *label*.

Example

```
gap> gr := CompleteDigraph(3);
<digraph with 3 vertices, 6 edges>
```

```
gap> new := DigraphAddVertex(gr);
<digraph with 4 vertices, 6 edges>
gap> DigraphVertices(new);
[ 1 .. 4 ]
gap> new := DigraphAddVertex(gr, Group([(1, 2)]));
<digraph with 4 vertices, 6 edges>
gap> DigraphVertexLabels(new);
[ 1, 2, 3, Group([ (1,2) ]) ]
```

3.3.14 DigraphAddVertices

▷ DigraphAddVertices(*digraph*, *m*[, *labels*]) (operation)

Returns: A digraph.

For a non-negative integer *m*, this operation returns a new digraph constructed from *digraph* by adding *m* new vertices.

If the optional third argument *labels* is a list of length *m* consisting of GAP objects, then the new vertices will be labelled according to this list.

Example

```
gap> gr := CompleteDigraph(3);
<digraph with 3 vertices, 6 edges>
gap> new := DigraphAddVertices(gr, 3);
<digraph with 6 vertices, 6 edges>
gap> DigraphVertices(new);
[ 1 .. 6 ]
gap> new := DigraphAddVertices(gr, 2, [Group([(1, 2)]), "d"]);
<digraph with 5 vertices, 6 edges>
gap> DigraphVertexLabels(new);
[ 1, 2, 3, Group([ (1,2) ]), "d" ]
gap> DigraphAddVertices(gr, 0) = gr;
true
```

3.3.15 DigraphAddEdge

▷ DigraphAddEdge(*digraph*, *edge*) (operation)

Returns: A digraph.

If *edge* is a pairs of vertices of *digraph*, then this operation returns a new digraph constructed from *digraph* by adding a new edge with source *edge*[1] and range *edge*[2].

Example

```
gap> gr1 := Digraph([[2], [3], []]);
<digraph with 3 vertices, 2 edges>
gap> DigraphEdges(gr1);
[ [ 1, 2 ], [ 2, 3 ] ]
gap> gr2 := DigraphAddEdge(gr1, [3, 1]);
<digraph with 3 vertices, 3 edges>
gap> DigraphEdges(gr2);
[ [ 1, 2 ], [ 2, 3 ], [ 3, 1 ] ]
gap> gr3 := DigraphAddEdge(gr2, [2, 3]);
<multidigraph with 3 vertices, 4 edges>
gap> DigraphEdges(gr3);
[ [ 1, 2 ], [ 2, 3 ], [ 2, 3 ], [ 3, 1 ] ]
```

3.3.16 DigraphAddEdgeOrbit

▷ DigraphAddEdgeOrbit(*digraph, edge*) (operation)

Returns: A new digraph.

This operation returns a new digraph with the same vertices and edges as *digraph* and with additional edges consisting of the orbit of the edge *edge* under the action of the DigraphGroup (7.2.9) of *digraph*. If *edge* is already an edge in *digraph*, then *digraph* is returns unchanged.

An edge is simply a pair of vertices of *digraph*.

Example

```
gap> gr1 := CayleyDigraph(DihedralGroup(8));
<digraph with 8 vertices, 24 edges>
gap> gr2 := DigraphAddEdgeOrbit(gr1, [1, 8]);
<digraph with 8 vertices, 32 edges>
gap> DigraphEdges(gr1);
[ [ 1, 2 ], [ 1, 3 ], [ 1, 4 ], [ 2, 1 ], [ 2, 8 ], [ 2, 6 ],
  [ 3, 5 ], [ 3, 4 ], [ 3, 7 ], [ 4, 6 ], [ 4, 7 ], [ 4, 1 ],
  [ 5, 3 ], [ 5, 2 ], [ 5, 8 ], [ 6, 4 ], [ 6, 5 ], [ 6, 2 ],
  [ 7, 8 ], [ 7, 1 ], [ 7, 3 ], [ 8, 7 ], [ 8, 6 ], [ 8, 5 ] ]
gap> DigraphEdges(gr2);
[ [ 1, 2 ], [ 1, 3 ], [ 1, 4 ], [ 1, 8 ], [ 2, 1 ], [ 2, 8 ],
  [ 2, 6 ], [ 2, 3 ], [ 3, 5 ], [ 3, 4 ], [ 3, 7 ], [ 3, 2 ],
  [ 4, 6 ], [ 4, 7 ], [ 4, 1 ], [ 4, 5 ], [ 5, 3 ], [ 5, 2 ],
  [ 5, 8 ], [ 5, 4 ], [ 6, 4 ], [ 6, 5 ], [ 6, 2 ], [ 6, 7 ],
  [ 7, 8 ], [ 7, 1 ], [ 7, 3 ], [ 7, 6 ], [ 8, 7 ], [ 8, 6 ],
  [ 8, 5 ], [ 8, 1 ] ]
gap> gr3 := DigraphRemoveEdgeOrbit(gr2, [1, 8]);
<digraph with 8 vertices, 24 edges>
gap> gr3 = gr1;
true
```

3.3.17 DigraphAddEdges

▷ DigraphAddEdges(*digraph, edges*) (operation)

Returns: A digraph.

If *edges* is a (possibly empty) list of pairs of vertices of *digraph*, then this operation returns a new digraph constructed from *digraph* by adding the edges specified by *edges*. More precisely, for every edge in *edges*, a new edge will be added with source edge[1] and range edges[2].

If an edge is included in *edges* with multiplicity k, then it will be added k times.

Example

```
gap> func := function(n)
>  local source, range, i;
>  source := [];
>  range  := [];
>  for i in [1 .. n - 2] do
>    Add(source, i);
>    Add(range, i + 1);
>  od;
>  return Digraph(n, source, range);
> end;;
gap> gr := func(1024);
<digraph with 1024 vertices, 1022 edges>
```

```
gap> gr := DigraphAddEdges(gr,
> [[1023, 1024], [1, 1024], [1023, 1024], [1024, 1]]);
<multidigraph with 1024 vertices, 1026 edges>
```

3.3.18 DigraphRemoveVertex

▷ DigraphRemoveVertex(*digraph*, *v*) (operation)

Returns: A digraph.

If *v* is a vertex of *digraph*, then this operation returns a new digraph constructed from *digraph* by removing vertex *v*, along with any edge whose source or range vertex is *v*.

If *digraph* has n vertices, then the vertices of the new digraph are [1..n-1], but the original labels can be accessed via DigraphVertexLabels (5.1.9).

Example

```
gap> gr := Digraph(["a", "b", "c"],
>                  ["a", "a", "b", "c", "c"],
>                  ["b", "c", "a", "a", "c"]);
<digraph with 3 vertices, 5 edges>
gap> DigraphVertexLabels(gr);
[ "a", "b", "c" ]
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 1, 3 ], [ 2, 1 ], [ 3, 1 ], [ 3, 3 ] ]
gap> new := DigraphRemoveVertex(gr, 2);
<digraph with 2 vertices, 3 edges>
gap> DigraphVertexLabels(new);
[ "a", "c" ]
```

3.3.19 DigraphRemoveVertices

▷ DigraphRemoveVertices (*digraph*, *verts*) (operation)

Returns: A digraph.

If *verts* is a (possibly empty) duplicate-free list of vertices of *digraph*, then this operation returns a new digraph constructed from *digraph* by removing every vertex in *verts*, along with any edge whose source or range vertex is in *verts*.

If *digraph* has n vertices, then the vertices of the new digraph are [1 .. n-Length(*verts*)], but the original labels can be accessed via DigraphVertexLabels (5.1.9).

Example

```
gap> gr := Digraph([[3], [1, 3, 5], [1], [1, 2, 4], [2, 3, 5]]);
<digraph with 5 vertices, 11 edges>
gap> SetDigraphVertexLabels(gr, ["a", "b", "c", "d", "e"]);
gap> new := DigraphRemoveVertices(gr, [2, 4]);
<digraph with 3 vertices, 4 edges>
gap> DigraphVertexLabels(new);
[ "a", "c", "e" ]
```

3.3.20 DigraphRemoveEdge

▷ DigraphRemoveEdge(*digraph*, *edge*) (operation)

Returns: A digraph.

If one of the following holds:

- *digraph* is a digraph with no multiple edges, and *edge* is a pair of vertices of *digraph*, or
- *digraph* is any digraph and *edge* is the index of an edge of *digraph*,

then this operation returns a new digraph constructed from *digraph* by removing the edges specified by *edges*. If, in the first case, the pair of vertices *edge* does not specify an edge of *digraph*, then a new copy of *digraph* will be returned.

Example

```
gap> gr := CycleDigraph(250000);
<digraph with 250000 vertices, 250000 edges>
gap> gr := DigraphRemoveEdge(gr, [250000, 1]);
<digraph with 250000 vertices, 249999 edges>
gap> gr := DigraphRemoveEdge(gr, 10);
<digraph with 250000 vertices, 249998 edges>
```

3.3.21 DigraphRemoveEdgeOrbit

▷ DigraphRemoveEdgeOrbit(*digraph*, *edge*) (operation)

Returns: A new digraph.

This operation returns a new digraph with the same vertices as *digraph* and with the orbit of the edge *edge* (under the action of the DigraphGroup (7.2.9) of *digraph*) removed. If *edge* is not an edge in *digraph*, then *digraph* is returned unchanged.

An edge is simply a pair of vertices of *digraph*.

Example

```
gap> gr1 := CayleyDigraph(DihedralGroup(8));
<digraph with 8 vertices, 24 edges>
gap> gr2 := DigraphAddEdgeOrbit(gr1, [1, 8]);
<digraph with 8 vertices, 32 edges>
gap> DigraphEdges(gr1);
[ [ 1, 2 ], [ 1, 3 ], [ 1, 4 ], [ 2, 1 ], [ 2, 8 ], [ 2, 6 ],
  [ 3, 5 ], [ 3, 4 ], [ 3, 7 ], [ 4, 6 ], [ 4, 7 ], [ 4, 1 ],
  [ 5, 3 ], [ 5, 2 ], [ 5, 8 ], [ 6, 4 ], [ 6, 5 ], [ 6, 2 ],
  [ 7, 8 ], [ 7, 1 ], [ 7, 3 ], [ 8, 7 ], [ 8, 6 ], [ 8, 5 ] ]
gap> DigraphEdges(gr2);
[ [ 1, 2 ], [ 1, 3 ], [ 1, 4 ], [ 1, 8 ], [ 2, 1 ], [ 2, 8 ],
  [ 2, 6 ], [ 2, 3 ], [ 3, 5 ], [ 3, 4 ], [ 3, 7 ], [ 3, 2 ],
  [ 4, 6 ], [ 4, 7 ], [ 4, 1 ], [ 4, 5 ], [ 5, 3 ], [ 5, 2 ],
  [ 5, 8 ], [ 5, 4 ], [ 6, 4 ], [ 6, 5 ], [ 6, 2 ], [ 6, 7 ],
  [ 7, 8 ], [ 7, 1 ], [ 7, 3 ], [ 7, 6 ], [ 8, 7 ], [ 8, 6 ],
  [ 8, 5 ], [ 8, 1 ] ]
gap> gr3 := DigraphRemoveEdgeOrbit(gr2, [1, 8]);
<digraph with 8 vertices, 24 edges>
gap> gr3 = gr1;
true
```

3.3.22 DigraphRemoveEdges

▷ DigraphRemoveEdges(*digraph*, *edges*) (operation)

Returns: A digraph.

If one of the following holds:

- *digraph* is a digraph with no multiple edges, and *edges* is a list of pairs of vertices of *digraph*, or
- *digraph* is any digraph and *edges* is a list of indices of edges of *digraph*,

then this operation returns a new digraph constructed from *digraph* by removing all of the edges specified by *edges* [see DigraphRemoveEdge (3.3.20)].

Example

```
gap> gr := CycleDigraph(250000);
<digraph with 250000 vertices, 250000 edges>
gap> gr := DigraphRemoveEdges(gr, [[250000, 1]]);
<digraph with 250000 vertices, 249999 edges>
gap> gr := DigraphRemoveEdges(gr, [10]);
<digraph with 250000 vertices, 249998 edges>
```

3.3.23 DigraphRemoveLoops

▷ DigraphRemoveLoops(*digraph*) (operation)

Returns: A digraph.

If *digraph* is a digraph, then this operation returns a new digraph constructed from *digraph* by removing every loop. A loop is an edge with equal source and range.

Example

```
gap> gr := Digraph([[1, 2, 4], [1, 4], [3, 4], [1, 4, 5], [1, 5]]);
<digraph with 5 vertices, 12 edges>
gap> DigraphRemoveLoops(gr);
<digraph with 5 vertices, 8 edges>
```

3.3.24 DigraphRemoveAllMultipleEdges

▷ DigraphRemoveAllMultipleEdges(*digraph*) (operation)

Returns: A digraph.

If *digraph* is a digraph, then this operation returns a new digraph constructed from *digraph* by removing all multiple edges. The result is the largest subdigraph of *digraph* which does not contain multiple edges.

Example

```
gap> gr1 := Digraph([[1, 2, 3, 2], [1, 1, 3], [2, 2, 2]]);
<multidigraph with 3 vertices, 10 edges>
gap> gr2 := DigraphRemoveAllMultipleEdges(gr1);
<digraph with 3 vertices, 6 edges>
gap> OutNeighbours(gr2);
[ [ 1, 2, 3 ], [ 1, 3 ], [ 2 ] ]
```

3.3.25 DigraphReverseEdges

▷ DigraphReverseEdges(*digraph*, *edges*) (operation)

▷ DigraphReverseEdge(*digraph*, *edge*) (operation)

Returns: A digraph.

If *digraph* is a digraph without multiple edges, and *edges* is either:

- a list of pairs of vertices of *digraph* (the entries of each pair corresponding to the source and the range of an edge, respectively),
- a list of positions of elements in the list DigraphEdges (5.1.3),

then DigraphReverseEdges returns a new digraph constructed from *digraph* by reversing the orientation of every edge specified by *edges*. If only one edge is to be reversed, then DigraphReverseEdge can be used instead. In this case, the second argument should just be a single vertex-pair or a single position.

Note that even though *digraph* cannot have multiple edges, the output may have multiple edges.

Example

```
gap> gr := DigraphFromDiSparse6String(".Tg?i@s?t_e?_qEsC");
<digraph with 21 vertices, 8 edges>
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 1, 7 ], [ 1, 8 ], [ 5, 21 ], [ 7, 19 ], [ 9, 1 ],
  [ 11, 2 ], [ 21, 1 ] ]
gap> gr2 := DigraphReverseEdges(gr, [1, 2, 4]);
<digraph with 21 vertices, 8 edges>
gap> gr = DigraphReverseEdges(gr2, [[7, 1], [2, 1], [21, 5]]);
true
gap> gr2 := DigraphReverseEdge(gr, 5);
<digraph with 21 vertices, 8 edges>
gap> gr2 = DigraphReverseEdge(gr, [7, 19]);
true
```

3.3.26 DigraphDisjointUnion (for an arbitrary number of digraphs)

▷ DigraphDisjointUnion(*gr1, gr2, ...*) (function)
▷ DigraphDisjointUnion(*list*) (function)

Returns: A digraph.

In the first form, if *gr1*, *gr2*, etc. are digraphs, then DigraphDisjointUnion returns their disjoint union. In the second form, if *list* is a non-empty list of digraphs, then DigraphDisjointUnion returns the disjoint union of the digraphs contained in the list.

For a disjoint union of digraphs, the vertex set is the disjoint union of the vertex sets, and the edge list is the disjoint union of the edge lists.

More specifically, for a collection of digraphs *gr1*, *gr2*, ..., the disjoint union with have DigraphNrVertices(*gr1*) + DigraphNrVertices(*gr2*) + ... vertices. The edges of *gr1* will remain unchanged, whilst the edges of the ith digraph, *gr*[i], will be changed so that they belong to the vertices of the disjoint union corresponding to *gr*[i]. In particular, the edges of *gr*[i] will have their source and range increased by DigraphNrVertices(*gr1*) + ... + DigraphNrVertices(*gr*[i-1]).

Note that previously set DigraphVertexLabels (5.1.9) will be lost.

Example

```
gap> gr1 := CycleDigraph(3);
<digraph with 3 vertices, 3 edges>
gap> OutNeighbours(gr1);
[ [ 2 ], [ 3 ], [ 1 ] ]
gap> gr2 := CompleteDigraph(3);
<digraph with 3 vertices, 6 edges>
gap> OutNeighbours(gr2);
```

```
[ [ 2, 3 ], [ 1, 3 ], [ 1, 2 ] ]
gap> union := DigraphDisjointUnion(gr1, gr2);
<digraph with 6 vertices, 9 edges>
gap> OutNeighbours(union);
[ [ 2 ], [ 3 ], [ 1 ], [ 5, 6 ], [ 4, 6 ], [ 4, 5 ] ]
```

3.3.27 DigraphEdgeUnion (for an arbitrary number of digraphs)

▷ DigraphEdgeUnion(*gr1, gr2, ...*) (function)
▷ DigraphEdgeUnion(*list*) (function)

Returns: A digraph.

In the first form, if *gr1*, *gr2*, etc. are digraphs, then DigraphEdgeUnion returns their edge union. In the second form, if *list* is a non-empty list of digraphs, then DigraphEdgeUnion returns the edge union of the digraphs contained in the list.

The vertex set of the edge union of a collection of digraphs is the *union* of the vertex sets, whilst the edge list of the edge union is the *concatenation* of the edge lists. The number of vertices of the edge union is equal to the *maximum* number of vertices of one of the digraphs, whilst the number of edges of the edge union will equal the *sum* of the number of edges of each digraph.

Note that previously set DigraphVertexLabels (5.1.9) will be lost.

Example

```
gap> gr := CycleDigraph(10);
<digraph with 10 vertices, 10 edges>
gap> DigraphEdgeUnion(gr, gr);
<multidigraph with 10 vertices, 20 edges>
gap> gr1 := Digraph([[2], [1]]);
<digraph with 2 vertices, 2 edges>
gap> gr2 := Digraph([[2, 3], [2], [1]]);
<digraph with 3 vertices, 4 edges>
gap> union := DigraphEdgeUnion(gr1, gr2);
<multidigraph with 3 vertices, 6 edges>
gap> OutNeighbours(union);
[ [ 2, 2, 3 ], [ 1, 2 ], [ 1 ] ]
gap> union = DigraphByEdges(
> Concatenation(DigraphEdges(gr1), DigraphEdges(gr2)));
true
```

3.3.28 DigraphJoin (for an arbitrary number of digraphs)

▷ DigraphJoin(*gr1, gr2, ...*) (function)
▷ DigraphJoin(*list*) (function)

Returns: A digraph.

In the first form, if *gr1*, *gr2*, etc. are digraphs, then DigraphJoin returns their join. In the second form, if *list* is a non-empty list of digraphs, then DigraphJoin returns the join of the digraphs contained in the list.

The join of a collection of digraphs *gr1*, *gr2*, ... is formed by first taking the DigraphDisjointUnion (3.3.26) of the collection. In the disjoint union, if $i \neq j$ then there are no edges between vertices corresponding to digraphs *gr*[i] and *gr*[j] in the collection; the join is created by including all such edges.

For example, the join of two empty digraphs is a complete bipartite digraph.

Note that previously set DigraphVertexLabels (5.1.9) will be lost.

Example

```
gap> gr := CompleteDigraph(3);
<digraph with 3 vertices, 6 edges>
gap> IsCompleteDigraph(DigraphJoin(gr, gr));
true
gap> gr2 := CycleDigraph(3);
<digraph with 3 vertices, 3 edges>
gap> DigraphJoin(gr, gr2);
<digraph with 6 vertices, 27 edges>
```

3.3.29 LineDigraph

▷ LineDigraph(*digraph*) (operation)

▷ EdgeDigraph(*digraph*) (operation)

Returns: A digraph.

Given a digraph *digraph*, the operation returns the digraph obtained by associating a vertex with each edge of *digraph*, and creating an edge from a vertex v to a vertex u if and only if the terminal vertex of the edge associated with v is the start vertex of the edge associated with u.

Example

```
gap> LineDigraph(CompleteDigraph(3));
<digraph with 6 vertices, 12 edges>
gap> LineDigraph(ChainDigraph(3));
<digraph with 2 vertices, 1 edge>
```

3.3.30 LineUndirectedDigraph

▷ LineUndirectedDigraph(*digraph*) (operation)

▷ EdgeUndirectedDigraph(*digraph*) (operation)

Returns: A digraph.

Given a symmetric digraph *digraph*, the operation returns the symmetric digraph obtained by associating a vertex with each edge of *digraph*, ignoring directions and multiplicites, and adding an edge between two vertices if and only if the corresponding edges have a vertex in common.

Example

```
gap> LineUndirectedDigraph(CompleteDigraph(3));
<digraph with 3 vertices, 6 edges>
gap> LineUndirectedDigraph(DigraphSymmetricClosure(ChainDigraph(3)));
<digraph with 2 vertices, 2 edges>
```

3.3.31 DoubleDigraph

▷ DoubleDigraph(*digraph*) (operation)

Returns: A digraph.

Let *digraph* be a digraph with vertex set V. This function returns the double digraph of *digraph*. The vertex set of the double digraph is the orginal vertex set together with a duplicate. The edges are [u_1, v_2] and [u_2, v_1] if and only if [u, v] is an edge in *digraph*, together with the original edges and their duplicates.

Example

```
gap> gamma := Digraph([[2], [3], [1]]);
<digraph with 3 vertices, 3 edges>
gap> DoubleDigraph(gamma);
<digraph with 6 vertices, 12 edges>
```

3.3.32 BipartiteDoubleDigraph

▷ BipartiteDoubleDigraph(*digraph*) (operation)

Returns: A digraph.

Let *digraph* be a digraph with vertex set V. This function returns the bipartite double digraph of *digraph*. The vertex set of the double digraph is the orginal vertex set together with a duplicate. The edges are [u_1, v_2] and [u_2, v_1] if and only if [u, v] is an edge in *digraph*. The resulting graph is bipartite, since the orignal edges are not included in the resulting digraph.

Example

```
gap> gamma := Digraph([[2], [3], [1]]);
<digraph with 3 vertices, 3 edges>
gap> BipartiteDoubleDigraph(gamma);
<digraph with 6 vertices, 6 edges>
```

3.3.33 DigraphAddAllLoops

▷ DigraphAddAllLoops(*digraph*) (operation)

Returns: A digraph.

For a digraph *digraph* this operation return a copy of *digraph* such that a loop is added for every vertex which did not have a loop in *digraph*.

Example

```
gap> gr := EmptyDigraph(13);
<digraph with 13 vertices, 0 edges>
gap> gr := DigraphAddAllLoops(gr);
<digraph with 13 vertices, 13 edges>
gap> OutNeighbours(gr);
[ [ 1 ], [ 2 ], [ 3 ], [ 4 ], [ 5 ], [ 6 ], [ 7 ], [ 8 ], [ 9 ],
  [ 10 ], [ 11 ], [ 12 ], [ 13 ] ]
gap> gr := Digraph([[1, 2, 3], [1, 3], [1]]);
<digraph with 3 vertices, 6 edges>
gap> gr := DigraphAddAllLoops(gr);
<digraph with 3 vertices, 8 edges>
gap> OutNeighbours(gr);
[ [ 1, 2, 3 ], [ 1, 3, 2 ], [ 1, 3 ] ]
```

3.3.34 DistanceDigraph (for digraph and int)

▷ DistanceDigraph(*digraph, i*) (operation)

▷ DistanceDigraph(*digraph, list*) (operation)

Returns: A digraph.

The first argument is a digraph, the second argument is a non-negative integer or a list of positive integers. This operation returns a digraph on the same set of vertices as *digraph*, with two vertices

being adjacent if and only if the distance between them in *digraph* equals *i* or is a number in *list*. See DigraphShortestDistance (5.3.2).

Example

```
gap> digraph := DigraphFromSparse6String(
> ":]n?AL‘BC_DEbEF‘GIaGHdIJeGKcKL_@McDHfILaBJfHMjKM");
<digraph with 30 vertices, 90 edges>
gap> DistanceDigraph(digraph, 1);
<digraph with 30 vertices, 90 edges>
gap> DistanceDigraph(digraph, [1, 2]);
<digraph with 30 vertices, 270 edges>
```

3.3.35 DigraphClosure (for a digraph and positive integer)

▷ DigraphClosure(*digraph, k*) (operation)

Returns: A digraph

Given a symmetric loopless digraph with no multiple edges *digraph*, the *k-closure of digraph* is defined to be the unique smallest symmetric loopless digraph C with no multiple edges on the vertices of *digraph* that contains all the edges of *digraph* and satsifies the property that the sum of the degrees of every two non-adjacenct vertices in C is less than *k*. See IsSymmetricDigraph (6.1.10), DigraphHasLoops (6.1.1), IsMultiDigraph (6.1.8), and OutDegreeOfVertex (5.2.10).

The operation DigraphClosure returns the *k*-closure of *digraph*.

Example

```
gap> gr := CompleteDigraph(6);;
gap> DigraphRemoveEdges(gr, [[1, 2], [2, 1]]);;
gap> closure := DigraphClosure(gr, 6);
<digraph with 6 vertices, 30 edges>
gap> IsCompleteDigraph(closure);
true
```

3.4 Random digraphs

3.4.1 RandomDigraph

▷ RandomDigraph(*n[, p]*) (operation)

Returns: A digraph.

If *n* is a positive integer, then this function returns a random digraph with *n* vertices and without multiple edges. The result may or may not have loops.

If the optional second argument *p* is a float with value $0 \leq p \leq 1$, then an edge will exist between each pair of vertices with probability approximately *p*. If *p* is not specified, then a random probability will be assumed (chosen with uniform probability).

Example

```
gap> RandomDigraph(1000);
<digraph with 1000 vertices, 364444 edges>
gap> RandomDigraph(10000, 0.023);
<digraph with 10000 vertices, 2300438 edges>
```

3.4.2 RandomMultiDigraph

▷ `RandomMultiDigraph(`*`n[, m]`*`)` (operation)

Returns: A digraph.

If *n* is a positive integer, then this function returns a random digraph with *n* vertices. If the optional second argument *m* is a positive integer, then the digraph will have *m* edges. If *m* is not specified, then the number of edges will be chosen randomly (with uniform probability) from the range `[1 ..` $\binom{n}{2}$`]`.

The method used by this function chooses each edge from the set of all possible edges with uniform probability. No effort is made to avoid creating multiple edges, so it is possible (but not guaranteed) that the result will have multiple edges. The result may or may not have loops.

Example

```
gap> RandomMultiDigraph(1000);
<multidigraph with 1000 vertices, 216659 edges>
gap> RandomMultiDigraph(1000, 950);
<multidigraph with 1000 vertices, 950 edges>
```

3.4.3 RandomTournament

▷ `RandomTournament(`*`n`*`)` (operation)

Returns: A digraph.

If *n* is a non-negative integer, this function returns a random tournament with *n* vertices. See `IsTournament` (6.1.11).

Example

```
gap> RandomTournament(10);
<digraph with 10 vertices, 45 edges>
```

3.5 Standard examples

3.5.1 ChainDigraph

▷ `ChainDigraph(`*`n`*`)` (operation)

Returns: A digraph.

If *n* is a positive integer, this function returns a chain with *n* vertices and *n* `- 1` edges. Specifically, for each vertex `i` (with `i < n`), there is a directed edge with source `i` and range `i + 1`.

The `DigraphReflexiveTransitiveClosure` (3.3.11) of a chain represents a total order.

Example

```
gap> ChainDigraph(42);
<digraph with 42 vertices, 41 edges>
```

3.5.2 CompleteDigraph

▷ `CompleteDigraph(`*`n`*`)` (operation)

Returns: A digraph.

If *n* is a non-negative integer, this function returns the complete digraph with *n* vertices. See `IsCompleteDigraph` (6.1.5).

Example

```
gap> CompleteDigraph(20);
<digraph with 20 vertices, 380 edges>
```

3.5.3 CompleteBipartiteDigraph

▷ `CompleteBipartiteDigraph(`*m*`, `*n*`)` (operation)

Returns: A digraph.

A complete bipartite digraph is a digraph whose vertices can be partitioned into two non-empty vertex sets, such there exists a unique edge with source `i` and range `j` if and only if `i` and `j` lie in different vertex sets.

If *m* and *n* are positive integers, this function returns the complete bipartite digraph with vertex sets of sizes *m* (containing the vertices `[1 .. m]`) and *n* (containing the vertices `[m + 1 .. m + n]`).

Example

```
gap> CompleteBipartiteDigraph(2, 3);
<digraph with 5 vertices, 12 edges>
```

3.5.4 CompleteMultipartiteDigraph

▷ `CompleteMultipartiteDigraph(`*orders*`)` (operation)

Returns: A digraph.

For a list *orders* of `n` positive integers, this function returns the digraph containing `n` independent sets of vertices of orders `[`*l*`[1] .. `*l*`[n]]`. Moreover, each vertex is adjacent to every other not contained in the same independent set.

Example

```
gap> CompleteMultipartiteDigraph([5, 4, 2]);
<digraph with 11 vertices, 76 edges>
```

3.5.5 CycleDigraph

▷ `CycleDigraph(`*n*`)` (operation)

Returns: A digraph.

If *n* is a positive integer, this function returns a *cycle* digraph with *n* vertices and *n* edges. Specifically, for each vertex `i` (with `i < n`), there is a directed edge with source `i` and range `i + 1`. In addition, there is an edge with source `n` and range `1`.

Example

```
gap> CycleDigraph(1);
<digraph with 1 vertex, 1 edge>
gap> CycleDigraph(123);
<digraph with 123 vertices, 123 edges>
```

3.5.6 EmptyDigraph

▷ `EmptyDigraph(`*n*`)` (operation)

▷ `NullDigraph(`*n*`)` (operation)

Returns: A digraph.

If *n* is a non-negative integer, this function returns the *empty* or *null* digraph with *n* vertices. An empty digraph is one with no edges.

`NullDigraph` is a synonym for `EmptyDigraph`.

Example

```
gap> EmptyDigraph(20);
<digraph with 20 vertices, 0 edges>
gap> NullDigraph(10);
<digraph with 10 vertices, 0 edges>
```

3.5.7 JohnsonDigraph

▷ JohnsonDigraph(*n*, *k*) (operation)

Returns: A digraph.

If *n* and *k* are non-negative integers, then this operation returns a symmetric digraph which corresponds to the undirected *Johnson graph* $J(n,k)$.

The *Johnson graph* $J(n,k)$ has vertices given by all the k-subsets of the range [1 .. *k*], and two vertices are connected by an edge iff their intersection has size $k-1$.

Example

```
gap> gr := JohnsonDigraph(3, 1);
<digraph with 3 vertices, 6 edges>
gap> OutNeighbours(gr);
[ [ 2, 3 ], [ 1, 3 ], [ 1, 2 ] ]
gap> gr := JohnsonDigraph(4, 2);
<digraph with 6 vertices, 24 edges>
gap> OutNeighbours(gr);
[ [ 2, 3, 4, 5 ], [ 1, 3, 4, 6 ], [ 1, 2, 5, 6 ], [ 1, 2, 5, 6 ],
  [ 1, 3, 4, 6 ], [ 2, 3, 4, 5 ] ]
gap> JohnsonDigraph(1, 0);
<digraph with 1 vertex, 0 edges>
```

Chapter 4

Operators

4.1 Operators for digraphs

digraph1 = *digraph2*

returns true if *digraph1* and *digraph2* have the same vertices, and DigraphEdges(*digraph1*) = DigraphEdges(*digraph2*), up to some re-ordering of the edge lists.

Note that this operator does not compare the vertex labels of *digraph1* and *digraph2*.

digraph1 < *digraph2*

This operator returns true if one of the following holds:

- The number n_1 of vertices in *digraph1* is less than the number n_2 of vertices in *digraph2*;
- $n_1 = n_2$, and the number m_1 of edges in *digraph1* is less than the number m_2 of edges in *digraph2*;
- $n_1 = n_2$, $m_1 = m_2$, and DigraphEdges(*digraph1*) is less than DigraphEdges(*digraph2*) after having both of these sets have been sorted with respect to the lexicographical order.

4.1.1 IsSubdigraph

▷ IsSubdigraph(*super*, *sub*) (operation)

Returns: true or false.

If *super* and *sub* are digraphs, then this operation returns true if *sub* is a subdigraph of *super*, and false if it is not.

A digraph *sub* is a *subdigraph* of a digraph *super* if *sub* and *super* share the same number of vertices, and the collection of edges of *super* (including repeats) contains the collection of edges of *sub* (including repeats).

In other words, *sub* is a subdigraph of *super* if and only if DigraphNrVertices(*sub*) = DigraphNrVertices(*super*), and for each pair of vertices i and j, there are at least as many edges of the form [i, j] in *super* as there are in *sub*.

Example

```
gap> g := Digraph([[2, 3], [1], [2, 3]]);
<digraph with 3 vertices, 5 edges>
gap> h := Digraph([[2, 3], [], [2]]);
```

```
<digraph with 3 vertices, 3 edges>
gap> IsSubdigraph(g, h);
true
gap> IsSubdigraph(h, g);
false
gap> IsSubdigraph(CompleteDigraph(4), CycleDigraph(4));
true
gap> IsSubdigraph(CycleDigraph(4), ChainDigraph(4));
true
gap> g := Digraph([[2, 2], [1]]);
<multidigraph with 2 vertices, 3 edges>
gap> h := Digraph([[2], [1]]);
<digraph with 2 vertices, 2 edges>
gap> IsSubdigraph(g, h);
true
gap> IsSubdigraph(h, g);
false
```

4.1.2 IsUndirectedSpanningTree

▷ `IsUndirectedSpanningTree(`*super*`, `*sub*`)` (operation)
▷ `IsUndirectedSpanningForest(`*super*`, `*sub*`)` (operation)

Returns: `true` or `false`.

The operation `IsUndirectedSpanningTree` returns `true` if the digraph *sub* is an undirected spanning tree of the digraph *super*, and the operation `IsUndirectedSpanningForest` returns `true` if the digraph *sub* is an undirected spanning forest of the digraph *super*.

An *undirected spanning tree* of a digraph *super* is a subdigraph of *super* that is an undirected tree (see `IsSubdigraph` (4.1.1) and `IsUndirectedTree` (6.3.8)). Note that a digraph whose `MaximalSymmetricSubdigraph` (3.3.4) is not connected has no undirected spanning trees (see `IsConnectedDigraph` (6.3.3)).

An *undirected spanning forest* of a digraph *super* is a subdigraph of *super* that is an undirected forest (see `IsSubdigraph` (4.1.1) and `IsUndirectedForest` (6.3.8)), and is not contained in any larger such subdigraph of *super*. Equivalently, an undirected spanning forest is a subdigraph of *super* whose connected components coincide with those of the `MaximalSymmetricSubdigraph` (3.3.4) of *super* (see `DigraphConnectedComponents` (5.3.8)).

Note that an undirected spanning tree is an undirected spanning forest that is connected.

Example

```
gap> gr := CompleteDigraph(4);
<digraph with 4 vertices, 12 edges>
gap> tree := Digraph([[3], [4], [1, 4], [2, 3]]);
<digraph with 4 vertices, 6 edges>
gap> IsSubdigraph(gr, tree) and IsUndirectedTree(tree);
true
gap> IsUndirectedSpanningTree(gr, tree);
true
gap> forest := EmptyDigraph(4);
<digraph with 4 vertices, 0 edges>
gap> IsSubdigraph(gr, forest) and IsUndirectedForest(forest);
true
gap> IsUndirectedSpanningForest(gr, forest);
```

```
false
gap> IsSubdigraph(tree, forest);
true
gap> gr := DigraphDisjointUnion(CycleDigraph(2), CycleDigraph(2));
<digraph with 4 vertices, 4 edges>
gap> IsUndirectedTree(gr);
false
gap> IsUndirectedForest(gr) and IsUndirectedSpanningForest(gr, gr);
true
```

Chapter 5

Attributes and operations

5.1 Vertices and edges

5.1.1 DigraphVertices

▷ `DigraphVertices(`*digraph*`)` (attribute)

Returns: A list of integers.

Returns the vertices of the digraph *digraph*.

Note that the vertices of a digraph are always a range of positive integers from 1 to the number of vertices of the graph.

Example

```
gap> gr := Digraph(["a", "b", "c"],
>                  ["a", "b", "b"],
>                  ["b", "c", "a"]);
<digraph with 3 vertices, 3 edges>
gap> DigraphVertices(gr);
[ 1 .. 3 ]
gap> gr := Digraph([1, 2, 3, 4, 5, 7],
>                  [1, 2, 2, 4, 4],
>                  [2, 7, 5, 3, 7]);
<digraph with 6 vertices, 5 edges>
gap> DigraphVertices(gr);
[ 1 .. 6 ]
gap> DigraphVertices(RandomDigraph(100));
[ 1 .. 100 ]
```

5.1.2 DigraphNrVertices

▷ `DigraphNrVertices(`*digraph*`)` (attribute)

Returns: An integer.

Returns the number of vertices of the digraph *digraph*.

Example

```
gap> gr := Digraph(["a", "b", "c"],
>                  ["a", "b", "b"],
>                  ["b", "c", "a"]);
<digraph with 3 vertices, 3 edges>
gap> DigraphNrVertices(gr);
```

```
3
gap> gr := Digraph([1, 2, 3, 4, 5, 7],
>                  [1, 2, 2, 4, 4],
>                  [2, 7, 5, 3, 7]);
<digraph with 6 vertices, 5 edges>
gap> DigraphNrVertices(gr);
6
gap> DigraphNrVertices(RandomDigraph(100));
100
```

5.1.3 DigraphEdges

▷ `DigraphEdges(`*digraph*`)` (attribute)

Returns: A list of lists.

`DigraphEdges` returns a list of edges of the digraph *digraph*, where each edge is a pair of elements of `DigraphVertices` (5.1.1) of the form `[source,range]`.

The entries of `DigraphEdges(`*digraph*`)` are in one-to-one corresponence with the edges of *digraph*. Hence `DigraphEdges(`*digraph*`)` is duplicate-free if and only if *digraph* contains no multiple edges.

The entries of `DigraphEdges` are guaranteed to be sorted by their first component (i.e. by the source of each edge), but they are not necessarily then sorted by the second component.

Example

```
gap> gr := DigraphFromDiSparse6String(".DaXbOe?EAM@G~");
<multidigraph with 5 vertices, 16 edges>
gap> edges := ShallowCopy(DigraphEdges(gr));; Sort(edges);
gap> edges;
[ [ 1, 1 ], [ 1, 3 ], [ 1, 3 ], [ 1, 4 ], [ 1, 5 ], [ 2, 1 ],
  [ 2, 2 ], [ 2, 3 ], [ 2, 5 ], [ 3, 2 ], [ 3, 4 ], [ 3, 5 ],
  [ 4, 2 ], [ 4, 4 ], [ 4, 5 ], [ 5, 1 ] ]
```

5.1.4 DigraphNrEdges

▷ `DigraphNrEdges(`*digraph*`)` (attribute)

Returns: An integer.

This function returns the number of edges of the digraph *digraph*.

Example

```
gap> gr := Digraph([
> [1, 3, 4, 5], [1, 2, 3, 5], [2, 4, 5], [2, 4, 5], [1]]);;
gap> DigraphNrEdges(gr);
15
gap> gr := Digraph(["a", "b", "c"],
>                  ["a", "b", "b"],
>                  ["b", "a", "a"]);
<multidigraph with 3 vertices, 3 edges>
gap> DigraphNrEdges(gr);
3
```

5.1.5 DigraphSinks

▷ DigraphSinks(*digraph*) (attribute)

Returns: A list of vertices.

This function returns a list of the sinks of the digraph *digraph*. A sink of a digraph is a vertex with out-degree zero. See OutDegreeOfVertex (5.2.10).

Example

```
gap> gr := Digraph([[3, 5, 2, 2], [3], [], [5, 2, 5, 3], []]);
<multidigraph with 5 vertices, 9 edges>
gap> DigraphSinks(gr);
[ 3, 5 ]
```

5.1.6 DigraphSources

▷ DigraphSources(*digraph*) (attribute)

Returns: A list of vertices.

This function returns a list of the sources of the digraph *digraph*. A source of a digraph is a vertex with in-degree zero. See InDegreeOfVertex (5.2.12).

Example

```
gap> gr := Digraph([[3, 5, 2, 2], [3], [], [5, 2, 5, 3], []]);
<multidigraph with 5 vertices, 9 edges>
gap> DigraphSources(gr);
[ 1, 4 ]
```

5.1.7 DigraphTopologicalSort

▷ DigraphTopologicalSort(*digraph*) (attribute)

Returns: A list of positive integers, or fail.

If *digraph* is a digraph whose only directed cycles are loops, then DigraphTopologicalSort returns the vertices of *digraph* ordered so that every edge's source appears no earlier in the list than its range. If the digraph *digraph* contains directed cycles of length greater than 1, then this operation returns fail.

See section 1.1.1 for the definition of a directed cycle, and the definition of a loop.

The method used for this attribute has complexity $O(m+n)$ where m is the number of edges (counting multiple edges as one) and n is the number of vertices in the digraph.

Example

```
gap> gr := Digraph([
> [2, 3], [], [4, 6], [5], [], [7, 8, 9], [], [], []]);
<digraph with 9 vertices, 8 edges>
gap> DigraphTopologicalSort(gr);
[ 2, 5, 4, 7, 8, 9, 6, 3, 1 ]
```

5.1.8 DigraphVertexLabel

▷ DigraphVertexLabel(*digraph, i*) (operation)

▷ SetDigraphVertexLabel(*digraph, i, obj*) (operation)

If *digraph* is a digraph, then the first operation returns the label of the vertex *i*. The second operation can be used to set the label of the vertex *i* in *digraph* to the arbitrary GAP object *obj*.

The label of a vertex can be changed an arbitrary number of times. If no label has been set for the vertex *i*, then the default value is *i*.

If *digraph* is a digraph created from a record with a component `vertices`, then the labels of the vertices are set to the value of this component.

Induced subdigraphs, and other operations which create new digraphs from old ones, inherit their labels from their parents.

Example

```
gap> gr := DigraphFromDigraph6String("&DHUEe_");
<digraph with 5 vertices, 11 edges>
gap> DigraphVertexLabel(gr, 3);
3
gap> gr := Digraph(["a", "b", "c"], [], []);
<digraph with 3 vertices, 0 edges>
gap> DigraphVertexLabel(gr, 2);
"b"
gap> SetDigraphVertexLabel(gr, 2, "d");
gap> DigraphVertexLabel(gr, 2);
"d"
gap> gr := InducedSubdigraph(gr, [1, 2]);
<digraph with 2 vertices, 0 edges>
gap> DigraphVertexLabel(gr, 2);
"d"
```

5.1.9 DigraphVertexLabels

▷ `DigraphVertexLabels(`*digraph*`)` (operation)

▷ `SetDigraphVertexLabels(`*digraph*`, `*list*`)` (operation)

If *digraph* is a digraph, then `DigraphVertexLabels` returns a copy of the labels of the vertices in *digraph*. `SetDigraphVertexLabels` can be used to set the labels of the vertices in *digraph* to the list of arbitrary GAP objects *list*.

The label of a vertex can be changed an arbitrary number of times. If no label has been set for the vertex *i*, then the default value is *i*.

If *digraph* is a digraph created from a record with a component `vertices`, then the labels of the vertices are set to the value of this component.

Induced subdigraphs, and other operations which create new digraphs from old ones, inherit their labels from their parents.

Example

```
gap> gr := DigraphFromDigraph6String("&DHUEe_");
<digraph with 5 vertices, 11 edges>
gap> DigraphVertexLabels(gr);
[ 1 .. 5 ]
gap> gr := Digraph(["a", "b", "c"], [], []);
<digraph with 3 vertices, 0 edges>
gap> DigraphVertexLabels(gr);
[ "a", "b", "c" ]
gap> SetDigraphVertexLabel(gr, 2, "d");
gap> DigraphVertexLabels(gr);
```

```
[ "a", "d", "c" ]
gap> gr := InducedSubdigraph(gr, [1, 3]);
<digraph with 2 vertices, 0 edges>
gap> DigraphVertexLabels(gr);
[ "a", "c" ]
```

5.1.10 DigraphEdgeLabel

▷ DigraphEdgeLabel(*digraph*, *i*, *j*) (operation)
▷ SetDigraphEdgeLabel(*digraph*, *i*, *j*, *obj*) (operation)

If *digraph* is a digraph without multiple edges, then the first operation returns the label of the edge from vertex *i* to vertex *j*. The second operation can be used to set the label of the edge between vertex *i* and vertex *j* to the arbitrary GAP object *obj*.

The label of an edge can be changed an arbitrary number of times. If no label has been set for the edge, then the default value is *1*.

Induced subdigraphs, and some other operations which create new digraphs from old ones, inherit their edge labels from their parents. See also DigraphEdgeLabels (5.1.11).

Example

```
gap> gr := DigraphFromDigraph6String("&DHUEe_");
<digraph with 5 vertices, 11 edges>
gap> DigraphEdgeLabel(gr, 3, 1);
1
gap> SetDigraphEdgeLabel(gr, 2, 5, [42]);
gap> DigraphEdgeLabel(gr, 2, 5);
[ 42 ]
gap> gr := InducedSubdigraph(gr, [2, 5]);
<digraph with 2 vertices, 3 edges>
gap> DigraphEdgeLabel(gr, 1, 2);
[ 42 ]
```

5.1.11 DigraphEdgeLabels

▷ DigraphEdgeLabels(*digraph*) (operation)
▷ SetDigraphEdgeLabels(*digraph*, *labels*) (operation)
▷ SetDigraphEdgeLabels(*digraph*, *func*) (operation)

If *digraph* is a digraph without multiple edges, then DigraphEdgeLabels returns a copy of the labels of the edges in *digraph* as a list of lists labels such that labels[i][j] is the label on the edge from vertex i to vertex OutNeighbours(digraph)[i][j]. SetDigraphEdgeLabels can be used to set the labels of the edges in *digraph* without multiple edges to the list *labels* of lists of arbitrary GAP objects such that list[i][j] is the label on the edge from vertex i to the vertex OutNeighbours(digraph>[i][j]. Alternatively SetDigraphEdgeLabels can be called with binary function *func* that as its second argument that when passed two vertices i and j returns the label for the edge between vertex i and vertex j.

The label of an edge can be changed an arbitrary number of times. If no label has been set for an edge, then the default value is 1.

Induced subdigraphs, and some other operations which create new digraphs from old ones, inherit their labels from their parents.

Example

```
gap> gr := DigraphFromDigraph6String("&DHUEe_");
<digraph with 5 vertices, 11 edges>
gap> DigraphEdgeLabels(gr);
[ [ 1 ], [ 1, 1, 1 ], [ 1 ], [ 1, 1, 1 ], [ 1, 1, 1 ] ]
gap> SetDigraphEdgeLabel(gr, 2, 1, "d");
gap> DigraphEdgeLabels(gr);
[ [ 1 ], [ "d", 1, 1 ], [ 1 ], [ 1, 1, 1 ], [ 1, 1, 1 ] ]
gap> gr := InducedSubdigraph(gr, [1, 2, 3]);
<digraph with 3 vertices, 4 edges>
gap> DigraphEdgeLabels(gr);
[ [ 1 ], [ "d", 1 ], [ 1 ] ]
gap> OutNeighbours(gr);
[ [ 3 ], [ 1, 3 ], [ 1 ] ]
```

5.1.12 DigraphInEdges

▷ DigraphInEdges(*digraph*, *vertex*) (operation)

Returns: A list of edges.

DigraphInEdges returns the list of all edges of *digraph* which have *vertex* as their range.

Example

```
gap> gr := Digraph([[2, 2], [3, 3], [4, 4], [1, 1]]);
<multidigraph with 4 vertices, 8 edges>
gap> DigraphInEdges(gr, 2);
[ [ 1, 2 ], [ 1, 2 ] ]
```

5.1.13 DigraphOutEdges

▷ DigraphOutEdges(*digraph*, *vertex*) (operation)

Returns: A list of edges.

DigraphOutEdges returns the list of all edges of *digraph* which have *vertex* as their source.

Example

```
gap> gr := Digraph([[2, 2], [3, 3], [4, 4], [1, 1]]);
<multidigraph with 4 vertices, 8 edges>
gap> DigraphOutEdges(gr, 2);
[ [ 2, 3 ], [ 2, 3 ] ]
```

5.1.14 IsDigraphEdge (for digraph and list)

▷ IsDigraphEdge(*digraph*, *list*) (operation)

▷ IsDigraphEdge(*digraph*, *u*, *v*) (operation)

Returns: true or false.

In the first form, this function returns true if and only if the list *list* specifies an edge in the digraph *digraph*. Specifically, this operation returns true if *list* is a pair of positive integers where *list*[1] is the source and *list*[2] is the range of an edge in *digraph*, and false otherwise.

The second form simply returns true if [*u*, *v*] is an edge in *digraph*, and false otherwise.

Example

```
gap> gr := Digraph([[2, 2], [6], [], [3], [], [1]]);
<multidigraph with 6 vertices, 5 edges>
gap> IsDigraphEdge(gr, [1, 1]);
false
gap> IsDigraphEdge(gr, [1, 2]);
true
gap> IsDigraphEdge(gr, [1, 8]);
false
```

5.1.15 IsMatching

▷ IsMatching(*digraph*, *list*) (operation)
▷ IsMaximalMatching(*digraph*, *list*) (operation)
▷ IsPerfectMatching(*digraph*, *list*) (operation)

Returns: true or false.

If *digraph* is a digraph and *list* is a list of pairs of vertices of *digraph*, then IsMatching returns true if *list* is a matching of *digraph*. The operations IsMaximalMatching and IsPerfectMatching return true if *list* is a maximal, or perfect, matching of *digraph*, respectively. Otherwise, these operations return false.

A *matching* M of a digraph *digraph* is a subset of the edges of *digraph*, i.e. DigraphEdges(*digraph*), such that no pair of distinct edges in M are incident to the same vertex of *digraph*. Note that this definition allows a matching to contain loops. See DigraphHasLoops (6.1.1). The matching M is *maximal* if it is contained in no larger matching of the digraph, and is *perfect* if every vertex of the digraph is incident to an edge in the matching. Every perfect matching is maximal.

Example

```
gap> gr := Digraph([[2], [1], [2, 3, 4], [3, 5], [1]]);
<digraph with 5 vertices, 8 edges>
gap> IsMatching(gr, [[2, 1], [3, 2]]);
false
gap> edges := [[3, 2]];;
gap> IsMatching(gr, edges);
true
gap> IsMaximalMatching(gr, edges);
false
gap> edges := [[5, 1], [3, 3]];;
gap> IsMaximalMatching(gr, edges);
true
gap> IsPerfectMatching(gr, edges);
false
gap> edges := [[1, 2], [3, 3], [4, 5]];;
gap> IsPerfectMatching(gr, edges);
true
```

5.2 Neighbours and degree

5.2.1 AdjacencyMatrix

▷ `AdjacencyMatrix(`*digraph*`)` (attribute)
▷ `AdjacencyMatrixMutableCopy(`*digraph*`)` (operation)

Returns: A square matrix of non-negative integers.

This function returns the adjacency matrix `mat` of the digraph *digraph*. The value of the matrix entry `mat[i][j]` is the number of edges in *digraph* with source `i` and range `j`. If *digraph* has no vertices, then the empty list is returned.

The function `AdjacencyMatrix` returns an immutable list of immutable lists, whereas the function `AdjacencyMatrixMutableCopy` returns a copy of `AdjacencyMatrix` that is a mutable list of mutable lists.

Example

```
gap> gr := Digraph([
> [2, 2, 2], [1, 3, 6, 8, 9, 10], [4, 6, 8],
> [1, 2, 3, 9], [3, 3], [3, 5, 6, 10], [1, 2, 7],
> [1, 2, 3, 10, 5, 6, 10], [1, 3, 4, 5, 8, 10],
> [2, 3, 4, 6, 7, 10]]);
<multidigraph with 10 vertices, 44 edges>
gap> mat := AdjacencyMatrix(gr);;
gap> Display(mat);
[ [  0,  3,  0,  0,  0,  0,  0,  0,  0,  0 ],
  [  1,  0,  1,  0,  0,  1,  0,  1,  1,  1 ],
  [  0,  0,  0,  1,  0,  1,  0,  1,  0,  0 ],
  [  1,  1,  1,  0,  0,  0,  0,  0,  1,  0 ],
  [  0,  0,  2,  0,  0,  0,  0,  0,  0,  0 ],
  [  0,  0,  1,  0,  1,  1,  0,  0,  0,  1 ],
  [  1,  1,  0,  0,  0,  0,  1,  0,  0,  0 ],
  [  1,  1,  1,  0,  1,  1,  0,  0,  0,  2 ],
  [  1,  0,  1,  1,  1,  0,  0,  1,  0,  1 ],
  [  0,  1,  1,  1,  0,  1,  1,  0,  0,  1 ] ]
```

5.2.2 CharacteristicPolynomial

▷ `CharacteristicPolynomial(`*digraph*`)` (attribute)

Returns: A polynomial with integer coefficients.

This function returns the characteristic polynomial of the digraph *digraph*. That is it returns the characteristic polynomial of the adjacency matrix of the digraph *digraph*

Example

```
gap> gr := Digraph([
> [2, 2, 2], [1, 3, 6, 8, 9, 10], [4, 6, 8],
> [1, 2, 3, 9], [3, 3], [3, 5, 6, 10], [1, 2, 7],
> [1, 2, 3, 10, 5, 6, 10], [1, 3, 4, 5, 8, 10],
> [2, 3, 4, 6, 7, 10]]);
<multidigraph with 10 vertices, 44 edges>
gap> CharacteristicPolynomial(gr);
x_1^10-3*x_1^9-7*x_1^8-x_1^7+14*x_1^6+x_1^5-26*x_1^4+51*x_1^3-10*x_1^2\
+18*x_1-30
gap> gr := CompleteDigraph(5);
<digraph with 5 vertices, 20 edges>
```

```
gap> CharacteristicPolynomial(gr);
x_1^5-10*x_1^3-20*x_1^2-15*x_1-4
```

5.2.3 BooleanAdjacencyMatrix

▷ `BooleanAdjacencyMatrix(`*digraph*`)` (attribute)
▷ `BooleanAdjacencyMatrixMutableCopy(`*digraph*`)` (operation)

Returns: A square matrix of booleans.

If *digraph* is a digraph with a positive number of vertices `n`, then `BooleanAdjacencyMatrix(`*digraph*`)` returns the boolean adjacency matrix `mat` of *digraph*. The value of the matrix entry `mat[j][i]` is `true` if and only if there exists an edge in *digraph* with source `j` and range `i`. If *digraph* has no vertices, then the empty list is returned.

Note that the boolean adjacency matrix loses information about multiple edges.

The attribute `BooleanAdjacencyMatrix` returns an immutable list of immutable lists, whereas the function `BooleanAdjacencyMatrixMutableCopy` returns a copy of the `BooleanAdjacencyMatrix` that is a mutable list of mutable lists.

Example

```
gap> gr := Digraph([[3, 4], [2, 3], [1, 2, 4], [4]]);
<digraph with 4 vertices, 8 edges>
gap> PrintArray(BooleanAdjacencyMatrix(gr));
[ [  false,  false,   true,   true ],
  [  false,   true,   true,  false ],
  [   true,   true,  false,   true ],
  [  false,  false,  false,   true ] ]
gap> gr := CycleDigraph(4);;
gap> PrintArray(BooleanAdjacencyMatrix(gr));
[ [  false,   true,  false,  false ],
  [  false,  false,   true,  false ],
  [  false,  false,  false,   true ],
  [   true,  false,  false,  false ] ]
gap> BooleanAdjacencyMatrix(EmptyDigraph(0));
[  ]
```

5.2.4 DigraphAdjacencyFunction

▷ `DigraphAdjacencyFunction(`*digraph*`)` (attribute)

Returns: A function.

If *digraph* is a digraph, then `DigraphAdjacencyFunction` returns a function which takes two integer parameters `x`, `y` and returns `true` if there exists an edge from vertex `x` to vertex `y` in *digraph* and `false` if not.

Example

```
gap> digraph := Digraph([[1, 2], [3], []]);
<digraph with 3 vertices, 3 edges>
gap> foo := DigraphAdjacencyFunction(digraph);
function( u, v ) ... end
gap> foo(1, 1);
true
gap> foo(1, 2);
true
```

```
gap> foo(1, 3);
false
gap> foo(3, 1);
false
gap> gr := Digraph(["a", "b", "c"],
>                  ["a", "b", "b"],
>                  ["b", "a", "a"]);
<multidigraph with 3 vertices, 3 edges>
gap> foo := DigraphAdjacencyFunction(gr);
function( u, v ) ... end
gap> foo(1, 2);
true
gap> foo(3, 2);
false
gap> foo(3, 1);
false
```

5.2.5 DigraphRange

▷ DigraphRange(*digraph*) (attribute)
▷ DigraphSource(*digraph*) (attribute)

Returns: A list of positive integers.

DigraphRange and DigraphSource return the range and source of the digraph *digraph*. More precisely, position i in DigraphRange(*digraph*) is the range of the ith edge of *digraph*.

Example

```
gap> gr := Digraph([
> [2, 1, 3, 5], [1, 3, 4], [2, 3], [2], [1, 2, 3, 4]]);
<digraph with 5 vertices, 14 edges>
gap> DigraphRange(gr);
[ 2, 1, 3, 5, 1, 3, 4, 2, 3, 2, 1, 2, 3, 4 ]
gap> DigraphSource(gr);
[ 1, 1, 1, 1, 2, 2, 2, 3, 3, 4, 5, 5, 5, 5 ]
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 1, 1 ], [ 1, 3 ], [ 1, 5 ], [ 2, 1 ], [ 2, 3 ],
  [ 2, 4 ], [ 3, 2 ], [ 3, 3 ], [ 4, 2 ], [ 5, 1 ], [ 5, 2 ],
  [ 5, 3 ], [ 5, 4 ] ]
```

5.2.6 OutNeighbours

▷ OutNeighbours(*digraph*) (attribute)
▷ OutNeighbors(*digraph*) (attribute)
▷ OutNeighboursMutableCopy(*digraph*) (operation)
▷ OutNeighborsMutableCopy(*digraph*) (operation)

Returns: The adjacencies of a digraph.

This function returns the list out of out-neighbours of each vertex of the digraph *digraph*. More specifically, a vertex j appears in out[i] each time there exists an edge with source i and range j in *digraph*.

The function OutNeighbours returns an immutable list of immutable lists, whereas the function OutNeighboursMutableCopy returns a copy of OutNeighbours which is a mutable list of mutable lists.

Example

```
gap> gr := Digraph(["a", "b", "c"],
>                  ["a", "b", "b"],
>                  ["b", "a", "c"]);
<digraph with 3 vertices, 3 edges>
gap> OutNeighbours(gr);
[ [ 2 ], [ 1, 3 ], [  ] ]
gap> gr := Digraph([[1, 2, 3], [2, 1], [3]]);
<digraph with 3 vertices, 6 edges>
gap> OutNeighbours(gr);
[ [ 1, 2, 3 ], [ 2, 1 ], [ 3 ] ]
gap> gr := DigraphByAdjacencyMatrix([
>  [1, 2, 1],
>  [1, 1, 0],
>  [0, 0, 1]]);
<multidigraph with 3 vertices, 7 edges>
gap> OutNeighbours(gr);
[ [ 1, 2, 2, 3 ], [ 1, 2 ], [ 3 ] ]
gap> OutNeighboursMutableCopy(gr);
[ [ 1, 2, 2, 3 ], [ 1, 2 ], [ 3 ] ]
```

5.2.7 InNeighbours

▷ InNeighbours(*digraph*) (attribute)
▷ InNeighbors(*digraph*) (attribute)
▷ InNeighboursMutableCopy(*digraph*) (operation)
▷ InNeighborsMutableCopy(*digraph*) (operation)

Returns: A list of lists of vertices.

This function returns the list `inn` of in-neighbours of each vertex of the digraph *digraph*. More specifically, a vertex `j` appears in `inn[i]` each time there exists an edge with source `j` and range `i` in *digraph*.

The function `InNeighbours` returns an immutable list of immutable lists, whereas the function `InNeighboursMutableCopy` returns a copy of `InNeighbours` which is a mutable list of mutable lists.

Note that each entry of `inn` is sorted into ascending order.

Example

```
gap> gr := Digraph(["a", "b", "c"],
>                  ["a", "b", "b"],
>                  ["b", "a", "c"]);
<digraph with 3 vertices, 3 edges>
gap> InNeighbours(gr);
[ [ 2 ], [ 1 ], [ 2 ] ]
gap> gr := Digraph([[1, 2, 3], [2, 1], [3]]);
<digraph with 3 vertices, 6 edges>
gap> InNeighbours(gr);
[ [ 1, 2 ], [ 1, 2 ], [ 1, 3 ] ]
gap> gr := DigraphByAdjacencyMatrix([
>  [1, 2, 1],
>  [1, 1, 0],
>  [0, 0, 1]]);
```

```
<multidigraph with 3 vertices, 7 edges>
gap> InNeighbours(gr);
[ [ 1, 2 ], [ 1, 1, 2 ], [ 1, 3 ] ]
gap> InNeighboursMutableCopy(gr);
[ [ 1, 2 ], [ 1, 1, 2 ], [ 1, 3 ] ]
```

5.2.8 OutDegrees

▷ `OutDegrees(`*digraph*`)` (attribute)
▷ `OutDegreeSequence(`*digraph*`)` (attribute)
▷ `OutDegreeSet(`*digraph*`)` (attribute)

Returns: A list of non-negative integers.

Given a digraph *digraph* with n vertices, the function `OutDegrees` returns a list `out` of length n, such that for a vertex `i` in *digraph*, the value of `out[i]` is the out-degree of vertex `i`. See `OutDegreeOfVertex` (5.2.10).

The function `OutDegreeSequence` returns the same list, after it has been sorted into non-increasing order.

The function `OutDegreeSet` returns the same list, sorted into increasing order with duplicate entries removed.

Example

```
gap> gr := Digraph([[1, 3, 2, 2], [], [2, 1], []]);
<multidigraph with 4 vertices, 6 edges>
gap> OutDegrees(gr);
[ 4, 0, 2, 0 ]
gap> OutDegreeSequence(gr);
[ 4, 2, 0, 0 ]
gap> OutDegreeSet(gr);
[ 0, 2, 4 ]
```

5.2.9 InDegrees

▷ `InDegrees(`*digraph*`)` (attribute)
▷ `InDegreeSequence(`*digraph*`)` (attribute)
▷ `InDegreeSet(`*digraph*`)` (attribute)

Returns: A list of non-negative integers.

Given a digraph *digraph* with n vertices, the function `InDegrees` returns a list `inn` of length n, such that for a vertex `i` in *digraph*, the value of `inn[i]` is the in-degree of vertex `i`. See `InDegreeOfVertex` (5.2.12).

The function `InDegreeSequence` returns the same list, after it has been sorted into non-increasing order.

The function `InDegreeSet` returns the same list, sorted into increasing order with duplicate entries removed.

Example

```
gap> gr := Digraph([[1, 3, 2, 2, 4], [], [2, 1, 4], []]);
<multidigraph with 4 vertices, 8 edges>
gap> InDegrees(gr);
[ 2, 3, 1, 2 ]
gap> InDegreeSequence(gr);
```

```
[ 3, 2, 2, 1 ]
gap> InDegreeSet(gr);
[ 1, 2, 3 ]
```

5.2.10 OutDegreeOfVertex

▷ OutDegreeOfVertex(*digraph*, *vertex*) (operation)

Returns: The non-negative integer.

This operation returns the out-degree of the vertex *vertex* in the digraph *digraph*. The out-degree of *vertex* is the number of edges in *digraph* whose source is *vertex*.

Example

```
gap> gr := Digraph([
> [2, 2, 1], [1, 4], [2, 2, 4, 2], [1, 1, 2, 2, 1, 2, 2]]);
<multidigraph with 4 vertices, 16 edges>
gap> OutDegreeOfVertex(gr, 1);
3
gap> OutDegreeOfVertex(gr, 2);
2
gap> OutDegreeOfVertex(gr, 3);
4
gap> OutDegreeOfVertex(gr, 4);
7
```

5.2.11 OutNeighboursOfVertex

▷ OutNeighboursOfVertex(*digraph*, *vertex*) (operation)

▷ OutNeighborsOfVertex(*digraph*, *vertex*) (operation)

Returns: A list of vertices.

This operation returns the list out of vertices of the digraph *digraph*. A vertex i appears in the list out each time there exists an edge with source *vertex* and range i in *digraph*; in particular, this means that out may contain duplicates.

Example

```
gap> gr := Digraph([
> [2, 2, 3], [1, 3, 4], [2, 2, 3], [1, 1, 2, 2, 1, 2, 2]]);
<multidigraph with 4 vertices, 16 edges>
gap> OutNeighboursOfVertex(gr, 1);
[ 2, 2, 3 ]
gap> OutNeighboursOfVertex(gr, 3);
[ 2, 2, 3 ]
```

5.2.12 InDegreeOfVertex

▷ InDegreeOfVertex(*digraph*, *vertex*) (operation)

Returns: A non-negative integer.

This operation returns the in-degree of the vertex *vertex* in the digraph *digraph*. The in-degree of *vertex* is the number of edges in *digraph* whose range is *vertex*.

Example

```
gap> gr := Digraph([
> [2, 2, 1], [1, 4], [2, 2, 4, 2], [1, 1, 2, 2, 1, 2, 2]]);
```

```
<multidigraph with 4 vertices, 16 edges>
gap> InDegreeOfVertex(gr, 1);
5
gap> InDegreeOfVertex(gr, 2);
9
gap> InDegreeOfVertex(gr, 3);
0
gap> InDegreeOfVertex(gr, 4);
2
```

5.2.13 InNeighboursOfVertex

▷ InNeighboursOfVertex(*digraph*, *vertex*) (operation)
▷ InNeighborsOfVertex(*digraph*, *vertex*) (operation)

Returns: A list of postitive vertices.

This operation returns the list inn of vertices of the digraph *digraph*. A vertex i appears in the list inn each time there exists an edge with source i and range *vertex* in *digraph*; in particular, this means that inn may contain duplicates.

Example

```
gap> gr := Digraph([
> [2, 2, 3], [1, 3, 4], [2, 2, 3], [1, 1, 2, 2, 1, 2, 2]]);
<multidigraph with 4 vertices, 16 edges>
gap> InNeighboursOfVertex(gr, 1);
[ 2, 4, 4, 4 ]
gap> InNeighboursOfVertex(gr, 2);
[ 1, 1, 3, 3, 4, 4, 4, 4 ]
```

5.2.14 DigraphLoops

▷ DigraphLoops(*digraph*) (attribute)

Returns: A list of vertices.

If *digraph* is a digraph, then DigraphLoops returns the list consisting of the DigraphVertices (5.1.1) of *digraph* at which there is a loop. See DigraphHasLoops (6.1.1).

Example

```
gap> gr := Digraph([[2], [3], []]);
<digraph with 3 vertices, 2 edges>
gap> DigraphHasLoops(gr);
false
gap> DigraphLoops(gr);
[  ]
gap> gr := Digraph([[3, 5], [1], [2, 4, 3], [4], [2, 1]]);
<digraph with 5 vertices, 9 edges>
gap> DigraphLoops(gr);
[ 3, 4 ]
```

5.2.15 PartialOrderDigraphMeetOfVertices (for a digraph and two vertices)

▷ PartialOrderDigraphMeetOfVertices(*digraph*, *u*, *v*) (operation)
▷ PartialOrderDigraphJoinOfVertices(*digraph*, *u*, *v*) (operation)

Returns: A positive integer or fail

If the first argument is a partial order digraph `IsPartialOrderDigraph` (6.1.14) then these operations return the meet, or the join, of the two input vertices. If the meet (or join) is does not exist then `fail` is returned. The meet (or join) is guaranteed to exist when the first argument satisfies `IsMeetSemilatticeDigraph` (6.1.15) (or `IsJoinSemilatticeDigraph` (6.1.15)) - see the documentation for these properties for the definition of the meet (or the join).

Example

```
gap> gr := Digraph([[1], [1, 2], [1, 3], [1, 2, 3, 4]]);
<digraph with 4 vertices, 9 edges>
gap> PartialOrderDigraphMeetOfVertices(gr, 2, 3);
4
gap> PartialOrderDigraphJoinOfVertices(gr, 2, 3);
1
gap> PartialOrderDigraphMeetOfVertices(gr, 1, 2);
2
gap> PartialOrderDigraphJoinOfVertices(gr, 3, 4);
3
gap> gr := Digraph([[1], [2], [1, 2, 3], [1, 2, 4]]);
<digraph with 4 vertices, 8 edges>
gap> PartialOrderDigraphMeetOfVertices(gr, 3, 4);
fail
gap> PartialOrderDigraphJoinOfVertices(gr, 3, 4);
fail
gap> PartialOrderDigraphMeetOfVertices(gr, 1, 2);
fail
gap> PartialOrderDigraphJoinOfVertices(gr, 1, 2);
fail
```

5.3 Reachability and connectivity

5.3.1 DigraphDiameter

▷ `DigraphDiameter(`*digraph*`)` (attribute)

Returns: An integer or `fail`.

This function returns the diameter of the digraph *digraph*.

If a digraph *digraph* is strongly connected and has at least 1 vertex, then the *diameter* is the maximum shortest distance between any pair of distinct vertices. Otherwise then the diameter of *digraph* is undefined, and this function returns the value `fail`.

See `DigraphShortestDistances` (5.3.3).

Example

```
gap> gr := Digraph([[2], [3], [4, 5], [5], [1, 2, 3, 4, 5]]);
<digraph with 5 vertices, 10 edges>
gap> DigraphDiameter(gr);
3
gap> gr := ChainDigraph(2);
<digraph with 2 vertices, 1 edge>
gap> DigraphDiameter(gr);
fail
gap> IsStronglyConnectedDigraph(gr);
false
```

5.3.2 DigraphShortestDistance (for a digraph and two vertices)

▷ DigraphShortestDistance(*digraph*, *u*, *v*) (operation)
▷ DigraphShortestDistance(*digraph*, *list*) (operation)
▷ DigraphShortestDistance(*digraph*, *list1*, *list2*) (operation)

Returns: An integer or fail

If there is a directed path in the digraph *digraph* between vertex *u* and vertex *v*, then this operation returns the length of the shortest such directed path. If no such directed path exists, then this operation returns fail. See section 1.1.1 for the definition of a directed path.

If the second form is used, then *list* should be a list of length two, containing two positive integers which correspond to the vertices *u* and *v*.

Note that as usual, a vertex is considered to be at distance 0 from itself .

If the third form is used, then *list1* and *list2* are both lists of vertices. The shortest directed path between *list1* and *list2* is then the length of the shortest directed path which starts with a vertex in *list1* and terminates at a vertex in *list2*, if such directed path exists. If *list1* and *list2* have non-empty intersection, the operation returns 0.

Example

```
gap> gr := Digraph([[2], [3], [1, 4], [1, 3], [5]]);
<digraph with 5 vertices, 7 edges>
gap> DigraphShortestDistance(gr, 1, 3);
2
gap> DigraphShortestDistance(gr, [3, 3]);
0
gap> DigraphShortestDistance(gr, 5, 2);
fail
gap> DigraphShortestDistance(gr, [1, 2], [4, 5]);
2
gap> DigraphShortestDistance(gr, [1, 3], [3, 5]);
0
```

5.3.3 DigraphShortestDistances

▷ DigraphShortestDistances(*digraph*) (attribute)

Returns: A square matrix.

If *digraph* is a digraph with n vertices, then this function returns an $n \times n$ matrix mat, where each entry is either a non-negative integer, or fail. If $n = 0$, then an empty list is returned.

If there is a directed path from vertex i to vertex j, then the value of mat[i][j] is the length of the shortest such directed path. If no such directed path exists, then the value of mat[i][j] is fail. We use the convention that the distance from every vertex to itself is 0, i.e. mat[i][i] = 0 for all vertices i.

The method used in this function is a version of the Floyd-Warshall algorithm, and has complexity $O(n^3)$.

Example

```
gap> gr := Digraph([[1, 2], [3], [1, 2], [4]]);
<digraph with 4 vertices, 6 edges>
gap> mat := DigraphShortestDistances(gr);;
gap> PrintArray(mat);
[ [    0,    1,    2,  fail ],
  [    2,    0,    1,  fail ],
```

```
    [     1,     1,     0,  fail ],
    [  fail,  fail,  fail,     0 ] ]
```

5.3.4 DigraphLongestDistanceFromVertex

▷ DigraphLongestDistanceFromVertex(*digraph, v*) (operation)

Returns: An integer, or `infinity`.

If *digraph* is a digraph and *v* is a vertex in *digraph*, then this operation returns the length of the longest directed walk in *digraph* which begins at vertex *v*. See section 1.1.1 for the definitions of directed walk, directed cycle, and loop.

- If there exists a directed walk starting at vertex *v* which traverses a loop or a directed cycle, then we consider there to be a walk of infinite length from *v* (realised by repeatedly traversing the loop/directed cycle), and so the result is `infinity`. To disallow walks using loops, try using `DigraphRemoveLoops` (3.3.23):

  `DigraphLongestDistanceFromVertex(DigraphRemoveLoops(`*digraph*`,`*v*`))`.

- Otherwise, if all directed walks starting at vertex *v* have finite length, then the length of the longest such walk is returned.

Note that the result is `0` if and only if *v* is a sink of *digraph*. See `DigraphSinks` (5.1.5).

Example

```
gap> gr := Digraph([[2], [3, 4], [], [5], [], [6]]);
<digraph with 6 vertices, 5 edges>
gap> DigraphLongestDistanceFromVertex(gr, 1);
3
gap> DigraphLongestDistanceFromVertex(gr, 3);
0
gap> 3 in DigraphSinks(gr);
true
gap> DigraphLongestDistanceFromVertex(gr, 6);
infinity
```

5.3.5 DigraphDistanceSet (for a digraph, a pos int, and an int)

▷ DigraphDistanceSet(*digraph, vertex, distance*) (operation)

▷ DigraphDistanceSet(*digraph, vertex, distances*) (operation)

Returns: A list of vertices

This operation returns the list of all vertices in digraph *digraph* such that the shortest distance to a vertex *vertex* is *distance* or is in the list *distances*.

digraph should be a digraph, *vertex* should be a positive integer, *distance* should be a non-negative integer, and *distances* should be a list of non-negative integers.

Example

```
gap> gr := Digraph([[2], [3], [1, 4], [1, 3]]);
<digraph with 4 vertices, 6 edges>
gap> DigraphDistanceSet(gr, 2, [1, 2]);
[ 3, 1, 4 ]
gap> DigraphDistanceSet(gr, 3, 1);
[ 1, 4 ]
```

```
gap> DigraphDistanceSet(gr, 2, 0);
[ 2 ]
```

5.3.6 DigraphGirth

▷ DigraphGirth(*digraph*) (attribute)

Returns: An integer, or `infinity`.

This attribute returns the *girth* of the digraph *digraph*. The *girth* of a digraph is the length of its shortest simple circuit. See section 1.1.1 for the definitions of simple circuit, directed cycle, and loop.

If *digraph* has no directed cycles, then this function will return `infinity`. If *digraph* contains a loop, then this function will return `1`.

In the worst case, the method used in this function is a version of the Floyd-Warshall algorithm, and has complexity `O(`*n*` ^ 3)`, where *n* is the number of vertices in *digraph*. If the digraph has known automorphisms [see `DigraphGroup` (7.2.9)], then the performance is likely to be better.

For symmetric digraphs, see also `DigraphUndirectedGirth` (5.3.7).

Example

```
gap> gr := Digraph([[1], [1]]);
<digraph with 2 vertices, 2 edges>
gap> DigraphGirth(gr);
1
gap> gr := Digraph([[2, 3], [3], [4], []]);
<digraph with 4 vertices, 4 edges>
gap> DigraphGirth(gr);
infinity
gap> gr := Digraph([[2, 3], [3], [4], [1]]);
<digraph with 4 vertices, 5 edges>
gap> DigraphGirth(gr);
3
```

5.3.7 DigraphUndirectedGirth

▷ DigraphUndirectedGirth(*digraph*) (attribute)

Returns: An integer or `infinity`.

If *digraph* is a symmetric digraph, then this function returns the girth of *digraph* when treated as an undirected graph (i.e. each pair of edges $[i, j]$ and $[j, i]$ is treated as a single edge between i and j).

The *girth* of an undirected graph is the length of its shortest simple cycle, i.e. the shortest non-trivial path starting and ending at the same vertex and passing through no vertex or edge more than once.

If *digraph* has no cycles, then this function will return `infinity`.

Example

```
gap> gr := Digraph([[2, 4], [1, 3], [2, 4], [1, 3]]);
<digraph with 4 vertices, 8 edges>
gap> DigraphUndirectedGirth(gr);
4
gap> gr := Digraph([[2], [1, 3], [2]]);
<digraph with 3 vertices, 4 edges>
gap> DigraphUndirectedGirth(gr);
```

```
infinity
gap> gr := Digraph([[1], [], [4], [3]]);
<digraph with 4 vertices, 3 edges>
gap> DigraphUndirectedGirth(gr);
1
```

5.3.8 DigraphConnectedComponents

▷ DigraphConnectedComponents(*digraph*) (attribute)

Returns: A record.

This function returns the record wcc corresponding to the weakly connected components of the digraph *digraph*. Two vertices of *digraph* are in the same weakly connected component whenever they are equal, or there exists a directed path (ignoring the orientation of edges) between them. More formally, two vertices are in the same weakly connected component of *digraph* if and only if they are in the same strongly connected component (see DigraphStronglyConnectedComponents (5.3.10)) of the DigraphSymmetricClosure (3.3.10) of *digraph*.

The set of weakly connected components is a partition of the vertex set of *digraph*.

The record wcc has 2 components: comps and id. The component comps is a list of the weakly connected components of *digraph* (each of which is a list of vertices). The component id is a list such that the vertex i is an element of the weakly connected component comps[id[i]].

The method used in this function has complexity $O(m+n)$, where m is the number of edges and n is the number of vertices in the digraph.

Example

```
gap> gr := Digraph([[2], [3, 1], []]);
<digraph with 3 vertices, 3 edges>
gap> DigraphConnectedComponents(gr);
rec( comps := [ [ 1, 2, 3 ] ], id := [ 1, 1, 1 ] )
gap> gr := Digraph([[1], [1, 2], []]);
<digraph with 3 vertices, 3 edges>
gap> DigraphConnectedComponents(gr);
rec( comps := [ [ 1, 2 ], [ 3 ] ], id := [ 1, 1, 2 ] )
gap> gr := EmptyDigraph(0);
<digraph with 0 vertices, 0 edges>
gap> DigraphConnectedComponents(gr);
rec( comps := [  ], id := [  ] )
```

5.3.9 DigraphConnectedComponent

▷ DigraphConnectedComponent(*digraph*, *vertex*) (operation)

Returns: A list of vertices.

If *vertex* is a vertex in the digraph *digraph*, then this operation returns the connected component of *vertex* in *digraph*. See DigraphConnectedComponents (5.3.8) for more information.

Example

```
gap> gr := Digraph([[3], [2], [1, 2], [4]]);
<digraph with 4 vertices, 5 edges>
gap> DigraphConnectedComponent(gr, 3);
[ 1, 2, 3 ]
gap> DigraphConnectedComponent(gr, 2);
[ 1, 2, 3 ]
```

```
gap> DigraphConnectedComponent(gr, 4);
[ 4 ]
```

5.3.10 DigraphStronglyConnectedComponents

▷ DigraphStronglyConnectedComponents(*digraph*) (attribute)

Returns: A record.

This function returns the record scc corresponding to the strongly connected components of the digraph *digraph*. Two vertices of *digraph* are in the same strongly connected component whenever they are equal, or there is a directed path from each vertex to the other. The set of strongly connected components is a partition of the vertex set of *digraph*.

The record scc has 2 components: comps and id. The component comps is a list of the strongly connected components of *digraph* (each of which is a list of vertices). The component id is a list such that the vertex i is an element of the strongly connected component comps[id[i]].

The method used in this function is a non-recursive version of Gabow's Algorithm [Gab00] and has complexity $O(m+n)$ where m is the number of edges (counting multiple edges as one) and n is the number of vertices in the digraph.

Example

```
gap> gr := Digraph([[2], [3, 1], []]);
<digraph with 3 vertices, 3 edges>
gap> DigraphStronglyConnectedComponents(gr);
rec( comps := [ [ 3 ], [ 1, 2 ] ], id := [ 2, 2, 1 ] )
```

5.3.11 DigraphStronglyConnectedComponent

▷ DigraphStronglyConnectedComponent(*digraph*, *vertex*) (operation)

Returns: A list of vertices.

If *vertex* is a vertex in the digraph *digraph*, then this operation returns the strongly connected component of *vertex* in *digraph*. See DigraphStronglyConnectedComponents (5.3.10) for more information.

Example

```
gap> gr := Digraph([[3], [2], [1, 2], [3]]);
<digraph with 4 vertices, 5 edges>
gap> DigraphStronglyConnectedComponent(gr, 3);
[ 1, 3 ]
gap> DigraphStronglyConnectedComponent(gr, 2);
[ 2 ]
gap> DigraphStronglyConnectedComponent(gr, 4);
[ 4 ]
```

5.3.12 DigraphBicomponents

▷ DigraphBicomponents(*digraph*) (attribute)

Returns: A pair of lists of vertices, or fail.

If *digraph* is a bipartite digraph, i.e. if it satisfies IsBipartiteDigraph (6.1.3), then DigraphBicomponents returns a pair of bicomponents of *digraph*. Otherwise, DigraphBicomponents returns fail.

For a bipartite digraph, the vertices can be partitioned into two non-empty sets such that the source and range of any edge are in distinct sets. The parts of this partition are called *bicomponents* of *digraph*. Equivalently, a pair of bicomponents of *digraph* consists of the color-classes of a 2-coloring of *digraph*.

For a bipartite digraph with at least 3 vertices, there is a unique pair of bicomponents of bipartite if and only if the digraph is connected. See IsConnectedDigraph (6.3.3) for more information.

Example

```
gap> gr := CycleDigraph(3);
<digraph with 3 vertices, 3 edges>
gap> DigraphBicomponents(gr);
fail
gap> gr := ChainDigraph(5);
<digraph with 5 vertices, 4 edges>
gap> DigraphBicomponents(gr);
[ [ 1, 3, 5 ], [ 2, 4 ] ]
gap> gr := Digraph([[5], [1, 4], [5], [5], []]);
<digraph with 5 vertices, 5 edges>
gap> DigraphBicomponents(gr);
[ [ 1, 3, 4 ], [ 2, 5 ] ]
```

5.3.13 ArticulationPoints

▷ ArticulationPoints(*digraph*) (attribute)

Returns: A list of vertices.

A connected digraph is *biconnected* if it is still connected (in the sense of IsConnectedDigraph (6.3.3)) when any vertex is removed. If the digraph *digraph* is not biconnected but is connected, then any vertex v of *digraph* whose removal makes the resulting digraph disconnected is called an *articulation point*.

ArticulationPoints returns a list of the articulation points of *digraph*, if any, and, in particular, returns the empty list if *digraph* is not connected.

Multiple edges and loops are ignored by this method.

The method used in this operation has complexity $O(m+n)$ where m is the number of edges (counting multiple edges as one, and not counting loops) and n is the number of vertices in the digraph. See also IsBiconnectedDigraph (6.3.4).

Example

```
gap> ArticulationPoints(CycleDigraph(5));
[  ]
gap> digraph := Digraph([[2, 7], [3, 5], [4], [2], [6], [1], []]);;
gap> ArticulationPoints(digraph);
[ 2, 1 ]
gap> ArticulationPoints(ChainDigraph(5));
[ 4, 3, 2 ]
gap> ArticulationPoints(NullDigraph(5));
[  ]
```

5.3.14 DigraphPeriod

▷ DigraphPeriod(*digraph*) (attribute)

Returns: An integer.

This function returns the period of the digraph *digraph*.

If a digraph *digraph* has at least one directed cycle, then the period is the greatest positive integer which divides the lengths of all directed cycles of *digraph*. If *digraph* has no directed cycles, then this function returns 0. See section 1.1.1 for the definition of a directed cycle.

A digraph with a period of 1 is said to be *aperiodic*. See IsAperiodicDigraph (6.3.6).

Example

```
gap> gr := Digraph([[6], [1], [2], [3], [4, 4], [5]]);
<multidigraph with 6 vertices, 7 edges>
gap> DigraphPeriod(gr);
6
gap> gr := Digraph([[2], [3, 5], [4], [5], [1, 2]]);
<digraph with 5 vertices, 7 edges>
gap> DigraphPeriod(gr);
1
gap> gr := ChainDigraph(2);
<digraph with 2 vertices, 1 edge>
gap> DigraphPeriod(gr);
0
gap> IsAcyclicDigraph(gr);
true
```

5.3.15 DigraphFloydWarshall

▷ DigraphFloydWarshall(*digraph*, *func*, *nopath*, *edge*) (operation)

Returns: A matrix.

If *digraph* is a digraph with n vertices, then this operation returns an $n \times n$ matrix mat containing the output of a generalised version of the Floyd-Warshall algorithm, applied to *digraph*.

The operation DigraphFloydWarshall is customised by the arguments *func*, *nopath*, and *edge*. The arguments *nopath* and *edge* can be arbitrary GAP objects. The argument *func* must be a function which accepts 4 arguments: the matrix mat, followed by 3 postive integers. The function *func* is where the work to calculate the desired outcome must be performed.

This method initialises the matrix mat by setting entry mat[i][j] to equal *edge* if there is an edge with source i and range j, and by setting entry mat[i][j] to equal *nopath* otherwise. The final part of DigraphFloydWarshall then calls the function *func* inside three nested for loops, over the vertices of *digraph*:

```
for i in DigraphsVertices(digraph) do
  for j in DigraphsVertices(digraph) do
    for k in DigraphsVertices(digraph) do
      func(mat, i, j, k);
    od;
  od;
od;
```

The matrix mat is then returned as the result. An example of using DigraphFloydWarshall to calculate the shortest (non-zero) distances between the vertices of a digraph is shown below:

Example

```
gap> gr := DigraphFromDigraph6String("&EAHQeDB");
<digraph with 6 vertices, 12 edges>
```

```
gap> func := function(mat, i, j, k)
>   if mat[i][k] <> -1 and mat[k][j] <> -1 then
>     if (mat[i][j] = -1) or (mat[i][j] > mat[i][k] + mat[k][j]) then
>       mat[i][j] := mat[i][k] + mat[k][j];
>     fi;
>   fi;
> end;
function( mat, i, j, k ) ... end
gap> shortest_distances := DigraphFloydWarshall(gr, func, -1, 1);;
gap> Display(shortest_distances);
[ [  3,  -1,  -1,   2,   1,   2 ],
  [  4,   2,   1,   3,   2,   1 ],
  [  3,   1,   2,   2,   1,   2 ],
  [  1,  -1,  -1,   1,   1,   2 ],
  [  2,  -1,  -1,   1,   2,   1 ],
  [  3,  -1,  -1,   2,   1,   1 ] ]
```

5.3.16 IsReachable

▷ `IsReachable(`*`digraph, u, v`*`)` (operation)

Returns: `true` or `false`.

This operation returns `true` if there exists a non-trivial directed walk from vertex `u` to vertex `v` in the digraph *`digraph`*, and `false` if there does not exist such a directed walk. See section 1.1.1 for the definition of a non-trivial directed walk.

The method for `IsReachable` has worst case complexity of $O(m+n)$ where m is the number of edges and n the number of vertices in *`digraph`*.

Example

```
gap> gr := Digraph([[2], [3], [2, 3]]);
<digraph with 3 vertices, 4 edges>
gap> IsReachable(gr, 1, 3);
true
gap> IsReachable(gr, 2, 1);
false
gap> IsReachable(gr, 3, 3);
true
gap> IsReachable(gr, 1, 1);
false
```

5.3.17 DigraphPath

▷ `DigraphPath(`*`digraph, u, v`*`)` (operation)

Returns: A pair of lists, or `fail`.

If there exists a non-trivial directed path (or a non-trivial cycle, in the case that `u = v`) from vertex `u` to vertex `v` in the digraph *`digraph`*, then this operation returns such a directed path (or directed cycle). Otherwise, this operation returns `fail`. See Section 'Definitions' for the definition of a directed path and a directed cycle.

A directed path (or directed cycle) of non-zero length `n-1`, $(v_1, e_1, v_2, e_2, \ldots, e_{n-1}, v_n)$, is represented by a pair of lists `[v,a]` as follows:

- `v` is the list $[v_1, v_2, \ldots, v_n]$.

- a is the list of positive integers $[a_1, a_2, \ldots, a_{n-1}]$ where for each each $i < n$, a_i is the position of v_{i+1} in `OutNeighboursOfVertex(`*digraph*`,`v_i`)` corresponding to the edge e_i. This is can be useful if the position of a vertex in a list of out-neighours is significant, for example in orbit digraphs.

The method for `DigraphPath` has worst case complexity of $O(m+n)$ where m is the number of edges and n the number of vertices in *digraph*.

Example

```
gap> gr := Digraph([[2], [3], [2, 3]]);
<digraph with 3 vertices, 4 edges>
gap> DigraphPath(gr, 1, 3);
[ [ 1, 2, 3 ], [ 1, 1 ] ]
gap> DigraphPath(gr, 2, 1);
fail
gap> DigraphPath(gr, 3, 3);
[ [ 3, 3 ], [ 2 ] ]
gap> DigraphPath(gr, 1, 1);
fail
```

5.3.18 DigraphShortestPath

▷ `DigraphShortestPath(`*digraph, u, v*`)` (operation)

Returns: A pair of lists, or `fail`.

Returns the shortest directed path in the digraph digraph from the vertex u to the vertex v, if such a path exists. If u = v, then the shortest non-trivial cycle is returned, again, if it exists. Otherwise, this operation returns `fail`. See Section 'Definitions' for the definition of a directed path and a directed cycle.

See `DigraphPath` (5.3.17) for details on the output. The method for `DigraphShortestPath` has worst case complexity of $O(m+n)$ where m is the number of edges and n the number of vertices in *digraph*.

Example

```
gap> gr := Digraph([[1, 2], [3], [2, 4], [1], [2, 4]]);
<digraph with 5 vertices, 8 edges>
gap> DigraphShortestPath(gr, 5, 1);
[ [ 5, 4, 1 ], [ 2, 1 ] ]
gap> DigraphShortestPath(gr, 3, 3);
[ [ 3, 2, 3 ], [ 1, 1 ] ]
gap> DigraphShortestPath(gr, 5, 5);
fail
gap> DigraphShortestPath(gr, 1, 1);
[ [ 1, 1 ], [ 1 ] ]
```

5.3.19 IteratorOfPaths

▷ `IteratorOfPaths(`*digraph, u, v*`)` (operation)

Returns: An iterator.

If *digraph* is a digraph or a list of adjacencies which defines a digraph - see `OutNeighbours` (5.2.6) - then this operation returns an iterator of the non-trivial directed paths (or directed cycles, in the case that `u = v`) in *digraph* from the vertex `u` to the vertex `v`.

See DigraphPath (5.3.17) for more information about the repesentation of a directed path or directed cycle which is used, and see (**Reference: Iterators**) for more information about iterators. See Section 'Definitions' for the definition of a directed path and a directed cycle.

Example

```
gap> gr := Digraph([[1, 4, 4, 2], [3, 5], [2, 3], [1, 2], [4]]);
<multidigraph with 5 vertices, 11 edges>
gap> iter := IteratorOfPaths(gr, 1, 4);
<iterator>
gap> NextIterator(iter);
[ [ 1, 4 ], [ 2 ] ]
gap> NextIterator(iter);
[ [ 1, 4 ], [ 3 ] ]
gap> NextIterator(iter);
[ [ 1, 2, 5, 4 ], [ 4, 2, 1 ] ]
gap> IsDoneIterator(iter);
true
gap> iter := IteratorOfPaths(gr, 4, 3);
<iterator>
gap> NextIterator(iter);
[ [ 4, 1, 2, 3 ], [ 1, 4, 1 ] ]
```

5.3.20 DigraphAllSimpleCircuits

▷ DigraphAllSimpleCircuits(*digraph*) (attribute)

Returns: A list of lists of vertices.

If *digraph* is a digraph, then DigraphAllSimpleCircuits returns a list of the *simple circuits* in *digraph*.

See section 1.1.1 for the definition of a simple circuit, and related notions. Note that a loop is a simple circuit.

For a digraph without multiple edges, a simple circuit is uniquely determined by its subsequence of vertices. However this is not the case for a multidigraph. The attribute DigraphAllSimpleCircuits ignores multiple edges, and identifies a simple circuit using only its subsequence of vertices. For example, although the simple circuits (v,e,v) and (v,e',v) (for distinct edges e and e') are mathematically distinct, DigraphAllSimpleCircuits considers them to be the same.

With this approach, a directed circuit of length n can be determined by a list of its first n vertices. Thus a simple circuit $(v_1,e_1,v_2,e_2,\ldots,e_{n-1},v_n,e_{n+1},v_1)$ can be represented as the list $[v_1,\ldots,v_n]$, or any cyclic permutation thereof. For each simple circuit of *digraph*, DigraphAllSimpleCircuits(*digraph*) includes precisely one such list to represent the circuit.

Example

```
gap> gr := Digraph([[], [3], [2, 4], [5, 4], [4]]);
<digraph with 5 vertices, 6 edges>
gap> DigraphAllSimpleCircuits(gr);
[ [ 4 ], [ 4, 5 ], [ 2, 3 ] ]
gap> gr := ChainDigraph(10);;
gap> DigraphAllSimpleCircuits(gr);
[ ]
gap> gr := Digraph([[3], [1], [1]]);
<digraph with 3 vertices, 3 edges>
gap> DigraphAllSimpleCircuits(gr);
[ [ 1, 3 ] ]
```

```
gap> gr := Digraph([[1, 1]]);
<multidigraph with 1 vertex, 2 edges>
gap> DigraphAllSimpleCircuits(gr);
[ [ 1 ] ]
```

5.3.21 DigraphLongestSimpleCircuit

▷ DigraphLongestSimpleCircuit(*digraph*) (attribute)

Returns: A list of vertices, or fail.

If *digraph* is a digraph, then DigraphLongestSimpleCircuit returns the longest *simple circuit* in *digraph*. See section 1.1.1 for the definition of simple circuit, and the definition of length for a simple circuit.

This attribute computes DigraphAllSimpleCircuits(*digraph*) to find all the simple circuits of *digraph*, and returns one of maximal length. A simple circuit is represented as a list of vertices, in the same way as described in DigraphAllSimpleCircuits (5.3.20).

If *digraph* has no simple circuits, then this attribute returns fail. If *digraph* has multiple simple circuits of maximal length, then this attribute returns one of them.

Example

```
gap> gr := Digraph([[], [3], [2, 4], [5, 4], [4]]);;
gap> DigraphLongestSimpleCircuit(gr);
[ 4, 5 ]
gap> gr := ChainDigraph(10);;
gap> DigraphLongestSimpleCircuit(gr);
fail
gap> gr := Digraph([[3], [1], [1, 4], [1, 1]]);;
gap> DigraphLongestSimpleCircuit(gr);
[ 1, 3, 4 ]
```

5.3.22 DigraphLayers

▷ DigraphLayers(*digraph, vertex*) (operation)

Returns: A list.

This operation returns a list list such that list[i] is the list of vertices whose minimum distance from the vertex *vertex* in *digraph* is i - 1. Vertex *vertex* is assumed to be at distance 0 from itself.

Example

```
gap> gr := CompleteDigraph(4);;
gap> DigraphLayers(gr, 1);
[ [ 1 ], [ 2, 3, 4 ] ]
```

5.3.23 DigraphDegeneracy

▷ DigraphDegeneracy(*digraph*) (attribute)

Returns: A non-negative integer, or fail.

If *digraph* is a symmetric digraph without multiple edges - see IsSymmetricDigraph (6.1.10) and IsMultiDigraph (6.1.8) - then this attribute returns the degeneracy of *digraph*.

The degeneracy of a digraph is the least integer k such that every induced of *digraph* contains a vertex whose number of neighbours (excluding itself) is at most k. Note that this means that loops are ignored.

If *digraph* is not symmetric or has multiple edges then this attribute returns fail.

Example

```
gap> gr := DigraphSymmetricClosure(ChainDigraph(5));;
gap> DigraphDegeneracy(gr);
1
gap> gr := CompleteDigraph(5);;
gap> DigraphDegeneracy(gr);
4
gap> gr := Digraph([[1], [2, 4, 5], [3, 4], [2, 3, 4], [2], []]);
<digraph with 6 vertices, 10 edges>
gap> DigraphDegeneracy(gr);
1
```

5.3.24 DigraphDegeneracyOrdering

▷ DigraphDegeneracyOrdering(*digraph*) (attribute)

Returns: A list of integers, or fail.

If *digraph* is a digraph for which DigraphDegeneracy(*digraph*) is a non-negative integer k - see DigraphDegeneracy (5.3.23) - then this attribute returns a degeneracy ordering of the vertices of the vertices of *digraph*.

A degeneracy ordering of *digraph* is a list ordering of the vertices of *digraph* ordered such that for any position i of the list, the vertex ordering[i] has at most k neighbours in later position of the list.

If DigraphDegeneracy(*digraph*) returns fail, then this attribute returns fail.

Example

```
gap> gr := DigraphSymmetricClosure(ChainDigraph(5));;
gap> DigraphDegeneracyOrdering(gr);
[ 5, 4, 3, 2, 1 ]
gap> gr := CompleteDigraph(5);;
gap> DigraphDegeneracyOrdering(gr);
[ 5, 4, 3, 2, 1 ]
gap> gr := Digraph([[1], [2, 4, 5], [3, 4], [2, 3, 4], [2], []]);
<digraph with 6 vertices, 10 edges>
gap> DigraphDegeneracyOrdering(gr);
[ 1, 6, 5, 2, 4, 3 ]
```

5.3.25 HamiltonianPath

▷ HamiltonianPath(*digraph*) (attribute)

Returns: A list or fail.

Returns a Hamiltonian path if one exists, fail if not.

A *Hamiltonian path* of a digraph with n vertices is directed cycle of length n. If *digraph* is a digraph that contains a Hamiltonian path, then this function returns one, described in the form used by DigraphAllSimpleCircuits (5.3.20). Note if *digraph* has 0 or 1 vertices, then HamiltonianPath returns [] or [1], respectively.

The method used in this attribute has the same worst case complexity as DigraphMonomorphism (7.3.4).

Example

```
gap> g := Digraph([[]]);
<digraph with 1 vertex, 0 edges>
gap> HamiltonianPath(g);
[ 1 ]
gap> g := Digraph([[2], [1]]);
<digraph with 2 vertices, 2 edges>
gap> HamiltonianPath(g);
[ 1, 2 ]
gap> g := Digraph([[3], [], [2]]);
<digraph with 3 vertices, 2 edges>
gap> HamiltonianPath(g);
fail
gap> g := Digraph([[2], [3], [1]]);
<digraph with 3 vertices, 3 edges>
gap> HamiltonianPath(g);
[ 1, 2, 3 ]
```

5.4 Cayley graphs of groups

5.4.1 GroupOfCayleyDigraph

▷ GroupOfCayleyDigraph(*digraph*) (attribute)

▷ SemigroupOfCayleyDigraph(*digraph*) (attribute)

Returns: A group or semigroup.

If *digraph* is a Cayley graph of a group G and *digraph* belongs to the category IsCayleyDigraph (3.1.2), then GroupOfCayleyDigraph returns G.

If *digraph* is a Cayley graph of a semigroup S and *digraph* belongs to the category IsCayleyDigraph (3.1.2), then SemigroupOfCayleyDigraph returns S.

See also GeneratorsOfCayleyDigraph (5.4.2).

Example

```
gap> G := DihedralGroup(IsPermGroup, 8);
Group([ (1,2,3,4), (2,4) ])
gap> digraph := CayleyDigraph(G);
<digraph with 8 vertices, 16 edges>
gap> GroupOfCayleyDigraph(digraph) = G;
true
```

5.4.2 GeneratorsOfCayleyDigraph

▷ GeneratorsOfCayleyDigraph(*digraph*) (attribute)

Returns: A list of generators.

If *digraph* is a Cayley graph of a group or semigroup with respect to a set of generators gens and *digraph* belongs to the category IsCayleyDigraph (3.1.2), then GeneratorsOfCayleyDigraph return the list of generators gens over which *digraph* is defined.

See also GroupOfCayleyDigraph (5.4.1) or SemigroupOfCayleyDigraph (5.4.1).

Example

```
gap> G := DihedralGroup(IsPermGroup, 8);
Group([ (1,2,3,4), (2,4) ])
gap> digraph := CayleyDigraph(G);
<digraph with 8 vertices, 16 edges>
gap> GeneratorsOfCayleyDigraph(digraph) = GeneratorsOfGroup(G);
true
gap> digraph := CayleyDigraph(G, [()]);
<digraph with 8 vertices, 8 edges>
gap> GeneratorsOfCayleyDigraph(digraph) = [()];
true
```

5.5 Associated semigroups

5.5.1 AsSemigroup

▷ AsSemigroup(*filt*, *digraph*) (operation)

▷ AsMonoid(*filt*, *digraph*) (operation)

Returns: A semilattice of partial perms.

The operation AsSemigroup requires that *filt* be equal to IsPartialPermSemigroup (**Reference: IsPartialPermSemigroup**). If *digraph* is a IsJoinSemilatticeDigraph (6.1.15) or IsLatticeDigraph (6.1.15) then AsSemigroup returns a semigroup of partial perms which is isomorphic to the semigroup whose elements are the vertices of *digraph* with the binary operation PartialOrderDigraphJoinOfVertices (5.2.15). If *digraph* satisfies IsMeetSemilatticeDigraph (6.1.15) but not IsJoinSemilatticeDigraph (6.1.15) then AsSemigroup returns a semigroup of partial perms which is isomorphic to the semigroup whose elements are the vertices of *digraph* with the binary operation PartialOrderDigraphMeetOfVertices (5.2.15).

The operation AsMonoid behaves similarly to AsSemigroup except that *filt* may also be equal to IsPartialPermMonoid (**Reference: IsPartialPermMonoid**), *digraph* must satisfy IsLatticeDigraph (6.1.15), and the output satisfies IsMonoid (**Reference: IsMonoid**).

The output of both of these operations is guaranteed to be of minimal degree (see DegreeOfPartialPermSemigroup (**Reference: DegreeOfPartialPermSemigroup**)). Furthermore the GeneratorsOfSemigroup (**Reference: GeneratorsOfSemigroup**) of the output is guaranteed to be the unique generating set of minimal size.

Example

```
gap> di := Digraph([[1], [1, 2], [1, 3], [1, 4], [1, 2, 3, 5]]);
<digraph with 5 vertices, 11 edges>
gap> S := AsSemigroup(IsPartialPermSemigroup, di);
<partial perm semigroup of rank 3 with 4 generators>
gap> ForAll(Elements(S), IsIdempotent);
true
gap> IsInverseSemigroup(S);
true
gap> Size(S);
5
gap> di := Digraph([[1], [1, 2], [1, 2, 3]]);
<digraph with 3 vertices, 6 edges>
gap> M := AsMonoid(IsPartialPermMonoid, di);
```

```
<partial perm monoid of rank 2 with 3 generators>
gap> Size(M);
3
```

5.6 Planarity

5.6.1 KuratowskiPlanarSubdigraph

▷ KuratowskiPlanarSubdigraph(*digraph*) (attribute)

Returns: A list or fail.

KuratowskiPlanarSubdigraph returns the list of out-neighbours of a (not necessarily induced) subdigraph of the digraph *digraph* that witnesses the fact that *digraph* is not planar, or fail if *digraph* is planar. In other words, KuratowskiPlanarSubdigraph returns the out-neighbours of a subdigraph of *digraph* that is homeomorphic to the complete graph with 5 vertices, or to the complete bipartite graph with vertex sets of sizes 3 and 3.

The directions and multiplicities of any edges in *digraph* are ignored when considering whether or not *digraph* is planar.

See also IsPlanarDigraph (6.4.1) and SubdigraphHomeomorphicToK33 (5.6.5).

This method uses the reference implementation in edge-addition-planarity-suite by John Boyer of the algorithms described in [BM06].

Example

```
gap> D := Digraph([[3, 5, 10], [8, 9, 10], [1, 4], [3, 6],
> [1, 7, 11], [4, 7], [6, 8], [2, 7], [2, 11], [1, 2], [5, 9]]);
<digraph with 11 vertices, 25 edges>
gap> KuratowskiPlanarSubdigraph(D);
fail
gap> D := Digraph([[2, 4, 7, 9, 10], [1, 3, 4, 6, 9, 10], [6, 10],
> [2, 5, 8, 9], [1, 2, 3, 4, 6, 7, 9, 10], [3, 4, 5, 7, 9, 10],
> [3, 4, 5, 6, 9, 10], [3, 4, 5, 7, 9], [2, 3, 5, 6, 7, 8], [3, 5]]);
<digraph with 10 vertices, 50 edges>
gap> IsPlanarDigraph(D);
false
gap> KuratowskiPlanarSubdigraph(D);
[ [ 2, 9, 7 ], [ 3 ], [ 6 ], [ 5, 9 ], [ 6 ], [  ], [ 4 ],
  [ 7, 9, 3 ], [  ], [  ] ]
```

5.6.2 KuratowskiOuterPlanarSubdigraph

▷ KuratowskiOuterPlanarSubdigraph(*digraph*) (attribute)

Returns: A list or fail.

KuratowskiOuterPlanarSubdigraph returns the list of out-neighbours of a (not necessarily induced) subdigraph of the digraph *digraph* that witnesses the fact that *digraph* is not outer planar, or fail if *digraph* is outer planar. In other words, KuratowskiOuterPlanarSubdigraph returns the out-neighbours of a subdigraph of *digraph* that is homeomorphic to the complete graph with 4 vertices, or to the complete bipartite graph with vertex sets of sizes 2 and 3.

The directions and multiplicities of any edges in *digraph* are ignored when considering whether or not *digraph* is outer planar.

See also IsOuterPlanarDigraph (6.4.2), SubdigraphHomeomorphicToK4 (5.6.5), and SubdigraphHomeomorphicToK23 (5.6.5).

This method uses the reference implementation in edge-addition-planarity-suite by John Boyer of the algorithms described in [BM06].

Example

```
gap> D := Digraph([[3, 5, 10], [8, 9, 10], [1, 4], [3, 6],
> [1, 7, 11], [4, 7], [6, 8], [2, 7], [2, 11], [1, 2], [5, 9]]);
<digraph with 11 vertices, 25 edges>
gap> KuratowskiOuterPlanarSubdigraph(D);
[ [ 3, 5, 10 ], [ 9, 8, 10 ], [ 4 ], [ 6 ], [ 11 ], [ 7 ], [ 8 ],
  [  ], [ 11 ], [  ], [  ] ]
gap> D := Digraph([[2, 4, 7, 9, 10], [1, 3, 4, 6, 9, 10], [6, 10],
> [2, 5, 8, 9], [1, 2, 3, 4, 6, 7, 9, 10], [3, 4, 5, 7, 9, 10],
> [3, 4, 5, 6, 9, 10], [3, 4, 5, 7, 9], [2, 3, 5, 6, 7, 8], [3, 5]]);
<digraph with 10 vertices, 50 edges>
gap> IsOuterPlanarDigraph(D);
false
gap> KuratowskiOuterPlanarSubdigraph(D);
[ [  ], [  ], [  ], [ 8, 9 ], [  ], [  ], [ 9, 4 ], [ 7, 9 ], [  ],
  [  ] ]
```

5.6.3 PlanarEmbedding

▷ PlanarEmbedding(*digraph*) (attribute)

Returns: A list or fail.

If *digraph* is a planar digraph, then PlanarEmbedding returns the list of out-neighbours of a subdigraph of *digraph* such that each vertex's neighbours are given in clockwise order. If *digraph* is not planar, then fail is returned.

The directions and multiplicities of any edges in *digraph* are ignored by PlanarEmbedding.

See also IsPlanarDigraph (6.4.1).

This method uses the reference implementation in edge-addition-planarity-suite by John Boyer of the algorithms described in [BM06].

Example

```
gap> D := Digraph([[3, 5, 10], [8, 9, 10], [1, 4], [3, 6],
> [1, 7, 11], [4, 7], [6, 8], [2, 7], [2, 11], [1, 2], [5, 9]]);
<digraph with 11 vertices, 25 edges>
gap> PlanarEmbedding(D);
[ [ 3, 10, 5 ], [ 10, 8, 9 ], [ 4 ], [ 6 ], [ 11, 7 ], [ 7 ], [ 8 ],
  [  ], [ 11 ], [  ], [  ] ]
gap> D := Digraph([[2, 4, 7, 9, 10], [1, 3, 4, 6, 9, 10], [6, 10],
> [2, 5, 8, 9], [1, 2, 3, 4, 6, 7, 9, 10], [3, 4, 5, 7, 9, 10],
> [3, 4, 5, 6, 9, 10], [3, 4, 5, 7, 9], [2, 3, 5, 6, 7, 8], [3, 5]]);
<digraph with 10 vertices, 50 edges>
gap> PlanarEmbedding(D);
fail
```

5.6.4 OuterPlanarEmbedding

▷ OuterPlanarEmbedding(*digraph*) (attribute)

Returns: A list or fail.

If *digraph* is an outer planar digraph, then OuterPlanarEmbedding returns the list of out-neighbours of a subdigraph of *digraph* such that each vertex's neighbours are given in clockwise order. If *digraph* is not outer planar, then fail is returned.

The directions and multiplicities of any edges in *digraph* are ignored by OuterPlanarEmbedding.

See also IsOuterPlanarDigraph (6.4.2).

This method uses the reference implementation in edge-addition-planarity-suite by John Boyer of the algorithms described in [BM06].

Example

```
gap> D := Digraph([[3, 5, 10], [8, 9, 10], [1, 4], [3, 6],
> [1, 7, 11], [4, 7], [6, 8], [2, 7], [2, 11], [1, 2], [5, 9]]);
<digraph with 11 vertices, 25 edges>
gap> OuterPlanarEmbedding(D);
fail
gap> D := Digraph([[2, 4, 7, 9, 10], [1, 3, 4, 6, 9, 10], [6, 10],
> [2, 5, 8, 9], [1, 2, 3, 4, 6, 7, 9, 10], [3, 4, 5, 7, 9, 10],
> [3, 4, 5, 6, 9, 10], [3, 4, 5, 7, 9], [2, 3, 5, 6, 7, 8], [3, 5]]);
<digraph with 10 vertices, 50 edges>
gap> OuterPlanarEmbedding(D);
fail
gap> OuterPlanarEmbedding(CompleteBipartiteDigraph(2, 2));
[ [ 3, 4 ], [ 4, 3 ], [  ], [  ] ]
```

5.6.5 SubdigraphHomeomorphicToK23

▷ SubdigraphHomeomorphicToK23(*digraph*) (attribute)

▷ SubdigraphHomeomorphicToK33(*digraph*) (attribute)

▷ SubdigraphHomeomorphicToK4(*digraph*) (attribute)

Returns: A list or fail.

These attributes return the list of out-neighbours of a subdigraph of the digraph *digraph* which is homeomorphic to one of the following: the complete bipartite graph with vertex sets of sizes 2 and 3; the complete bipartite graph with vertex sets of sizes 3 and 3; or the complete graph with 4 vertices. If *digraph* has no such subdigraphs, then fail is returned.

See also IsPlanarDigraph (6.4.1) and IsOuterPlanarDigraph (6.4.2) for more details.

This method uses the reference implementation in edge-addition-planarity-suite by John Boyer of the algorithms described in [BM06].

Example

```
gap> D := Digraph([[3, 5, 10], [8, 9, 10], [1, 4], [3, 6], [1, 7, 11],
> [4, 7], [6, 8], [2, 7], [2, 11], [1, 2], [5, 9]]);
<digraph with 11 vertices, 25 edges>
gap> SubdigraphHomeomorphicToK4(D);
[ [ 3, 5, 10 ], [ 9, 8, 10 ], [ 4 ], [ 6 ], [ 7, 11 ], [ 7 ], [ 8 ],
  [  ], [ 11 ], [  ], [  ] ]
gap> SubdigraphHomeomorphicToK23(D);
[ [ 3, 5, 10 ], [ 9, 8, 10 ], [ 4 ], [ 6 ], [ 11 ], [ 7 ], [ 8 ],
  [  ], [ 11 ], [  ], [  ] ]
gap> D := Digraph([[3, 5, 10], [8, 9, 10], [1, 4], [3, 6], [1, 11],
>  [4, 7], [6, 8], [2, 7], [2, 11], [1, 2], [5, 9]]);
<digraph with 11 vertices, 24 edges>
gap> SubdigraphHomeomorphicToK4(D);
```

```
fail
gap> SubdigraphHomeomorphicToK23(D);
[ [ 3, 10, 5 ], [ 10, 8, 9 ], [ 4 ], [ 6 ], [ 11 ], [ 7 ], [ 8 ],
  [  ], [ 11 ], [  ], [  ] ]
gap> SubdigraphHomeomorphicToK33(D);
fail
gap> SubdigraphHomeomorphicToK23(NullDigraph(0));
fail
gap> SubdigraphHomeomorphicToK33(CompleteDigraph(5));
fail
gap> SubdigraphHomeomorphicToK33(CompleteBipartiteDigraph(3, 3));
[ [ 4, 6, 5 ], [ 4, 5, 6 ], [ 6, 5, 4 ], [  ], [  ], [  ] ]
gap> SubdigraphHomeomorphicToK4(CompleteDigraph(3));
fail
```

Chapter 6

Properties of digraphs

6.1 Edge properties

6.1.1 DigraphHasLoops

▷ `DigraphHasLoops(`*`digraph`*`)` (property)

Returns: `true` or `false`.

Returns `true` if the digraph *`digraph`* has loops, and `false` if it does not. A loop is an edge with equal source and range.

Example

```
gap> gr := Digraph([[1, 2], [2]]);
<digraph with 2 vertices, 3 edges>
gap> DigraphEdges(gr);
[ [ 1, 1 ], [ 1, 2 ], [ 2, 2 ] ]
gap> DigraphHasLoops(gr);
true
gap> gr := Digraph([[2, 3], [1], [2]]);
<digraph with 3 vertices, 4 edges>
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 1, 3 ], [ 2, 1 ], [ 3, 2 ] ]
gap> DigraphHasLoops(gr);
false
```

6.1.2 IsAntisymmetricDigraph

▷ `IsAntisymmetricDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

This property is `true` if the digraph *`digraph`* is antisymmetric, and `false` if it is not.

A digraph is *antisymmetric* if whenever there is an edge with source `u` and range `v`, and an edge with source `v` and range `u`, then the vertices `u` and `v` are equal.

Example

```
gap> gr1 := Digraph([[2], [1, 3], [2, 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsAntisymmetricDigraph(gr1);
false
gap> DigraphEdges(gr1){[1, 2]};
[ [ 1, 2 ], [ 2, 1 ] ]
```

```
gap> gr2 := Digraph([[1, 2], [3, 3], [1]]);
<multidigraph with 3 vertices, 5 edges>
gap> IsAntisymmetricDigraph(gr2);
true
gap> DigraphEdges(gr2);
[ [ 1, 1 ], [ 1, 2 ], [ 2, 3 ], [ 2, 3 ], [ 3, 1 ] ]
```

6.1.3 IsBipartiteDigraph

▷ IsBipartiteDigraph(*digraph*) (property)

Returns: true or false.

This property is true if the digraph *digraph* is bipartite, and false if it is not. A digraph is bipartite if and only if the vertices of *digraph* can be partitioned into two non-empty sets such that the source and range of any edge of *digraph* lie in distinct sets. Equivalently, a digraph is bipartite if and only if it is 2-colorable; see DigraphGreedyColouring (7.3.14).

See also DigraphBicomponents (5.3.12).

Example

```
gap> gr := ChainDigraph(4);
<digraph with 4 vertices, 3 edges>
gap> IsBipartiteDigraph(gr);
true
gap> gr := CycleDigraph(3);
<digraph with 3 vertices, 3 edges>
gap> IsBipartiteDigraph(gr);
false
```

6.1.4 IsCompleteBipartiteDigraph

▷ IsCompleteBipartiteDigraph(*digraph*) (property)

Returns: true or false.

Returns true if the digraph *digraph* is a complete bipartite digraph, and false if it is not.

A digraph is a *complete bipartite digraph* if it is bipartite, see IsBipartiteDigraph (6.1.3), and there exists a unique edge with source i and range j if and only if i and j lie in different bicomponents of *digraph*, see DigraphBicomponents (5.3.12).

Equivalently, a bipartite digraph with bicomponents of size m and n is complete precisely when it has $2mn$ edges, none of which are multiple edges.

See also CompleteBipartiteDigraph (3.5.3).

Example

```
gap> gr := CycleDigraph(2);
<digraph with 2 vertices, 2 edges>
gap> IsCompleteBipartiteDigraph(gr);
true
gap> gr := CycleDigraph(4);
<digraph with 4 vertices, 4 edges>
gap> IsBipartiteDigraph(gr);
true
gap> IsCompleteBipartiteDigraph(gr);
false
```

6.1.5 IsCompleteDigraph

▷ IsCompleteDigraph(*digraph*) (property)

Returns: true or false.

Returns true if the digraph *digraph* is complete, and false if it is not.

A digraph is *complete* if it has no loops, and for all *distinct* vertices i and j, there is exactly one edge with source i and range j. Equivalently, a digraph with n vertices is complete precisely when it has $n(n-1)$ edges, no loops, and no multiple edges.

Example

```
gap> gr := Digraph([[2, 3], [1, 3], [1, 2]]);
<digraph with 3 vertices, 6 edges>
gap> IsCompleteDigraph(gr);
true
gap> gr := Digraph([[2, 2], [1]]);
<multidigraph with 2 vertices, 3 edges>
gap> IsCompleteDigraph(gr);
false
```

6.1.6 IsEmptyDigraph

▷ IsEmptyDigraph(*digraph*) (property)

▷ IsNullDigraph(*digraph*) (property)

Returns: true or false.

Returns true if the digraph *digraph* is empty, and false if it is not. A digraph is *empty* if it has no edges.

IsNullDigraph is a synonym for IsEmptyDigraph.

Example

```
gap> gr := Digraph([[], []]);
<digraph with 2 vertices, 0 edges>
gap> IsEmptyDigraph(gr);
true
gap> IsNullDigraph(gr);
true
gap> gr := Digraph([[], [1]]);
<digraph with 2 vertices, 1 edge>
gap> IsEmptyDigraph(gr);
false
gap> IsNullDigraph(gr);
false
```

6.1.7 IsFunctionalDigraph

▷ IsFunctionalDigraph(*digraph*) (property)

Returns: true or false.

This property is true if the digraph *digraph* is functional.

A digraph is *functional* if every vertex is the source of a unique edge.

Example

```
gap> gr1 := Digraph([[3], [2], [2], [1], [6], [5]]);
<digraph with 6 vertices, 6 edges>
gap> IsFunctionalDigraph(gr1);
```

```
true
gap> gr2 := Digraph([[1, 2], [1]]);
<digraph with 2 vertices, 3 edges>
gap> IsFunctionalDigraph(gr2);
false
gap> gr3 := Digraph(3, [1, 2, 3], [2, 3, 1]);
<digraph with 3 vertices, 3 edges>
gap> IsFunctionalDigraph(gr3);
true
```

6.1.8 IsMultiDigraph

▷ IsMultiDigraph(*digraph*) (property)

Returns: true or false.

A *multidigraph* is one that has at least two edges with equal source and range.

Example

```
gap> gr := Digraph(["a", "b", "c"], ["a", "b", "b"], ["b", "c", "a"]);
<digraph with 3 vertices, 3 edges>
gap> IsMultiDigraph(gr);
false
gap> gr := DigraphFromDigraph6String("&Bug");
<digraph with 3 vertices, 6 edges>
gap> IsDuplicateFree(DigraphEdges(gr));
true
gap> IsMultiDigraph(gr);
false
gap> gr := Digraph([[1, 2, 3, 2], [2, 1], [3]]);
<multidigraph with 3 vertices, 7 edges>
gap> IsDuplicateFree(DigraphEdges(gr));
false
gap> IsMultiDigraph(gr);
true
```

6.1.9 IsReflexiveDigraph

▷ IsReflexiveDigraph(*digraph*) (property)

Returns: true or false.

This property is true if the digraph *digraph* is reflexive, and false if it is not. A digraph is *reflexive* if it has a loop at every vertex.

Example

```
gap> gr := Digraph([[1, 2], [2]]);
<digraph with 2 vertices, 3 edges>
gap> IsReflexiveDigraph(gr);
true
gap> gr := Digraph([[3, 1], [4, 2], [3], [2, 1]]);
<digraph with 4 vertices, 7 edges>
gap> IsReflexiveDigraph(gr);
false
```

6.1.10 IsSymmetricDigraph

▷ IsSymmetricDigraph(*digraph*) (property)

Returns: true or false.

This property is true if the digraph *digraph* is symmetric, and false if it is not.

A *symmetric digraph* is one where for each non-loop edge, having source u and range v, there is a corresponding edge with source v and range u. If there are n edges with source u and range v, then there must be precisely n edges with source v and range u. In other words, a symmetric digraph has a symmetric adjacency matrix AdjacencyMatrix (5.2.1).

Example

```
gap> gr1 := Digraph([[2], [1, 3], [2, 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsSymmetricDigraph(gr1);
true
gap> adj1 := AdjacencyMatrix(gr1);;
gap> Display(adj1);
[ [  0,  1,  0 ],
  [  1,  0,  1 ],
  [  0,  1,  1 ] ]
gap> adj1 = TransposedMat(adj1);
true
gap> gr1 = DigraphReverse(gr1);
true
gap> gr2 := Digraph([[2, 3], [1, 3], [2, 3]]);
<digraph with 3 vertices, 6 edges>
gap> IsSymmetricDigraph(gr2);
false
gap> adj2 := AdjacencyMatrix(gr2);;
gap> Display(adj2);
[ [  0,  1,  1 ],
  [  1,  0,  1 ],
  [  0,  1,  1 ] ]
gap> adj2 = TransposedMat(adj2);
false
```

6.1.11 IsTournament

▷ IsTournament(*digraph*) (property)

Returns: true or false.

This property is true if the digraph *digraph* is a tournament, and false if it is not.

A tournament is an orientation of a complete (undirected) graph. Specifically, a tournament is a digraph which has a unique directed edge (of some orientation) between any pair of distinct vertices, and no loops.

Example

```
gap> gr := Digraph([[2, 3, 4], [3, 4], [4], []]);
<digraph with 4 vertices, 6 edges>
gap> IsTournament(gr);
true
gap> gr := Digraph([[2], [1], [3]]);
<digraph with 3 vertices, 3 edges>
```

```
gap> IsTournament(gr);
false
```

6.1.12 IsTransitiveDigraph

▷ `IsTransitiveDigraph(`*digraph*`)` (property)

Returns: `true` or `false`.

This property is `true` if the digraph *digraph* is transitive, and `false` if it is not. A digraph is *transitive* if whenever `[ i, j ]` and `[ j, k ]` are edges of the digraph, then `[ i, k ]` is also an edge of the digraph.

Let n be the number of vertices of an arbitrary digraph, and let m be the number of edges. For general digraphs, the methods used for this property use a version of the Floyd-Warshall algorithm, and have complexity $O(n^3)$. However for digraphs which are topologically sortable [`DigraphTopologicalSort` (5.1.7)], then methods with complexity $O(m+n+m\cdot n)$ will be used when appropriate.

Example

```
gap> gr := Digraph([[1, 2], [3], [3]]);
<digraph with 3 vertices, 4 edges>
gap> IsTransitiveDigraph(gr);
false
gap> gr2 := Digraph([[1, 2, 3], [3], [3]]);
<digraph with 3 vertices, 5 edges>
gap> IsTransitiveDigraph(gr2);
true
gap> gr2 = DigraphTransitiveClosure(gr);
true
gap> gr3 := Digraph([[1, 2, 2, 3], [3, 3], [3]]);
<multidigraph with 3 vertices, 7 edges>
gap> IsTransitiveDigraph(gr3);
true
```

6.1.13 IsPreorderDigraph

▷ `IsPreorderDigraph(`*digraph*`)` (property)

▷ `IsQuasiorderDigraph(`*digraph*`)` (property)

Returns: `true` or `false`.

A digraph is a preorder digraph if and only if the digraph satisifies both `IsReflexiveDigraph` (6.1.9) and `IsTransitiveDigraph` (6.1.12). A preorder digraph (or quasiorder digraph) *digraph* corresponds to the preorder relation $\leq$ defined by $x \leq y$ if and only if `[x, y]` is an edge of *digraph*.

Example

```
gap> gr := Digraph([[1], [2, 3], [2, 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsPreorderDigraph(gr);
true
gap> gr := Digraph([[1 .. 4], [1 .. 4], [1 .. 4], [1 .. 4]]);
<digraph with 4 vertices, 16 edges>
gap> IsPreorderDigraph(gr);
true
gap> gr := Digraph([[2], [3], [4], [5], [1]]);
```

```
<digraph with 5 vertices, 5 edges>
gap> IsPreorderDigraph(gr);
false
gap> gr := Digraph([[1], [1, 2], [2, 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsPreorderDigraph(gr);
false
```

6.1.14 IsPartialOrderDigraph

▷ `IsPartialOrderDigraph(`*digraph*`)` (property)

Returns: `true` or `false`.

A digraph is a partial order digraph if and only if the digraph satisifies all of `IsReflexiveDigraph` (6.1.9), `IsAntisymmetricDigraph` (6.1.2) and `IsTransitiveDigraph` (6.1.12). A partial order *digraph* corresponds to the partial order relation $\leq$ defined by $x \leq y$ if and only if `[x, y]` is an edge of *digraph*.

Example

```
gap> gr := Digraph([[1, 3], [2, 3], [3]]);
<digraph with 3 vertices, 5 edges>
gap> IsPartialOrderDigraph(gr);
true
gap> gr := CycleDigraph(5);
<digraph with 5 vertices, 5 edges>
gap> IsPartialOrderDigraph(gr);
false
gap> gr := Digraph([[1, 1], [1, 1, 2], [3], [3, 3, 4, 4]]);
<multidigraph with 4 vertices, 10 edges>
gap> IsPartialOrderDigraph(gr);
true
```

6.1.15 IsMeetSemilatticeDigraph

▷ `IsMeetSemilatticeDigraph(`*digraph*`)` (property)
▷ `IsJoinSemilatticeDigraph(`*digraph*`)` (property)
▷ `IsLatticeDigraph(`*digraph*`)` (property)

Returns: `true` or `false`.

`IsMeetSemilatticeDigraph` returns `true` if the digraph *digraph* is a meet semilattice; `IsJoinSemilatticeDigraph` returns `true` if the digraph *digraph* is a join semilattice; and `IsLatticeDigraph` returns `true` if the digraph *digraph* is both a meet and a join semilattice.

For a partial order digraph `IsPartialOrderDigraph` (6.1.14) the corresponding partial order is the relation $\leq$, defined by $x \leq y$ if and only if `[x, y]` is an edge. A digraph is a *meet semilattice* if it is a partial order and every pair of vertices has a greatest lower bound (meet) with respect to the aforementioned relation. A *join semilattice* is a partial order where every pair of vertices has a least upper bound (join) with respect to the relation.

Example

```
gap> gr := Digraph([[1, 3], [2, 3], [3]]);
<digraph with 3 vertices, 5 edges>
gap> IsMeetSemilatticeDigraph(gr);
false
```

```
gap> IsJoinSemilatticeDigraph(gr);
true
gap> IsLatticeDigraph(gr);
false
gap> gr := Digraph([[1], [2], [1 .. 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsJoinSemilatticeDigraph(gr);
false
gap> IsMeetSemilatticeDigraph(gr);
true
gap> IsLatticeDigraph(gr);
false
gap> gr := Digraph([[1 .. 4], [2, 4], [3, 4], [4]]);
<digraph with 4 vertices, 9 edges>
gap> IsMeetSemilatticeDigraph(gr);
true
gap> IsJoinSemilatticeDigraph(gr);
true
gap> IsLatticeDigraph(gr);
true
gap> gr := Digraph([[1, 1, 1], [1, 1, 2, 2],
>                   [1, 3, 3], [1, 2, 3, 3, 4]]);
<multidigraph with 4 vertices, 15 edges>
gap> IsMeetSemilatticeDigraph(gr);
true
gap> IsJoinSemilatticeDigraph(gr);
true
gap> IsLatticeDigraph(gr);
true
```

6.2 Regularity

6.2.1 IsInRegularDigraph

▷ IsInRegularDigraph(*digraph*) (property)

Returns: true or false.

This property is true if there is an integer n such that for every vertex v of digraph *digraph* there are exactly n edges terminating in v. See also IsOutRegularDigraph (6.2.2) and IsRegularDigraph (6.2.3).

Example

```
gap> IsInRegularDigraph(CompleteDigraph(4));
true
gap> IsInRegularDigraph(ChainDigraph(4));
false
```

6.2.2 IsOutRegularDigraph

▷ IsOutRegularDigraph(*digraph*) (property)

Returns: true or false.

This property is true if there is an integer n such that for every vertex v of digraph *digraph* there are exactly n edges starting at v. See also IsInRegularDigraph (6.2.1) and IsRegularDigraph (6.2.3).

Example

```
gap> IsOutRegularDigraph(CompleteDigraph(4));
true
gap> IsOutRegularDigraph(ChainDigraph(4));
false
```

6.2.3 IsRegularDigraph

▷ IsRegularDigraph(*digraph*) (property)

Returns: true or false.

This property is true if there is an integer n such that for every vertex v of digraph *digraph* there are exactly n edges starting and terminating at v. In other words, the property is true if *digraph* is both in-regular and and out-regular. See also IsInRegularDigraph (6.2.1) and IsOutRegularDigraph (6.2.2).

Example

```
gap> IsRegularDigraph(CompleteDigraph(4));
true
gap> IsRegularDigraph(ChainDigraph(4));
false
```

6.2.4 IsDistanceRegularDigraph

▷ IsDistanceRegularDigraph(*digraph*) (property)

Returns: true or false.

If *digraph* is a connected symmetric graph, this property returns true if for any two vertices u and v of *digraph* and any two integers i and j between 0 and the diameter of *digraph*, the number of vertices at distance i from u and distance j from v depends only on i, j, and the distance between vertices u and v.

Alternatively, a distance regular graph is a graph for which there exist integers b_i, c_i, and i such that for any two vertices u, v in *digraph* which are distance i apart, there are exactly b_i neighbors of v which are at distance i - 1 away from u, and c_i neighbors of v which are at distance i + 1 away from u. This definition is used to check whether *digraph* is distance regular.

In the case where *digraph* is not symmetric or not connected, the property is false.

Example

```
gap> gr := DigraphSymmetricClosure(ChainDigraph(5));;
gap> IsDistanceRegularDigraph(gr);
false
gap> gr := Digraph([[2, 3, 4], [1, 3, 4], [1, 2, 4], [1, 2, 3]]);
<digraph with 4 vertices, 12 edges>
gap> IsDistanceRegularDigraph(gr);
true
```

6.3 Connectivity and cycles

6.3.1 IsAcyclicDigraph

▷ `IsAcyclicDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

This property is `true` if the digraph *`digraph`* is acyclic, and `false` if it is not. A digraph is *acyclic* if every directed cycle on the digraph is trivial. See section 1.1.1 for the definition of a directed cycle, and of a trivial directed cycle.

The method used in this operation has complexity $O(m+n)$ where m is the number of edges (counting multiple edges as one) and n is the number of vertices in the digraph.

Example

```
gap> Petersen := Graph(SymmetricGroup(5), [[1, 2]], OnSets,
> function(x, y)
>   return IsEmpty(Intersection(x, y));
> end);;
gap> gr := Digraph(Petersen);
<digraph with 10 vertices, 30 edges>
gap> IsAcyclicDigraph(gr);
false
gap> gr := DigraphFromDiSparse6String(
> ".b_OGCIDBaPGkULEbQHCeRIdrHcuZMfRyDAbPhTi|zF");
<digraph with 35 vertices, 34 edges>
gap> IsAcyclicDigraph(gr);
true
gap> IsAcyclicDigraph(ChainDigraph(10));
true
gap> IsAcyclicDigraph(CycleDigraph(10));
false
```

6.3.2 IsChainDigraph

▷ `IsChainDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

`IsChainDigraph` returns `true` if the digraph *`digraph`* is isomorphic to the chain digraph with the same number of vertices as *`digraph`*, and `false` if it is not; see `ChainDigraph` (3.5.1).

A digraph is a *chain* if and only if it is a directed tree, in which every vertex has out degree at most one; see `IsDirectedTree` (6.3.7) and `OutDegrees` (5.2.8).

Example

```
gap> gr := Digraph([[1, 3], [2, 3], [3]]);
<digraph with 3 vertices, 5 edges>
gap> IsChainDigraph(gr);
false
gap> gr := ChainDigraph(5);
<digraph with 5 vertices, 4 edges>
gap> IsChainDigraph(gr);
true
gap> gr := DigraphReverse(gr);
<digraph with 5 vertices, 4 edges>
gap> IsChainDigraph(gr);
true
```

6.3.3 IsConnectedDigraph

▷ `IsConnectedDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

This property is `true` if the digraph *`digraph`* is weakly connected and `false` if it is not. A digraph *`digraph`* is *weakly connected* if it is possible to travel from any vertex to any other vertex by traversing edges in either direction (possibly against the orientation of some of them).

The method used in this function has complexity $O(m)$ if the digraph's `DigraphSource` (5.2.5) attribute is set, otherwise it has complexity $O(m+n)$ (where m is the number of edges and n is the number of vertices of the digraph).

Example

```
gap> gr := Digraph([[2], [3], []]);;
gap> IsConnectedDigraph(gr);
true
gap> gr := Digraph([[1, 3], [4], [3], []]);;
gap> IsConnectedDigraph(gr);
false
```

6.3.4 IsBiconnectedDigraph

▷ `IsBiconnectedDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

A connected digraph is *biconnected* if it is still connected (in the sense of `IsConnectedDigraph` (6.3.3)) when any vertex is removed. `IsBiconnectedDigraph` returns `true` if the digraph *`digraph`* is biconnected, and `false` if it is not. In particular, `IsBiconnectedDigraph` returns `false` if *`digraph`* is not connected.

Multiple edges and loops are ignored by this method.

The method used in this operation has complexity $O(m+n)$ where m is the number of edges (counting multiple edges as one, and not counting loops) and n is the number of vertices in the digraph. See also `ArticulationPoints` (5.3.13).

Example

```
gap> IsBiconnectedDigraph(Digraph([[1, 3], [2, 3], [3]]));
false
gap> IsBiconnectedDigraph(CycleDigraph(5));
true
gap> digraph := Digraph([[1, 1], [1, 1, 2], [3], [3, 3, 4, 4]]);;
gap> IsBiconnectedDigraph(digraph);
false
```

6.3.5 IsStronglyConnectedDigraph

▷ `IsStronglyConnectedDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

This property is `true` if the digraph *`digraph`* is strongly connected and `false` if it is not.

A digraph *`digraph`* is *strongly connected* if there is a directed path from every vertex to every other vertex. See section 1.1.1 for the definition of a directed path.

The method used in this operation is based on Gabow's Algorithm [Gab00] and has complexity $O(m+n)$, where m is the number of edges (counting multiple edges as one) and n is the number of vertices in the digraph.

Example

```
gap> gr := CycleDigraph(250000);
<digraph with 250000 vertices, 250000 edges>
gap> IsStronglyConnectedDigraph(gr);
true
gap> gr := DigraphRemoveEdges(gr, [[250000, 1]]);
<digraph with 250000 vertices, 249999 edges>
gap> IsStronglyConnectedDigraph(gr);
false
```

6.3.6 IsAperiodicDigraph

▷ IsAperiodicDigraph(*digraph*) (property)

Returns: true or false.

This property is true if the digraph *digraph* is aperiodic, i.e. if its DigraphPeriod (5.3.14) is equal to 1. Otherwise, the property is false.

Example

```
gap> gr := Digraph([[6], [1], [2], [3], [4, 4], [5]]);
<multidigraph with 6 vertices, 7 edges>
gap> IsAperiodicDigraph(gr);
false
gap> gr := Digraph([[2], [3, 5], [4], [5], [1, 2]]);
<digraph with 5 vertices, 7 edges>
gap> IsAperiodicDigraph(gr);
true
```

6.3.7 IsDirectedTree

▷ IsDirectedTree(*digraph*) (property)

Returns: true or false.

Returns true if the digraph *digraph* is a directed tree, and false if it is not.

A *directed tree* is an acyclic digraph with precisely 1 source, such that no two vertices share an out-neighbour. Note the empty digraph is not considered a directed tree as it has no source.

See also DigraphSources (5.1.6).

Example

```
gap> gr := Digraph([[], [2]]);
<digraph with 2 vertices, 1 edge>
gap> IsDirectedTree(gr);
false
gap> gr := Digraph([[3], [3], []]);
<digraph with 3 vertices, 2 edges>
gap> IsDirectedTree(gr);
false
gap> gr := Digraph([[2], [3], []]);
<digraph with 3 vertices, 2 edges>
gap> IsDirectedTree(gr);
true
gap> gr := Digraph([[2, 3], [6], [4, 5], [], [], []]);
<digraph with 6 vertices, 5 edges>
```

```
gap> IsDirectedTree(gr);
true
```

6.3.8 IsUndirectedTree

▷ IsUndirectedTree(*digraph*) (property)
▷ IsUndirectedForest(*digraph*) (property)

Returns: true or false.

The property IsUndirectedTree returns true if the digraph *digraph* is an undirected tree, and the property IsUndirectedForest returns true if *digraph* is an undirected forest; otherwise, these properties return false.

An *undirected tree* is a symmetric digraph without loops, in which for any pair of distinct vertices u and v, there is exactly one directed path from u to v. See IsSymmetricDigraph (6.1.10) and DigraphHasLoops (6.1.1), and see section 1.1.1 for the definition of directed path. This definition implies that an undirected tree has no multiple edges.

An *undirected forest* is a digraph, each of whose connected components is an undirected tree. In other words, an undirected forest is isomorphic to a disjoint union of undirected trees. See DigraphConnectedComponents (5.3.8) and DigraphDisjointUnion (3.3.26). In particular, every undirected tree is an undirected forest.

Please note that the digraph with zero vertices is considered to be neither an undirected tree nor an undirected forest.

Example

```
gap> gr := Digraph([[3], [3], [1, 2]]);
<digraph with 3 vertices, 4 edges>
gap> IsUndirectedTree(gr);
true
gap> IsSymmetricDigraph(gr) and not DigraphHasLoops(gr);
true
gap> gr := Digraph([[3], [5], [1, 4], [3], [2]]);
<digraph with 5 vertices, 6 edges>
gap> IsConnectedDigraph(gr);
false
gap> IsUndirectedTree(gr);
false
gap> IsUndirectedForest(gr);
true
gap> gr := Digraph([[1, 2], [1], [2]]);
<digraph with 3 vertices, 4 edges>
gap> IsUndirectedTree(gr) or IsUndirectedForest(gr);
false
gap> IsSymmetricDigraph(gr) or not DigraphHasLoops(gr);
false
```

6.3.9 IsEulerianDigraph

▷ IsEulerianDigraph(*digraph*) (property)

Returns: true or false.

This property returns true if the digraph *digraph* is Eulerian.

A digraph is called *Eulerian* if there exists a directed circuit on the digraph which includes every edge exactly once. See section 1.1.1 for the definition of a directed circuit.

Example

```
gap> gr := Digraph([[]]);
<digraph with 1 vertex, 0 edges>
gap> IsEulerianDigraph(gr);
true
gap> gr := Digraph([[2], []]);
<digraph with 2 vertices, 1 edge>
gap> IsEulerianDigraph(gr);
false
gap> gr := Digraph([[3], [], [2]]);
<digraph with 3 vertices, 2 edges>
gap> IsEulerianDigraph(gr);
false
gap> gr := Digraph([[2], [3], [1]]);
<digraph with 3 vertices, 3 edges>
gap> IsEulerianDigraph(gr);
true
```

6.3.10 IsHamiltonianDigraph

▷ `IsHamiltonianDigraph(`*digraph*`)` (property)

Returns: `true` or `false`.

If *digraph* is Hamiltonian, then this property returns `true`, and `false` if it is not.

A digraph with `n` vertices is *Hamiltonian* if it has a directed cycle of length `n`. See Section 1.1.1 for the definition of a directed cycle. Note the empty digraphs on 0 and 1 vertices are considered to be Hamiltonian.

The method used in this operation has the worst case complexity as `DigraphMonomorphism` (7.3.4).

Example

```
gap> g := Digraph([[]]);
<digraph with 1 vertex, 0 edges>
gap> IsHamiltonianDigraph(g);
true
gap> g := Digraph([[2], [1]]);
<digraph with 2 vertices, 2 edges>
gap> IsHamiltonianDigraph(g);
true
gap> g := Digraph([[3], [], [2]]);
<digraph with 3 vertices, 2 edges>
gap> IsHamiltonianDigraph(g);
false
gap> g := Digraph([[2], [3], [1]]);
<digraph with 3 vertices, 3 edges>
gap> IsHamiltonianDigraph(g);
true
```

6.3.11 IsCycleDigraph

▷ `IsCycleDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

`IsCycleDigraph` returns `true` if the digraph *`digraph`* is isomorphic to the cycle digraph with the same number of vertices as *`digraph`*, and `false` if it is not; see `CycleDigraph` (3.5.5).

A digraph is a *cycle* if and only if it is strongly connected and has the same number of edges as vertices.

Example

```
gap> gr := Digraph([[1, 3], [2, 3], [3]]);
<digraph with 3 vertices, 5 edges>
gap> IsCycleDigraph(gr);
false
gap> gr := CycleDigraph(5);
<digraph with 5 vertices, 5 edges>
gap> IsCycleDigraph(gr);
true
gap> gr := OnDigraphs(gr, (1, 2, 3));
<digraph with 5 vertices, 5 edges>
gap> gr = CycleDigraph(5);
false
gap> IsCycleDigraph(gr);
true
```

6.4 Planarity

6.4.1 IsPlanarDigraph

▷ `IsPlanarDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

A *planar* digraph is a digraph that can be embedded in the plane in such a way that its edges do not intersect. A digraph is planar if and only if it does not have a subdigraph that is homeomorphic to either the complete graph on 5 vertices or the complete bipartite graph with vertex sets of sizes 3 and 3.

`IsPlanarDigraph` returns `true` if the digraph *`digraph`* is planar and `false` if it is not. The directions and multiplicities of any edges in *`digraph`* are ignored by `IsPlanarDigraph`.

See also `IsOuterPlanarDigraph` (6.4.2).

This method uses the reference implementation in edge-addition-planarity-suite by John Boyer of the algorithms described in [BM06].

Example

```
gap> IsPlanarDigraph(CompleteDigraph(4));
true
gap> IsPlanarDigraph(CompleteDigraph(5));
false
gap> IsPlanarDigraph(CompleteBipartiteDigraph(2, 3));
true
gap> IsPlanarDigraph(CompleteBipartiteDigraph(3, 3));
false
```

6.4.2 IsOuterPlanarDigraph

▷ `IsOuterPlanarDigraph(`*`digraph`*`)` (property)

Returns: `true` or `false`.

An *outer planar* digraph is a digraph that can be embedded in the plane in such a way that its edges do not intersect, and all vertices belong to the unbounded face of the embedding. A digraph is outer planar if and only if it does not have a subdigraph that is homeomorphic to either the complete graph on 4 vertices or the complete bipartite graph with vertex sets of sizes 2 and 3.

`IsOuterPlanarDigraph` returns `true` if the digraph *`digraph`* is outer planar and `false` if it is not. The directions and multiplicities of any edges in *`digraph`* are ignored by `IsPlanarDigraph`.

See also `IsPlanarDigraph` (6.4.1). This method uses the reference implementation in edge-addition-planarity-suite by John Boyer of the algorithms described in [BM06].

Example

```
gap> IsOuterPlanarDigraph(CompleteDigraph(4));
false
gap> IsOuterPlanarDigraph(CompleteDigraph(5));
false
gap> IsOuterPlanarDigraph(CompleteBipartiteDigraph(2, 3));
false
gap> IsOuterPlanarDigraph(CompleteBipartiteDigraph(3, 3));
false
gap> IsOuterPlanarDigraph(CycleDigraph(10));
true
```

Chapter 7

Homomorphisms

7.1 Acting on digraphs

7.1.1 OnDigraphs (for a digraph and a perm)

▷ `OnDigraphs(`*`digraph, perm`*`)` (operation)
▷ `OnDigraphs(`*`digraph, trans`*`)` (operation)

Returns: A digraph.

If *`digraph`* is a digraph, and the second argument *`perm`* is a *permutation* of the vertices of *`digraph`*, then this operation returns a digraph constructed by relabelling the vertices of *`digraph`* according to *`perm`*. Note that for an automorphism `f` of a digraph, we have `OnDigraphs(`*`digraph`*`, f) = `*`digraph`*.

If the second argument is a *transformation* *`trans`* of the vertices of *`digraph`*, then this operation returns a digraph constructed by transforming the source and range of each edge according to *`trans`*. Thus a vertex which does not appear in the image of *`trans`* will be isolated in the returned digraph, and the returned digraph may contain multiple edges, even if *`digraph`* does not. If *`trans`* is mathematically a permutation, then the result coincides with `OnDigraphs(`*`digraph`*`, AsPermutation(`*`trans`*`))`.

The `DigraphVertexLabels` (5.1.9) of *`digraph`* will not be retained in the returned digraph.

Example

```
gap> gr := Digraph([[3], [1, 3, 5], [1], [1, 2, 4], [2, 3, 5]]);
<digraph with 5 vertices, 11 edges>
gap> new := OnDigraphs(gr, (1, 2));
<digraph with 5 vertices, 11 edges>
gap> OutNeighbours(new);
[ [ 2, 3, 5 ], [ 3 ], [ 2 ], [ 2, 1, 4 ], [ 1, 3, 5 ] ]
gap> gr := Digraph([[2], [], [2]]);
<digraph with 3 vertices, 2 edges>
gap> t := Transformation([1, 2, 1]);;
gap> new := OnDigraphs(gr, t);
<multidigraph with 3 vertices, 2 edges>
gap> OutNeighbours(new);
[ [ 2, 2 ], [  ], [  ] ]
gap> ForAll(DigraphEdges(gr),
>  e -> IsDigraphEdge(new, [e[1] ^ t, e[2] ^ t]));
true
```

7.1.2 OnMultiDigraphs

▷ `OnMultiDigraphs(`*`digraph, pair`*`)` (operation)
▷ `OnMultiDigraphs(`*`digraph, perm1, perm2`*`)` (operation)

Returns: A digraph.

If *digraph* is a digraph, and *pair* is a pair consisting of a permutation of the vertices and a permutation of the edges of *digraph*, then this operation returns a digraph constructed by relabelling the vertices and edges of *digraph* according to *perm[1]* and *perm[2]*, respectively.

In its second form, `OnMultiDigraphs` returns a digraph with vertices and edges permuted by *perm1* and *perm2*, respectively.

Note that `OnDigraphs(`*digraph*`, perm)=OnMultiDigraphs(`*digraph*`, [perm, ()])` where `perm` is a permutation of the vertices of *digraph*. If you are only interested in the action of a permutation on the vertices of a digraph, then you can use `OnDigraphs` instead of `OnMultiDigraphs`.

Example

```
gap> gr1 := Digraph([
> [3, 6, 3], [], [3], [9, 10], [9], [],  [], [10, 4, 10], [], []]);
<multidigraph with 10 vertices, 10 edges>
gap> p := BlissCanonicalLabelling(gr1);
[ (1,9,5,3,10,6,4,7), (1,7,9,5,2,8,4,10,3,6) ]
gap> gr2 := OnMultiDigraphs(gr1, p);
<multidigraph with 10 vertices, 10 edges>
gap> OutNeighbours(gr2);
[ [  ], [  ], [ 5 ], [  ], [  ], [  ], [ 5, 6 ], [ 6, 7, 6 ],
  [ 10, 4, 10 ], [ 10 ] ]
```

7.2 Isomorphisms and canonical labellings

From version 0.11.0 of Digraphs it is possible to use either bliss or nauty (via NautyTracesInterface) to calculate canonical labellings and automorphism groups of digraphs; see [JK07] and [MP14] for more details about bliss and nauty, respectively.

7.2.1 DigraphsUseNauty

▷ `DigraphsUseNauty()` (function)
▷ `DigraphsUseBliss()` (function)

Returns: Nothing.

These functions can be used to specify whether nauty or bliss should be used by default by Digraphs. If NautyTracesInterface is not available, then these functions do nothing. Otherwise, by calling `DigraphsUseNauty` subsequent computations will default to using nauty rather than bliss, where possible.

You can call these functions at any point in a GAP session, as many times as you like, it is guaranteed that existing digraphs remain valid, and that comparison of existing digraphs and newly created digraphs via `IsIsomorphicDigraph` (7.2.14), `IsIsomorphicDigraph` (7.2.15), `IsomorphismDigraphs` (7.2.16), and `IsomorphismDigraphs` (7.2.17) are also valid.

It is also possible to compute the automorphism group of a specific digraph using both nauty and bliss using `NautyAutomorphismGroup` (7.2.4) and `BlissAutomorphismGroup` (7.2.3), respectively.

7.2.2 AutomorphismGroup (for a digraph)

▷ `AutomorphismGroup(`*digraph*`)` (attribute)

Returns: A permutation group.

If *digraph* is a digraph, then this attribute contains the group of automorphisms of *digraph*. An *automorphism* of *digraph* is an isomorphism from *digraph* to itself. See `IsomorphismDigraphs` (7.2.16) for more information about isomorphisms of digraphs.

The form in which the automorphism group is returned depends on whether *digraph* has multiple edges; see `IsMultiDigraph` (6.1.8).

for a digraph without multiple edges

If *digraph* has no multiple edges, then the automorphism group is returned as a group of permutations on the vertices of *digraph*.

for a multidigraph

If *digraph* is a multidigraph, then the automorphism group is a group of permutations on the vertices and edges of *digraph*.

For convenience, the group is returned as the direct product `G` of the group of automorphisms of the vertices of *digraph* with the stabiliser of the vertices in the automorphism group of the edges. These two groups can be accessed using the operation `Projection` (**Reference: Projection for a domain and a positive integer**), with the second argument being `1` or `2`, respectively.

The permutations in the group `Projection(G, 1)` act on the vertices of *digraph*, and the permutations in the group `Projection(G, 2)` act on the indices of `DigraphEdges(`*digraph*`)`.

By default, the automorphism group is found using bliss by Tommi Junttila and Petteri Kaski. If NautyTracesInterface is available, then nauty by Brendan Mckay and Adolfo Piperno can be used instead; see `BlissAutomorphismGroup` (7.2.3), `NautyAutomorphismGroup` (7.2.4), `DigraphsUseBliss` (7.2.1), and `DigraphsUseNauty` (7.2.1).

Example

```
gap> johnson := DigraphFromGraph6String("E}lw");
<digraph with 6 vertices, 24 edges>
gap> G := AutomorphismGroup(johnson);
Group([ (3,4), (2,3)(4,5), (1,2)(5,6) ])
gap> cycle := CycleDigraph(9);
<digraph with 9 vertices, 9 edges>
gap> G := AutomorphismGroup(cycle);
Group([ (1,2,3,4,5,6,7,8,9) ])
gap> IsCyclic(G) and Size(G) = 9;
true
gap> gr := DigraphEdgeUnion(CycleDigraph(3), CycleDigraph(3));
<multidigraph with 3 vertices, 6 edges>
gap> G := AutomorphismGroup(gr);
Group([ (1,2,3), (8,9), (6,7), (4,5) ])
gap> Range(Projection(G, 1));
Group([ (1,2,3) ])
gap> Range(Projection(G, 2));
Group([ (5,6), (3,4), (1,2) ])
gap> Size(G);
24
```

```
gap> gr := Digraph([[2], [3, 3], [3], [2]]);
<multidigraph with 4 vertices, 5 edges>
gap> G := AutomorphismGroup(gr);
Group([ (1,2), (3,4) ])
gap> P1 := Projection(G, 1);
1st projection of Group([ (1,2), (3,4) ])
gap> P2 := Projection(G, 2);
2nd projection of Group([ (1,2), (3,4) ])
gap> DigraphVertices(gr);
[ 1 .. 4 ]
gap> Range(P1);
Group([ (1,4) ])
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 2, 3 ], [ 2, 3 ], [ 3, 3 ], [ 4, 2 ] ]
gap> Range(P2);
Group([ (2,3) ])
```

7.2.3 BlissAutomorphismGroup

▷ `BlissAutomorphismGroup(`*digraph[, colours]*`)` (attribute)

Returns: A permutation group.

If *digraph* is a digraph, then this attribute contains the group of automorphisms of *digraph* as calculated using bliss by Tommi Junttila and Petteri Kaski.

The attribute `AutomorphismGroup` (7.2.2) and operation `AutomorphismGroup` (7.2.5) returns the value of either `BlissAutomorphismGroup` or `NautyAutomorphismGroup` (7.2.4). These groups are, of course, equal but their generating sets may differ.

See also `DigraphsUseBliss` (7.2.1), and `DigraphsUseNauty` (7.2.1).

Example

```
gap> BlissAutomorphismGroup(JohnsonDigraph(5, 2));
Group([ (3,4)(6,7)(8,9), (2,3)(5,6)(9,10), (2,5)(3,6)(4,7), (1,2)(6,8)
(7,9) ])
```

7.2.4 NautyAutomorphismGroup

▷ `NautyAutomorphismGroup(`*digraph[, colours]*`)` (attribute)

Returns: A permutation group.

If *digraph* is a digraph, then this attribute contains the group of automorphisms of *digraph* as calculated using nauty by Brendan Mckay and Adolfo Piperno via NautyTracesInterface. The attribute `AutomorphismGroup` (7.2.2) and operation `AutomorphismGroup` (7.2.5) returns the value of either `NautyAutomorphismGroup` or `BlissAutomorphismGroup` (7.2.3). These groups are, of course, equal but their generating sets may differ.

See also `DigraphsUseBliss` (7.2.1), and `DigraphsUseNauty` (7.2.1).

Example

```
gap> NautyAutomorphismGroup(JohnsonDigraph(5, 2));
Group([ (3,4)(6,7)(8,9), (2,3)(5,6)(9,10), (2,5)(3,6)(4,7), (1,2)(6,8)(7,9) ])
```

7.2.5 AutomorphismGroup (for a digraph and a homogeneous list)

▷ `AutomorphismGroup(`*`digraph, colours`*`)` (operation)

Returns: A permutation group.

This operation computes the automorphism group of a coloured digraph. A coloured digraph can be specified by its underlying digraph *`digraph`* and its colouring *`colours`*. Let `n` be the number of vertices of *`digraph`*. The colouring *`colours`* may have one of the following two forms:

- a list of `n` integers, where *`colours`*`[i]` is the colour of vertex `i`, using the colours `[1 .. m]` for some `m <= n`; or
- a list of non-empty disjoint lists whose union is `DigraphVertices(`*`digraph`*`)`, such that *`colours`*`[i]` is the list of all vertices with colour `i`.

The *automorphism group* of a coloured digraph *`digraph`* with colouring *`colours`* is the group consisting of its automorphisms; an *automorphism* of *`digraph`* is an isomorphism of coloured digraphs from *`digraph`* to itself. This group is equal to the subgroup of `AutomorphismGroup(`*`digraph`*`)` consisting of those automorphisms that preserve the colouring specified by *`colours`*. See `AutomorphismGroup` (7.2.2), and see `IsomorphismDigraphs` (7.2.17) for more information about isomorphisms of coloured digraphs.

The form in which the automorphism group is returned depends on whether *`digraph`* has multiple edges; see `IsMultiDigraph` (6.1.8).

for a digraph without multiple edges

If *`digraph`* has no multiple edges, then the automorphism group is returned as a group of permutations on the vertices of *`digraph`*.

for a multidigraph

If *`digraph`* is a multidigraph, then the automorphism group is a group of permutations on the vertices and edges of *`digraph`*.

For convenience, the group is returned as the direct product `G` of the group of automorphisms of the vertices of *`digraph`* with the stabiliser of the vertices in the automorphism group of the edges. These two groups can be accessed using the operation `Projection` (**Reference: Projection for a domain and a positive integer**), with the second argument being `1` or `2`, respectively.

The permutations in the group `Projection(G, 1)` act on the vertices of *`digraph`*, and the permutations in the group `Projection(G, 2)` act on the indices of `DigraphEdges(`*`digraph`*`)`.

By default, the automorphism group is found using bliss by Tommi Junttila and Petteri Kaski. If NautyTracesInterface is available, then nauty by Brendan Mckay and Adolfo Piperno can be used instead; see `BlissAutomorphismGroup` (7.2.3), `NautyAutomorphismGroup` (7.2.4), `DigraphsUseBliss` (7.2.1), and `DigraphsUseNauty` (7.2.1).

Example

```
gap> cycle := CycleDigraph(9);
<digraph with 9 vertices, 9 edges>
gap> G := AutomorphismGroup(cycle);;
gap> IsCyclic(G) and Size(G) = 9;
true
gap> colours := [[1, 4, 7], [2, 5, 8], [3, 6, 9]];;
gap> H := AutomorphismGroup(cycle, colours);;
```

```
gap> Size(H);
3
gap> H = AutomorphismGroup(cycle, [1, 2, 3, 1, 2, 3, 1, 2, 3]);
true
gap> H = SubgroupByProperty(G, p -> OnTuplesSets(colours, p) = colours);
true
gap> IsTrivial(AutomorphismGroup(cycle, [1, 1, 2, 2, 2, 2, 2, 2, 2]));
true
gap> gr := Digraph([[2], [3, 3], [3], [2], [2]]);
<multidigraph with 5 vertices, 6 edges>
gap> G := AutomorphismGroup(gr, [1, 1, 2, 3, 1]);
Group([ (1,2), (3,4) ])
gap> P1 := Projection(G, 1);
1st projection of Group([ (1,2), (3,4) ])
gap> P2 := Projection(G, 2);
2nd projection of Group([ (1,2), (3,4) ])
gap> DigraphVertices(gr);
[ 1 .. 5 ]
gap> Range(P1);
Group([ (1,5) ])
gap> DigraphEdges(gr);
[ [ 1, 2 ], [ 2, 3 ], [ 2, 3 ], [ 3, 3 ], [ 4, 2 ], [ 5, 2 ] ]
gap> Range(P2);
Group([ (2,3) ])
```

7.2.6 BlissCanonicalLabelling (for a digraph)

▷ `BlissCanonicalLabelling(`*digraph*`)` (attribute)

▷ `NautyCanonicalLabelling(`*digraph*`)` (attribute)

Returns: A permutation, or a list of two permutations.

A function ρ that maps a digraph to a digraph is a *canonical representative map* if the following two conditions hold for all digraphs G and H:

- $\rho(G)$ and G are isomorphic as digraphs; and
- $\rho(G) = \rho(H)$ if and only if G and H are isomorphic as digraphs.

A *canonical labelling* of a digraph G (under ρ) is an isomorphism of G onto its *canonical representative*, $\rho(G)$. See `IsomorphismDigraphs` (7.2.16) for more information about isomorphisms of digraphs.

`BlissCanonicalLabelling` returns a canonical labelling of the digraph *digraph* found using bliss by Tommi Junttila and Petteri Kaski. `NautyCanonicalLabelling` returns a canonical labelling of the digraph *digraph* found using nauty by Brendan McKay and Adolfo Piperno. Note that the canonical labellings returned by bliss and nauty are not usually the same (and may depend of the version used).

The form of the canonical labelling returned by `BlissCanonicalLabelling` depends on whether *digraph* has multiple edges; see `IsMultiDigraph` (6.1.8).

for a digraph without multiple edges

If the digraph *digraph* has no multiple edges, then the canonical labelling of *digraph* is given

as a permutation of its vertices. The canonical representative of *digraph* can be created from *digraph* and its canonical labelling p by using the operation OnDigraphs (7.1.1):

Example

```
gap> OnDigraphs(digraph, p);
```

for a multidigraph

The canonical labelling of the multidigraph *digraph* is given as a pair P of permutations. The first, P[1], is a permutation of the vertices of *digraph*. The second, P[2], is a permutation of the edges of *digraph*; it acts on the indices of the list DigraphEdges(*digraph*). The canonical representative of *digraph* can be created from *digraph* and its canonical labelling P by using the operation OnMultiDigraphs (7.1.2):

Example

```
gap> OnMultiDigraphs(digraph, P);
```

Example

```
gap> digraph1 := DigraphFromDiSparse6String(".ImNS_AiB?qRN");
<digraph with 10 vertices, 8 edges>
gap> BlissCanonicalLabelling(digraph1);
(1,3,4)(2,10,6,7,9,8)
gap> p := (1, 2, 7, 5)(3, 9)(6, 10, 8);;
gap> digraph2 := OnDigraphs(digraph1, p);
<digraph with 10 vertices, 8 edges>
gap> digraph1 = digraph2;
false
gap> OnDigraphs(digraph1, BlissCanonicalLabelling(digraph1)) =
>    OnDigraphs(digraph2, BlissCanonicalLabelling(digraph2));
true
gap> gr := DigraphFromDiSparse6String(".ImEk|O@SK?od");
<multidigraph with 10 vertices, 10 edges>
gap> BlissCanonicalLabelling(gr);
[ (1,9,7,5)(2,10,3), (1,6,9)(2,5,10,4,8)(3,7) ]
gap> gr := Digraph([[2], [3, 3], [3], [2], [2]]);
<multidigraph with 5 vertices, 6 edges>
gap> BlissCanonicalLabelling(gr, [1, 2, 2, 1, 3]);
[ (1,2,4), (1,2,6,4,3,5) ]
```

7.2.7 BlissCanonicalLabelling (for a digraph and a list)

▷ BlissCanonicalLabelling(*digraph*, *colours*) (operation)

▷ NautyCanonicalLabelling(*digraph*, *colours*) (operation)

Returns: A permutation.

A function ρ that maps a coloured digraph to a coloured digraph is a *canonical representative map* if the following two conditions hold for all coloured digraphs G and H:

- $\rho(G)$ and G are isomorphic as coloured digraphs; and
- $\rho(G) = \rho(H)$ if and only if G and H are isomorphic as coloured digraphs.

A *canonical labelling* of a coloured digraph G (under ρ) is an isomorphism of G onto its *canonical representative*, $\rho(G)$. See IsomorphismDigraphs (7.2.17) for more information about isomorphisms of coloured digraphs.

A coloured digraph can be specified by its underlying digraph *digraph* and its colouring *colours*. Let n be the number of vertices of *digraph*. The colouring *colours* may have one of the following two forms:

- a list of n integers, where *colours*[i] is the colour of vertex i, using the colours [1 .. m] for some m <= n; or
- a list of non-empty disjoint lists whose union is DigraphVertices(*digraph*), such that *colours*[i] is the list of all vertices with colour i.

If *digraph* and *colours* together form a coloured digraph, BlissCanonicalLabelling returns a canonical labelling of the digraph *digraph* found using bliss by Tommi Junttila and Petteri Kaski. Similarly, NautyCanonicalLabelling returns a canonical labelling of the digraph *digraph* found using nauty by Brendan McKay and Adolfo Piperno. Note that the canonical labellings returned by bliss and nauty are not usually the same (and may depend of the version used).

The form of the canonical labelling returned by BlissCanonicalLabelling depends on whether *digraph* has multiple edges; see IsMultiDigraph (6.1.8).

for a digraph without multiple edges

If the digraph *digraph* has no multiple edges, then the canonical labelling of *digraph* is given as a permutation of its vertices. The canonical representative of *digraph* can be created from *digraph* and its canonical labelling p by using the operation OnDigraphs (7.1.1):

Example

```
gap> OnDigraphs(digraph, p);
```

for a multidigraph

The canonical labelling of the multidigraph *digraph* is given as a pair P of permutations. The first, P[1], is a permutation of the vertices of *digraph*. The second, P[2], is a permutation of the edges of *digraph*; it acts on the indices of the list DigraphEdges(*digraph*). The canonical representative of *digraph* can be created from *digraph* and its canonical labelling P by using the operation OnMultiDigraphs (7.1.2):

Example

```
gap> OnMultiDigraphs(digraph, P);
```

In either case, the colouring of the canonical representative can easily be constructed. A vertex v (in *digraph*) has colour i if and only if the vertex v ^ p (in the canonical representative) has colour i, where p is the permutation of the canonical labelling that acts on the vertices of *digraph*. In particular, if *colours* has the first form that is described above, then the colouring of the canonical representative is given by:

Example

```
gap> List(DigraphVertices(digraph), i -> colours[i / p]);
```

On the other hand, if *colours* has the second form above, then the canonical representative has colouring:

Example

```
gap> OnTuplesSets(colours, p);
```

Example

```
gap> digraph := DigraphFromDiSparse6String(".ImNS_AiB?qRN");
<digraph with 10 vertices, 8 edges>
gap> colours := [[1, 2, 8, 9, 10], [3, 4, 5, 6, 7]];;
gap> p := BlissCanonicalLabelling(digraph, colours);
(2,3,7,10)(4,6,9,5,8)
gap> OnDigraphs(digraph, p);
<digraph with 10 vertices, 8 edges>
gap> OnTuplesSets(colours, p);
[ [ 1, 2, 3, 4, 5 ], [ 6, 7, 8, 9, 10 ] ]
gap> colours := [1, 1, 1, 1, 2, 3, 1, 3, 2, 1];;
gap> p := BlissCanonicalLabelling(digraph, colours);
(2,3,4,6,10,5,8,9,7)
gap> OnDigraphs(digraph, p);
<digraph with 10 vertices, 8 edges>
gap> List(DigraphVertices(digraph), i -> colours[i / p]);
[ 1, 1, 1, 1, 1, 1, 2, 2, 3, 3 ]
```

7.2.8 BlissCanonicalDigraph

▷ `BlissCanonicalDigraph(`*digraph*`)` (attribute)
▷ `NautyCanonicalDigraph(`*digraph*`)` (attribute)

Returns: A digraph.

The attribute `BlissCanonicalLabelling` returns the canonical representative found by applying `BlissCanonicalLabelling` (7.2.6). The digraph returned is canonical in the sense that

- `BlissCanonicalDigraph(`*digraph*`)` and *digraph* are isomorphic as digraphs; and
- If `gr` is any digraph then `BlissCanonicalDigraph(gr)` and `BlissCanonicalDigraph(`*digraph*`)` are equal if and only if `gr` and *digraph* are isomorphic as digraphs.

Analogously, the attribute `NautyCanonicalLabelling` returns the canonical representative found by applying `NautyCanonicalLabelling` (7.2.6).

Example

```
gap> digraph := Digraph([[1], [2, 3], [3], [1, 2, 3]]);
<digraph with 4 vertices, 7 edges>
gap> canon := BlissCanonicalDigraph(digraph);
<digraph with 4 vertices, 7 edges>
gap> OutNeighbours(canon);
[ [ 1 ], [ 2, 4 ], [ 1, 2, 4 ], [ 4 ] ]
```

7.2.9 DigraphGroup

▷ `DigraphGroup(`*digraph*`)` (attribute)

Returns: A permutation group.

If *digraph* was created knowing a subgroup of its automorphism group, then this group is stored in the attribute `DigraphGroup`. If *digraph* is not created knowing a subgroup of its automorphism group, then `DigraphGroup` returns the entire automorphism group of *digraph*.

Note that certain other constructor operations such as CayleyDigraph (3.1.10), BipartiteDoubleDigraph (3.3.32), and DoubleDigraph (3.3.31), may not require a group as one of the arguments, but use the standard constructor method using a group, and hence set the DigraphGroup attribute for the resulting digraph.

Example

```
gap> n := 4;;
gap> adj := function(x, y)
>      return (((x - y) mod n) = 1) or (((x - y) mod n) = n - 1);
>    end;;
gap> group := CyclicGroup(IsPermGroup, n);
Group([ (1,2,3,4) ])
gap> digraph := Digraph(group, [1 .. n], \^, adj);
<digraph with 4 vertices, 8 edges>
gap> HasDigraphGroup(digraph);
true
gap> DigraphGroup(digraph);
Group([ (1,2,3,4) ])
gap> AutomorphismGroup(digraph);
Group([ (2,4), (1,2)(3,4) ])
gap> ddigraph := DoubleDigraph(digraph);
<digraph with 8 vertices, 32 edges>
gap> HasDigraphGroup(ddigraph);
true
gap> DigraphGroup(ddigraph);
Group([ (1,2,3,4)(5,6,7,8), (1,5)(2,6)(3,7)(4,8) ])
gap> AutomorphismGroup(ddigraph) =
> Group([(6, 8), (5, 7), (4, 6), (3, 5), (2, 4),
>        (1, 2)(3, 4)(5, 6)(7, 8)]);
true
gap> digraph := Digraph([[2, 3], [], []]);
<digraph with 3 vertices, 2 edges>
gap> HasDigraphGroup(digraph);
false
gap> HasAutomorphismGroup(digraph);
false
gap> DigraphGroup(digraph);
Group([ (2,3) ])
gap> HasAutomorphismGroup(digraph);
true
gap> group := DihedralGroup(8);
<pc group of size 8 with 3 generators>
gap> digraph := CayleyDigraph(group);
<digraph with 8 vertices, 24 edges>
gap> HasDigraphGroup(digraph);
true
gap> DigraphGroup(digraph);
Group([ (1,2)(3,8)(4,6)(5,7), (1,3,4,7)(2,5,6,8), (1,4)(2,6)(3,7)
(5,8) ])
```

7.2.10 DigraphOrbits

▷ `DigraphOrbits(`*`digraph`*`)` (attribute)

Returns: A list of lists of integers.

`DigraphOrbits` returns the orbits of the action of the `DigraphGroup` (7.2.9) on the set of vertices of *`digraph`*.

Example

```
gap> G := Group([(2, 3)(7, 8, 9), (1, 2, 3)(4, 5, 6)(8, 9)]);;
gap> gr := EdgeOrbitsDigraph(G, [1, 2]);
<digraph with 9 vertices, 6 edges>
gap> DigraphOrbits(gr);
[ [ 1, 2, 3 ], [ 4, 5, 6 ], [ 7, 8, 9 ] ]
```

7.2.11 DigraphOrbitReps

▷ `DigraphOrbitReps(`*`digraph`*`)` (attribute)

Returns: A list of integers.

`DigraphOrbitReps` returns a list of orbit representatives of the action of the `DigraphGroup` (7.2.9) on the set of vertices of *`digraph`*.

Example

```
gap> digraph := CayleyDigraph(AlternatingGroup(4));
<digraph with 12 vertices, 24 edges>
gap> DigraphOrbitReps(digraph);
[ 1 ]
gap> digraph := DigraphFromDigraph6String("&IGO??S?‘?_@?a?CK?O");
<digraph with 10 vertices, 14 edges>
gap> DigraphOrbitReps(digraph);
[ 1, 2, 3, 4, 5, 6, 7, 8, 9, 10 ]
```

7.2.12 DigraphSchreierVector

▷ `DigraphSchreierVector(`*`digraph`*`)` (attribute)

Returns: A list of integers.

`DigraphSchreierVector` returns the so-called *Schreier vector* of the action of the `DigraphGroup` (7.2.9) on the set of vertices of *`digraph`*. The Schreier vector is a list `sch` of integers with length `DigraphNrVertices(`*`digraph`*`)` where:

`sch[i] < 0`:
: implies that `i` is an orbit representative and `DigraphOrbitReps(`*`digraph`*`)[-sch[i]] = i`.

`sch[i] > 0`:
: implies that `i / gens[sch[i]]` is one step closer to the root (or representative) of the tree, where `gens` is the generators of `DigraphGroup(`*`digraph`*`)`.

Example

```
gap> digraph := CayleyDigraph(AlternatingGroup(4));
<digraph with 12 vertices, 24 edges>
gap> sch := DigraphSchreierVector(digraph);
[ -1, 2, 2, 1, 1, 1, 1, 1, 2, 2, 2, 1 ]
gap> DigraphOrbitReps(digraph);
[ 1 ]
```

```
gap> gens := GeneratorsOfGroup(DigraphGroup(digraph));
[ (1,5,7)(2,4,8)(3,6,9)(10,11,12), (1,2,3)(4,7,10)(5,9,11)(6,8,12) ]
gap> 10 / gens[sch[10]];
7
gap> 7 / gens[sch[7]];
5
gap> 5 / gens[sch[5]];
1
```

7.2.13 DigraphStabilizer

▷ `DigraphStabilizer(`*digraph*`, `*v*`)` (operation)

Returns: A permutation group.

`DigraphStabilizer` returns the stabilizer of the vertex *v* under of the action of the `DigraphGroup` (7.2.9) on the set of vertices of *digraph*.

Example

```
gap> digraph := DigraphFromDigraph6String("&GYHPQgWTIIPW");
<digraph with 8 vertices, 24 edges>
gap> DigraphStabilizer(digraph, 8);
Group(())
gap> DigraphStabilizer(digraph, 2);
Group(())
```

7.2.14 IsIsomorphicDigraph (for digraphs)

▷ `IsIsomorphicDigraph(`*digraph1*`, `*digraph2*`)` (operation)

Returns: `true` or `false`.

This operation returns `true` if there exists an isomorphism from the digraph *digraph1* to the digraph *digraph2*. See `IsomorphismDigraphs` (7.2.16) for more information about isomorphisms of digraphs.

By default, an isomorphism is found using the canonical labellings of the digraphs obtained from bliss by Tommi Junttila and Petteri Kaski. If NautyTracesInterface is available, then nauty by Brendan Mckay and Adolfo Piperno can be used instead; see `DigraphsUseBliss` (7.2.1), and `DigraphsUseNauty` (7.2.1).

Example

```
gap> digraph1 := CycleDigraph(4);
<digraph with 4 vertices, 4 edges>
gap> digraph2 := CycleDigraph(5);
<digraph with 5 vertices, 5 edges>
gap> IsIsomorphicDigraph(digraph1, digraph2);
false
gap> digraph2 := DigraphReverse(digraph1);
<digraph with 4 vertices, 4 edges>
gap> IsIsomorphicDigraph(digraph1, digraph2);
true
gap> digraph1 := DigraphFromDiSparse6String(".IiGdqrHiogeaF");
<multidigraph with 10 vertices, 10 edges>
gap> digraph2 := DigraphFromDiSparse6String(".IiK‘K@FFSouF_|^");
<multidigraph with 10 vertices, 10 edges>
gap> IsIsomorphicDigraph(digraph1, digraph2);
```

```
false
gap> digraph1 := Digraph([[3], [], []]);
<digraph with 3 vertices, 1 edge>
gap> digraph2 := Digraph([[], [], [2]]);
<digraph with 3 vertices, 1 edge>
gap> IsIsomorphicDigraph(digraph1, digraph2);
true
```

7.2.15 IsIsomorphicDigraph (for digraphs and homogeneous lists)

▷ IsIsomorphicDigraph(*digraph1*, *digraph2*, *colours1*, *colours2*) (operation)

Returns: true or false.

This operation tests for isomorphism of coloured digraphs. A coloured digraph can be specified by its underlying digraph *digraph1* and its colouring *colours1*. Let n be the number of vertices of *digraph1*. The colouring *colours1* may have one of the following two forms:

- a list of n integers, where *colours*[i] is the colour of vertex i, using the colours [1 .. m] for some m <= n; or
- a list of non-empty disjoint lists whose union is DigraphVertices(*digraph*), such that *colours*[i] is the list of all vertices with colour i.

If *digraph1* and *digraph2* are digraphs without multiple edges, and *colours1* and *colours2* are colourings of *digraph1* and *digraph2*, respectively, then this operation returns true if there exists an isomorphism between these two coloured digraphs. See IsomorphismDigraphs (7.2.17) for more information about isomorphisms of coloured digraphs.

By default, an isomorphism is found using the canonical labellings of the digraphs obtained from bliss by Tommi Junttila and Petteri Kaski. If NautyTracesInterface is available, then nauty by Brendan Mckay and Adolfo Piperno can be used instead; see DigraphsUseBliss (7.2.1), and DigraphsUseNauty (7.2.1).

Example

```
gap> digraph1 := ChainDigraph(4);
<digraph with 4 vertices, 3 edges>
gap> digraph2 := ChainDigraph(3);
<digraph with 3 vertices, 2 edges>
gap> IsIsomorphicDigraph(digraph1, digraph2,
>  [[1, 4], [2, 3]], [[1, 2], [3]]);
false
gap> digraph2 := DigraphReverse(digraph1);
<digraph with 4 vertices, 3 edges>
gap> IsIsomorphicDigraph(digraph1, digraph2,
>  [1, 1, 1, 1], [1, 1, 1, 1]);
true
gap> IsIsomorphicDigraph(digraph1, digraph2,
>  [1, 2, 2, 1], [1, 2, 2, 1]);
true
gap> IsIsomorphicDigraph(digraph1, digraph2,
>  [1, 1, 2, 2], [1, 1, 2, 2]);
false
gap> digraph1 := Digraph([[2, 1, 2], [1, 2, 1]]);
<multidigraph with 2 vertices, 6 edges>
```

```
gap> IsIsomorphicDigraph(digraph1, digraph1, [2, 1], [1, 2]);
true
gap> IsIsomorphicDigraph(digraph1, digraph1, [1, 1], [1, 2]);
false
```

7.2.16 IsomorphismDigraphs (for digraphs)

▷ IsomorphismDigraphs(*digraph1, digraph2*) (operation)

Returns: A permutation, or a pair of permutations, or fail.

This operation returns an isomorphism between the digraphs *digraph1* and *digraph2* if one exists, else this operation returns fail.

for digraphs without multiple edges

An *isomorphism* from a digraph *digraph1* to a digraph *digraph2* is a bijection p from the vertices of *digraph1* to the vertices of *digraph2* with the following property: for all vertices i and j of *digraph1*, [i, j] is an edge of *digraph1* if and only if [i ^ p, j ^ p] is an edge of *digraph2*.

If there exists such an isomorphism, then this operation returns one. The form of this isomorphism is a permutation p of the vertices of *digraph1* such that

OnDigraphs(*digraph1*, p) = digraph2.

for multidigraphs

An *isomorphism* from a multidigraph *digraph1* to a multidigraph *digraph2* is a bijection P[1] from the vertices of *digraph1* to the vertices of *digraph2* and a bijection P[2] from the indices of edges of *digraph1* to the indices of edges of *digraph2* with the following property: [i, j] is the kth edge of *digraph1* if and only if [i ^ P[1], j ^ P[1]] is the (k ^ P[2])th edge of *digraph2*.

If there exists such an isomorphism, then this operation returns one. The form of this isomorphism is a pair of permutations P -– where the first is a permutation of the vertices of *digraph1* and the second is a permutation of the indices of DigraphEdges(*digraph1*) -– such that

OnMultiDigraphs(*digraph1*, P) = *digraph2*.

By default, an isomorphism is found using the canonical labellings of the digraphs obtained from bliss by Tommi Junttila and Petteri Kaski. If NautyTracesInterface is available, then nauty by Brendan Mckay and Adolfo Piperno can be used instead; see DigraphsUseBliss (7.2.1), and DigraphsUseNauty (7.2.1).

Example

```
gap> digraph1 := CycleDigraph(4);
<digraph with 4 vertices, 4 edges>
gap> digraph2 := CycleDigraph(5);
<digraph with 5 vertices, 5 edges>
gap> IsomorphismDigraphs(digraph1, digraph2);
fail
gap> digraph1 := CompleteBipartiteDigraph(10, 5);
<digraph with 15 vertices, 100 edges>
gap> digraph2 := CompleteBipartiteDigraph(5, 10);
<digraph with 15 vertices, 100 edges>
gap> p := IsomorphismDigraphs(digraph1, digraph2);
```

```
(1,6,11)(2,7,12)(3,8,13)(4,9,14)(5,10,15)
gap> OnDigraphs(digraph1, p) = digraph2;
true
gap> digraph1 := DigraphFromDiSparse6String(".ImNS_?DSE@ce[~");
<multidigraph with 10 vertices, 10 edges>
gap> digraph2 := DigraphFromDiSparse6String(".IkOlQefi_kgOf");
<multidigraph with 10 vertices, 10 edges>
gap> IsomorphismDigraphs(digraph1, digraph2);
[ (1,9,5,3,10,6,4,7,2), (1,8,6,3,7)(2,9,4,10,5) ]
gap> digraph1 := DigraphByEdges([[7, 10], [7, 10]], 10);
<multidigraph with 10 vertices, 2 edges>
gap> digraph2 := DigraphByEdges([[2, 3], [2, 3]], 10);
<multidigraph with 10 vertices, 2 edges>
gap> IsomorphismDigraphs(digraph1, digraph2);
[ (2,4,6,8,9,10,3,5,7), () ]
```

7.2.17 IsomorphismDigraphs (for digraphs and homogeneous lists)

▷ `IsomorphismDigraphs(`*`digraph1, digraph2, colours1, colours2`*`)` (operation)

Returns: A permutation, or `fail`.

This operation searches for an isomorphism between coloured digraphs. A coloured digraph can be specified by its underlying digraph *`digraph1`* and its colouring *`colours1`*. Let `n` be the number of vertices of *`digraph1`*. The colouring *`colours1`* may have one of the following two forms:

- a list of `n` integers, where *`colours`*`[i]` is the colour of vertex `i`, using the colours `[1 .. m]` for some `m <= n`; or
- a list of non-empty disjoint lists whose union is `DigraphVertices(`*`digraph`*`)`, such that *`colours`*`[i]` is the list of all vertices with colour `i`.

An *isomorphism* between coloured digraphs is an isomorphism between the underlying digraphs that preserves the colourings. See `IsomorphismDigraphs` (7.2.16) for more information about isomorphisms of digraphs. More precisely, let `f` be an isomorphism of digraphs from the digraph *`digraph1`* (with colouring *`colours1`*) to the digraph *`digraph2`* (with colouring *`colours2`*), and let `p` be the permutation of the vertices of *`digraph1`* that corresponds to `f`. Then `f` preserves the colourings of *`digraph1`* and *`digraph2`* – and hence is an isomorphism of coloured digraphs – if *`colours1`*`[i] = `*`colours2`*`[i ^ p]` for all vertices `i` in *`digraph1`*.

This operation returns such an isomorphism if one exists, else it returns `fail`.

By default, an isomorphism is found using the canonical labellings of the digraphs obtained from bliss by Tommi Junttila and Petteri Kaski. If NautyTracesInterface is available, then nauty by Brendan Mckay and Adolfo Piperno can be used instead; see `DigraphsUseBliss` (7.2.1), and `DigraphsUseNauty` (7.2.1).

Example

```
gap> digraph1 := ChainDigraph(4);
<digraph with 4 vertices, 3 edges>
gap> digraph2 := ChainDigraph(3);
<digraph with 3 vertices, 2 edges>
gap> IsomorphismDigraphs(digraph1, digraph2,
>  [[1, 4], [2, 3]], [[1, 2], [3]]);
fail
```

```
gap> digraph2 := DigraphReverse(digraph1);
<digraph with 4 vertices, 3 edges>
gap> colours1 := [1, 1, 1, 1];;
gap> colours2 := [1, 1, 1, 1];;
gap> p := IsomorphismDigraphs(digraph1, digraph2, colours1, colours2);
(1,4)(2,3)
gap> OnDigraphs(digraph1, p) = digraph2;
true
gap> List(DigraphVertices(digraph1), i -> colours1[i ^ p]) = colours2;
true
gap> colours1 := [1, 1, 2, 2];;
gap> colours2 := [2, 2, 1, 1];;
gap> p := IsomorphismDigraphs(digraph1, digraph2, colours1, colours2);
(1,4)(2,3)
gap> OnDigraphs(digraph1, p) = digraph2;
true
gap> List(DigraphVertices(digraph1), i -> colours1[i ^ p]) = colours2;
true
gap> IsomorphismDigraphs(digraph1, digraph2,
>  [1, 1, 2, 2], [1, 1, 2, 2]);
fail
gap> digraph1 := Digraph([[2, 2], [2], [1]]);
<multidigraph with 3 vertices, 4 edges>
gap> digraph2 := Digraph([[1], [1, 1], [2]]);
<multidigraph with 3 vertices, 4 edges>
gap> IsomorphismDigraphs(digraph1, digraph2, [1, 2, 2], [2, 1, 2]);
[ (1,2), (1,2,3) ]
```

7.2.18 RepresentativeOutNeighbours

▷ `RepresentativeOutNeighbours(`*digraph*`)` (attribute)

Returns: An immutable list of immutable lists.

This function returns the list `out` of *out-neighbours* of each representative of the orbits of the action of `DigraphGroup` (7.2.9) on the vertex set of the digraph *digraph*.

More specifically, if `reps` is the list of orbit representatives, then a vertex `j` appears in `out[i]` each time there exists an edge with source `reps[i]` and range `j` in *digraph*.

If `DigraphGroup` (7.2.9) is trivial, then `OutNeighbours` (5.2.6) is returned.

Example

```
gap> digraph := Digraph([
>  [2, 1, 3, 4, 5], [3, 5], [2], [1, 2, 3, 5], [1, 2, 3, 4]]);
<digraph with 5 vertices, 16 edges>
gap> DigraphGroup(digraph);
Group(())
gap> RepresentativeOutNeighbours(digraph);
[ [ 2, 1, 3, 4, 5 ], [ 3, 5 ], [ 2 ], [ 1, 2, 3, 5 ], [ 1, 2, 3, 4 ] ]
gap> digraph := DigraphFromDigraph6String("&GYHPQgWTIIPW");
<digraph with 8 vertices, 24 edges>
gap> DigraphGroup(digraph);
Group([ (1,2)(3,4)(5,6)(7,8), (1,3,2,4)(5,7,6,8), (1,5)(2,6)(3,8)
(4,7) ])
```

```
gap> Set(RepresentativeOutNeighbours(digraph), Set);
[ [ 2, 3, 5 ] ]
```

7.2.19 IsDigraphIsomorphism

▷ IsDigraphIsomorphism(*src*, *ran*, *x*) (operation)
▷ IsDigraphAutomorphism(*digraph*, *x*) (operation)

Returns: true or false.

IsDigraphIsomorphism returns true if the permutation or transformation *x* is an isomorphism from the digraph *src* to the digraph *ran*.

IsDigraphAutomorphism returns true if the permutation or transformation *x* is an automorphism of the digraph *digraph*.

A permutation or transformation *x* is an *isomorphism* from a digraph *src* to a digraph *ran* if the following hold:

- *x* is a bijection from the vertices of *src* to those of *ran*;
- [u ^ *x*, v ^ *x*] is an edge of *ran* if and only if [u, v] is an edge of *src*; and
- *x* fixes every i which is not a vertex of *src*.

See also AutomorphismGroup (7.2.2).

For some digraphs, it can be faster to use IsDigraphAutomorphism than to test membership in the automorphism group of *digraph*.

Example

```
gap> src := Digraph([[1], [1, 2], [1, 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsDigraphAutomorphism(src, (1, 2, 3));
false
gap> IsDigraphAutomorphism(src, (2, 3));
true
gap> IsDigraphAutomorphism(src, (2, 3)(4, 5));
false
gap> IsDigraphAutomorphism(src, (1, 4));
false
gap> IsDigraphAutomorphism(src, ());
true
gap> ran := Digraph([[2, 1], [2], [2, 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsDigraphIsomorphism(src, ran, (1, 2));
true
gap> IsDigraphIsomorphism(ran, src, (1, 2));
true
gap> IsDigraphIsomorphism(ran, src, (1, 2));
true
gap> IsDigraphIsomorphism(src, Digraph([[3], [1, 3], [2]]), (1, 2, 3));
false
```

7.2.20 IsDigraphColouring

▷ IsDigraphColouring(*digraph*, *list*) (operation)
▷ IsDigraphColouring(*digraph*, *t*) (operation)

Returns: true or false.

The operation IsDigraphColouring verifies whether or not the list *list* describes a proper colouring of the digraph *digraph*.

A list *list* describes a *proper colouring* of a digraph *digraph* if *list* consists of positive integers, the length of *list* equals the number of vertices in *digraph*, and for any vertices u, v of *digraph* if u and v are adjacent, then *list*[u] >< *list*[v].

A transformation *t* describes a proper colouring of a digraph *digraph*, if ImageListOfTransformation(*t*, DigraphNrVertices(*digraph*)) is a proper colouring of *digraph*.

See also IsDigraphHomomorphism (7.3.10).

Example

```
gap> D := JohnsonDigraph(5, 3);
<digraph with 10 vertices, 60 edges>
gap> IsDigraphColouring(D, [1, 2, 3, 3, 2, 1, 4, 5, 6, 7]);
true
gap> IsDigraphColouring(D, [1, 2, 3, 3, 2, 1, 2, 5, 6, 7]);
false
gap> IsDigraphColouring(D, [1, 2, 3, 3, 2, 1, 2, 5, 6, -1]);
false
gap> IsDigraphColouring(D, [1, 2, 3]);
false
gap> IsDigraphColouring(D, IdentityTransformation);
true
```

7.3 Homomorphisms of digraphs

The following methods exist to find homomorphisms between digraphs. If an argument to one of these methods is a digraph with multiple edges, then the multiplicity of edges will be ignored in order to perform the calculation; the digraph will be treated as if it has no multiple edges.

7.3.1 HomomorphismDigraphsFinder

▷ HomomorphismDigraphsFinder(*D1*, *D2*, *hook*, *user_param*, *max_results*, *hint*, *injective*, *image*, *partial_map*, *colors1*, *colors2*[, *order*]) (function)

Returns: The argument *user_param*.

This function finds homomorphisms from the digraph *D1* to the digraph *D2* subject to the conditions imposed by the other arguments as described below.

If f and g are homomorphisms found by HomomorphismDigraphsFinder, then f cannot be obtained from g by right multiplying by an automorphism of *D2*.

hook

This argument should be a function or fail.

If *hook* is a function, then it must have two arguments *user_param* (see below) and a transformation t. The function *hook*(*user_param*, t) is called every time a new homomorphism t is found by HomomorphismDigraphsFinder.

If *hook* is fail, then a default function is used which simply adds every new homomorphism found by HomomorphismDigraphsFinder to *user_param*, which must be a mutable list in this case.

user_param
: If *hook* is a function, then *user_param* can be any GAP object. The object *user_param* is used as the first argument of the function *hook*. For example, *user_param* might be a transformation semigroup, and *hook*(*user_param*, t) might set *user_param* to be the closure of *user_param* and t.

  If the value of *hook* is fail, then the value of *user_param* must be a mutable list.

max_results
: This argument should be a positive integer or infinity. HomomorphismDigraphsFinder will return after it has found *max_results* homomorphisms or the search is complete, whichever happens first.

hint
: This argument should be a positive integer or fail.

  If *hint* is a positive integer, then only homorphisms of rank *hint* are found.

  If *hint* is fail, then no restriction is put on the rank of homomorphisms found.

injective
: This argument should be 0, 1, or 2. If it is 2, then only embeddings are found, if it is 1, then only injective homomorphisms are found, and if it is 0 there are no restrictions imposed by this argument.

  For backwards compatibility, *injective* can also be false or true which correspond to the values 0 and 1 described in the previous paragraph, respectively.

image
: This argument should be a subset of the vertices of the graph *D2*. HomomorphismDigraphsFinder only finds homomorphisms from *D1* to the subgraph of *D2* induced by the vertices *image*.

partial_map
: This argument should be a partial map from *D1* to *D2*, that is, a (not necessarily dense) list of vertices of the digraph *D2* of length no greater than the number vertices in the digraph *D1*. HomomorphismDigraphsFinder only finds homomorphisms extending *partial_map* (if any).

colors1
: This should be a list representing possible colours of vertices in the digraph *D1*; see AutomorphismGroup (7.2.5) for details of the permissible values for this argument.

colors2
: This should be a list representing possible colours of vertices in the digraph *D2*; see AutomorphismGroup (7.2.5) for details of the permissible values for this argument.

order
: The optional final argument *order* specifies the order the vertices in *D1* appear in the search for

homomorphisms. The value of this parameter can have a large impact on the runtime of the function. It seems in many cases to be a good idea for this to be the DigraphWelshPowellOrder (7.3.15), i.e. vertices ordered from highest to lowest degree.

Example

```
gap> D := ChainDigraph(10);
<digraph with 10 vertices, 9 edges>
gap> D := DigraphSymmetricClosure(D);
<digraph with 10 vertices, 18 edges>
gap> HomomorphismDigraphsFinder(D, D, fail, [], infinity, 2, 0,
> [3, 4], [], fail, fail);
[ Transformation( [ 3, 4, 3, 4, 3, 4, 3, 4, 3, 4 ] ),
  Transformation( [ 4, 3, 4, 3, 4, 3, 4, 3, 4, 3 ] ) ]
gap> D2 := CompleteDigraph(6);;
gap> HomomorphismDigraphsFinder(D, D2, fail, [], 1, fail, 0,
> [1 .. 6], [1, 2, 1], fail, fail);
[ Transformation( [ 1, 2, 1, 3, 4, 5, 6, 1, 2, 1 ] ) ]
gap> func := function(user_param, t)
> Add(user_param, t * user_param[1]);
> end;;
gap> HomomorphismDigraphsFinder(D, D2, func, [Transformation([2, 2])],
> 3, fail, 0, [1 .. 6], [1, 2, 1], fail, fail);
[ Transformation( [ 2, 2 ] ),
  Transformation( [ 2, 2, 2, 3, 4, 5, 6, 2, 2, 2 ] ),
  Transformation( [ 2, 2, 2, 3, 4, 5, 6, 2, 2, 3 ] ),
  Transformation( [ 2, 2, 2, 3, 4, 5, 6, 2, 2, 4 ] ) ]
```

7.3.2 DigraphHomomorphism

▷ DigraphHomomorphism(*digraph1, digraph2*) (operation)

Returns: A transformation, or fail.

A homomorphism from *digraph1* to *digraph2* is a mapping from the vertex set of *digraph1* to a subset of the vertices of *digraph2*, such that every pair of vertices [i,j] which has an edge i->j is mapped to a pair of vertices [a,b] which has an edge a->b. Note that non-adjacent vertices can still be mapped to adjacent vertices.

DigraphHomomorphism returns a single homomorphism between *digraph1* and *digraph2* if it exists, otherwise it returns fail.

Example

```
gap> gr1 := ChainDigraph(3);;
gap> gr2 := Digraph([[3, 5], [2], [3, 1], [], [4]]);
<digraph with 5 vertices, 6 edges>
gap> DigraphHomomorphism(gr1, gr1);
IdentityTransformation
gap> map := DigraphHomomorphism(gr1, gr2);
Transformation( [ 3, 1, 5, 4, 5 ] )
gap> IsDigraphHomomorphism(gr1, gr2, map);
true
```

7.3.3 HomomorphismsDigraphs

▷ HomomorphismsDigraphs(*digraph1, digraph2*) (operation)
▷ HomomorphismsDigraphsRepresentatives(*digraph1, digraph2*) (operation)

Returns: A list of transformations.

HomomorphismsDigraphsRepresentatives finds every DigraphHomomorphism (7.3.2) between *digraph1* and *digraph2*, up to right multiplication by an element of the AutomorphismGroup (7.2.2) of *digraph2*. In other words, every homomorphism f between *digraph1* and *digraph2* can be written as the composition f = g * x, where g is one of the HomomorphismsDigraphsRepresentatives and x is an automorphism of *digraph2*.

HomomorphismsDigraphs returns all homomorphisms between *digraph1* and *digraph2*.

Example

```
gap> gr1 := ChainDigraph(3);;
gap> gr2 := Digraph([[3, 5], [2], [3, 1], [], [4]]);
<digraph with 5 vertices, 6 edges>
gap> HomomorphismsDigraphs(gr1, gr2);
[ Transformation( [ 1, 3, 1 ] ), Transformation( [ 1, 3, 3 ] ),
  Transformation( [ 1, 5, 4, 4, 5 ] ), Transformation( [ 2, 2, 2 ] ),
  Transformation( [ 3, 1, 3 ] ), Transformation( [ 3, 1, 5, 4, 5 ] ),
  Transformation( [ 3, 3, 1 ] ), Transformation( [ 3, 3, 3 ] ) ]
gap> HomomorphismsDigraphsRepresentatives(gr1, CompleteDigraph(3));
[ Transformation( [ 2, 1 ] ), Transformation( [ 2, 1, 2 ] ) ]
```

7.3.4 DigraphMonomorphism

▷ DigraphMonomorphism(*digraph1, digraph2*) (operation)

Returns: A transformation, or fail.

DigraphMonomorphism returns a single *injective* DigraphHomomorphism (7.3.2) between *digraph1* and *digraph2* if one exists, otherwise it returns fail.

Example

```
gap> gr1 := ChainDigraph(3);;
gap> gr2 := Digraph([[3, 5], [2], [3, 1], [], [4]]);
<digraph with 5 vertices, 6 edges>
gap> DigraphMonomorphism(gr1, gr1);
IdentityTransformation
gap> DigraphMonomorphism(gr1, gr2);
Transformation( [ 3, 1, 5, 4, 5 ] )
```

7.3.5 MonomorphismsDigraphs

▷ MonomorphismsDigraphs(*digraph1, digraph2*) (operation)
▷ MonomorphismsDigraphsRepresentatives(*digraph1, digraph2*) (operation)

Returns: A list of transformations.

These operations behave the same as HomomorphismsDigraphs (7.3.3) and HomomorphismsDigraphsRepresentatives (7.3.3), except they only return *injective* homomorphisms.

Example

```
gap> gr1 := ChainDigraph(3);;
gap> gr2 := Digraph([[3, 5], [2], [3, 1], [], [4]]);
```

```
<digraph with 5 vertices, 6 edges>
gap> MonomorphismsDigraphs(gr1, gr2);
[ Transformation( [ 1, 5, 4, 4, 5 ] ),
  Transformation( [ 3, 1, 5, 4, 5 ] ) ]
gap> MonomorphismsDigraphsRepresentatives(gr1, CompleteDigraph(3));
[ Transformation( [ 2, 1 ] ) ]
```

7.3.6 DigraphEpimorphism

▷ DigraphEpimorphism(*digraph1*, *digraph2*) (operation)

Returns: A transformation, or fail.

DigraphEpimorphism returns a single *surjective* DigraphHomomorphism (7.3.2) between *digraph1* and *digraph2* if one exists, otherwise it returns fail.

Example

```
gap> gr1 := DigraphReverse(ChainDigraph(4));
<digraph with 4 vertices, 3 edges>
gap> gr2 := DigraphRemoveEdge(CompleteDigraph(3), [1, 2]);
<digraph with 3 vertices, 5 edges>
gap> DigraphEpimorphism(gr2, gr1);
fail
gap> DigraphEpimorphism(gr1, gr2);
Transformation( [ 3, 1, 2, 3 ] )
```

7.3.7 EpimorphismsDigraphs

▷ EpimorphismsDigraphs(*digraph1*, *digraph2*) (operation)

▷ EpimorphismsDigraphsRepresentatives(*digraph1*, *digraph2*) (operation)

Returns: A list of transformations.

These operations behave the same as HomomorphismsDigraphs (7.3.3) and HomomorphismsDigraphsRepresentatives (7.3.3), except they only return *surjective* homomorphisms.

Example

```
gap> gr1 := DigraphReverse(ChainDigraph(4));
<digraph with 4 vertices, 3 edges>
gap> gr2 := DigraphSymmetricClosure(CycleDigraph(3));
<digraph with 3 vertices, 6 edges>
gap> EpimorphismsDigraphsRepresentatives(gr1, gr2);
[ Transformation( [ 3, 1, 2, 1 ] ), Transformation( [ 3, 1, 2, 3 ] ),
  Transformation( [ 2, 1, 2, 3 ] ) ]
gap> EpimorphismsDigraphs(gr1, gr2);
[ Transformation( [ 1, 2, 1, 3 ] ), Transformation( [ 1, 2, 3, 1 ] ),
  Transformation( [ 1, 2, 3, 2 ] ), Transformation( [ 1, 3, 1, 2 ] ),
  Transformation( [ 1, 3, 2, 1 ] ), Transformation( [ 1, 3, 2, 3 ] ),
  Transformation( [ 2, 1, 2, 3 ] ), Transformation( [ 2, 1, 3, 1 ] ),
  Transformation( [ 2, 1, 3, 2 ] ), Transformation( [ 2, 3, 1, 2 ] ),
  Transformation( [ 2, 3, 1, 3 ] ), Transformation( [ 2, 3, 2, 1 ] ),
  Transformation( [ 3, 1, 2, 1 ] ), Transformation( [ 3, 1, 2, 3 ] ),
  Transformation( [ 3, 1, 3, 2 ] ), Transformation( [ 3, 2, 1, 2 ] ),
  Transformation( [ 3, 2, 1, 3 ] ), Transformation( [ 3, 2, 3, 1 ] ) ]
```

7.3.8 DigraphEmbedding

▷ DigraphEmbedding(*digraph1*, *digraph2*) (operation)

Returns: A transformation, or fail.

An embedding of a digraph *digraph1* into another digraph *digraph2* is a DigraphMonomorphism (7.3.4) from *digraph1* to *digraph2* which has the additional property that a pair of vertices [i, j] which have no edge i -> j in *digraph1* are mapped to a pair of vertices [a, b] which have no edge a->b in *digraph2*.

In other words, an embedding t is an isomorphism from *digraph1* to the InducedSubdigraph (3.3.2) of *digraph2* on the image of t.

DigraphEmbedding returns a single embedding if one exists, otherwise it returns fail.

Example

```
gap> gr := ChainDigraph(3);
<digraph with 3 vertices, 2 edges>
gap> DigraphEmbedding(gr, CompleteDigraph(4));
fail
gap> DigraphEmbedding(gr, Digraph([[3], [1, 4], [1], [3]]));
Transformation( [ 2, 4, 3, 4 ] )
```

7.3.9 EmbeddingsDigraphs

▷ EmbeddingsDigraphs(*D1*, *D2*) (operation)

▷ EmbeddingsDigraphsRepresentatives(*D1*, *D2*) (operation)

Returns: A list of transformations.

These operations behave the same as HomomorphismsDigraphs (7.3.3) and HomomorphismsDigraphsRepresentatives (7.3.3), except they only return embeddings of *D1* into *D2*.

See also IsDigraphEmbedding (7.3.11).

Example

```
gap> D1 := NullDigraph(2);
<digraph with 2 vertices, 0 edges>
gap> D2 := CycleDigraph(5);
<digraph with 5 vertices, 5 edges>
gap> EmbeddingsDigraphsRepresentatives(D1, D2);
[ Transformation( [ 1, 3, 3 ] ), Transformation( [ 1, 4, 3, 4 ] ) ]
gap> EmbeddingsDigraphs(D1, D2);
[ Transformation( [ 1, 3, 3 ] ), Transformation( [ 1, 4, 3, 4 ] ),
  Transformation( [ 2, 4, 4, 5, 1 ] ),
  Transformation( [ 2, 5, 4, 5, 1 ] ),
  Transformation( [ 3, 1, 5, 1, 2 ] ),
  Transformation( [ 3, 5, 5, 1, 2 ] ),
  Transformation( [ 4, 1, 1, 2, 3 ] ),
  Transformation( [ 4, 2, 1, 2, 3 ] ),
  Transformation( [ 5, 2, 2, 3, 4 ] ),
  Transformation( [ 5, 3, 2, 3, 4 ] ) ]
```

7.3.10 IsDigraphHomomorphism

▷ IsDigraphHomomorphism(*src*, *ran*, *x*) (operation)

▷ IsDigraphEpimorphism(*src*, *ran*, *x*) (operation)

▷ IsDigraphMonomorphism(*src*, *ran*, *x*) (operation)
▷ IsDigraphEndomorphism(*digraph*, *x*) (operation)

Returns: true or false.

IsDigraphHomomorphism returns true if the permutation or transformation *x* is a homomorphism from the digraph *src* to the digraph *ran*.

IsDigraphEpimorphism returns true if the permutation or transformation *x* is a surjective homomorphism from the digraph *src* to the digraph *ran*.

IsDigraphMonomorphism returns true if the permutation or transformation *x* is an injective homomorphism from the digraph *src* to the digraph *ran*.

IsDigraphEndomorphism returns true if the permutation or transformation *x* is an endomorphism of the digraph *digraph*.

A permutation or transformation *x* is a *homomorphism* from a digraph *src* to a digraph *ran* if the following hold:

- [u ^ x, v ^ x] is an edge of *ran* whenever [u, v] is an edge of *src*; and
- *x* fixes every i which is not a vertex of *src*.

See also GeneratorsOfEndomorphismMonoid (7.3.12).

Example

```
gap> src := Digraph([[1], [1, 2], [1, 3]]);
<digraph with 3 vertices, 5 edges>
gap> ran := Digraph([[1], [1, 2]]);
<digraph with 2 vertices, 3 edges>
gap> IsDigraphHomomorphism(src, ran, Transformation([1, 2, 2]));
true
gap> IsDigraphHomomorphism(src, ran, Transformation([2, 1, 2]));
false
gap> IsDigraphHomomorphism(src, ran, Transformation([3, 3, 3]));
false
gap> IsDigraphHomomorphism(src, src, Transformation([3, 3, 3]));
true
gap> IsDigraphEndomorphism(src, Transformation([3, 3, 3]));
true
gap> IsDigraphEpimorphism(src, ran, Transformation([3, 3, 3]));
false
gap> IsDigraphMonomorphism(src, ran, Transformation([1, 2, 2]));
false
gap> IsDigraphEpimorphism(src, ran, Transformation([1, 2, 2]));
true
gap> IsDigraphMonomorphism(ran, src, ());
true
```

7.3.11 IsDigraphEmbedding

▷ IsDigraphEmbedding(*src*, *ran*, *x*) (operation)

Returns: true or false.

IsDigraphEmbedding returns true if the permutation or transformation *x* is a embedding of the digraph *src* into the digraph *ran*.

A permutation or transformation *x* is a *embedding* of a digraph *src* into a digraph *ran* if *x* is a monomorphism from *src* to *ran* and the inverse of *x* is a monomorphism from the subdigraph of *ran* induced by the image of *x* to *src*. See also IsDigraphHomomorphism (7.3.10).

Example

```
gap> src := Digraph([[1], [1, 2]]);
<digraph with 2 vertices, 3 edges>
gap> ran := Digraph([[1], [1, 2], [1, 3]]);
<digraph with 3 vertices, 5 edges>
gap> IsDigraphMonomorphism(src, ran, ());
true
gap> IsDigraphEmbedding(src, ran, ());
true
gap> ran := Digraph([[1, 2], [1, 2], [1, 3]]);
<digraph with 3 vertices, 6 edges>
gap> IsDigraphMonomorphism(src, ran, IdentityTransformation);
true
gap> IsDigraphEmbedding(src, ran, IdentityTransformation);
false
```

7.3.12 GeneratorsOfEndomorphismMonoid

▷ GeneratorsOfEndomorphismMonoid(*digraph[, colors][, limit]*) (function)
▷ GeneratorsOfEndomorphismMonoidAttr(*digraph*) (attribute)

Returns: A list of transformations.

An endomorphism of *digraph* is a homomorphism DigraphHomomorphism (7.3.2) from *digraph* back to itself. GeneratorsOfEndomorphismMonoid, called with a single argument, returns a generating set for the monoid of all endomorphisms of *digraph*.

If the *colors* argument is specified, then GeneratorsOfEndomorphismMonoid will return a generating set for the monoid of endomorphisms which respect the given colouring. The colouring *colors* can be in one of two forms:

- A list of positive integers of size the number of vertices of *digraph*, where *colors*[i] is the colour of vertex i.
- A list of lists, such that *colors*[i] is a list of all vertices with colour i.

If the *limit* argument is specified, then it will return only the first *limit* homomorphisms, where *limit* must be a positive integer or infinity.

Example

```
gap> gr := Digraph(List([1 .. 3], x -> [1 .. 3]));;
gap> GeneratorsOfEndomorphismMonoid(gr);
[ Transformation( [ 1, 3, 2 ] ), Transformation( [ 2, 1 ] ),
  IdentityTransformation, Transformation( [ 1, 2, 1 ] ),
  Transformation( [ 1, 2, 2 ] ), Transformation( [ 1, 1, 2 ] ),
  Transformation( [ 1, 1, 1 ] ) ]
gap> GeneratorsOfEndomorphismMonoid(gr, 3);
[ Transformation( [ 1, 3, 2 ] ), Transformation( [ 2, 1 ] ),
  IdentityTransformation ]
gap> gr := CompleteDigraph(3);;
gap> GeneratorsOfEndomorphismMonoid(gr);
```

```
  [ Transformation( [ 1, 3, 2 ] ), Transformation( [ 2, 1 ] ),
    IdentityTransformation ]
gap> GeneratorsOfEndomorphismMonoid(gr, [1, 2, 2]);
[ Transformation( [ 1, 3, 2 ] ), IdentityTransformation ]
gap> GeneratorsOfEndomorphismMonoid(gr, [[1], [2, 3]]);
[ Transformation( [ 1, 3, 2 ] ), IdentityTransformation ]
```

7.3.13 DigraphColouring (for a digraph and a number of colours)

▷ DigraphColouring(*digraph*, *n*) (operation)
▷ DigraphColoring(*digraph*, *n*) (operation)

Returns: A transformation, or fail.

A *proper colouring* of a digraph is a labelling of its vertices in such a way that adjacent vertices have different labels. A *proper n-colouring* is a proper colouring that uses exactly n colours. Equivalently, a proper (n-)colouring of a digraph can be defined to be a DigraphEpimorphism (7.3.6) from a digraph onto the complete digraph (with n vertices); see CompleteDigraph (3.5.2). Note that a digraph with loops (DigraphHasLoops (6.1.1)) does not have a proper n-colouring for any value n.

If *digraph* is a digraph and *n* is a non-negative integer, then DigraphColouring(*digraph*, *n*) returns an epimorphism from *digraph* onto the complete digraph with *n* vertices if one exists, else it returns fail.

See also DigraphGreedyColouring (7.3.14) and

Note that a digraph with at least two vertices has a 2-colouring if and only if it is bipartite, see IsBipartiteDigraph (6.1.3).

Example

```
gap> DigraphColouring(CompleteDigraph(5), 4);
fail
gap> DigraphColouring(ChainDigraph(10), 1);
fail
gap> gr := ChainDigraph(10);;
gap> t := DigraphColouring(gr, 2);
Transformation( [ 1, 2, 1, 2, 1, 2, 1, 2, 1, 2 ] )
gap> ForAll(DigraphEdges(gr), e -> e[1] ^ t <> e[2] ^ t);
true
gap> DigraphGreedyColouring(gr);
Transformation( [ 2, 1, 2, 1, 2, 1, 2, 1, 2, 1 ] )
```

7.3.14 DigraphGreedyColouring (for a digraph and vertex order)

▷ DigraphGreedyColouring(*digraph*, *order*) (operation)
▷ DigraphGreedyColouring(*digraph*, *func*) (operation)
▷ DigraphGreedyColouring(*digraph*) (attribute)

Returns: A transformation, or fail.

A *proper colouring* of a digraph is a labelling of its vertices in such a way that adjacent vertices have different labels. Note that a digraph with loops (DigraphHasLoops (6.1.1)) does not have any proper colouring.

If *digraph* is a digraph and *order* is a dense list consisting of all of the vertices of *digraph* (in any order), then DigraphGreedyColouring uses a greedy algorithm with the specified order to obtain some proper colouring of *digraph*, which may not use the minimal number of colours.

If *digraph* is a digraph and *func* is a function whose argument is a digraph, and that returns a dense list *order*, then DigraphGreedyColouring(*digraph*, *func*) returns DigraphGreedyColouring(*digraph*, *func*(*digraph*)).

If the optional second argument (either a list or a function), is not specified, then DigraphWelshPowellOrder (7.3.15) is used by default.

See also DigraphColouring (7.3.13).

Example

```
gap> DigraphGreedyColouring(ChainDigraph(10));
Transformation( [ 2, 1, 2, 1, 2, 1, 2, 1, 2, 1 ] )
gap> DigraphGreedyColouring(ChainDigraph(10), [1 .. 10]);
Transformation( [ 1, 2, 1, 2, 1, 2, 1, 2, 1, 2 ] )
```

7.3.15 DigraphWelshPowellOrder

▷ DigraphWelshPowellOrder(*digraph*) (attribute)

Returns: A list of the vertices.

DigraphWelshPowellOrder returns a list of all of the vertices of the digraph *digraph* ordered according to the sum of the number of out- and in-neighbours, from highest to lowest.

Example

```
gap> DigraphWelshPowellOrder(Digraph([[4], [9], [9], [],
>                                     [4, 6, 9], [1], [], [],
>                                     [4, 5], [4, 5]]));
[ 5, 9, 4, 1, 6, 10, 2, 3, 7, 8 ]
```

7.3.16 ChromaticNumber

▷ ChromaticNumber(*digraph*) (attribute)

Returns: A non-negative integer.

A *proper colouring* of a digraph is a labelling of its vertices in such a way that adjacent vertices have different labels. Equivalently, a proper digraph colouring can be defined to be a DigraphEpimorphism (7.3.6) from a digraph onto a complete digraph.

If *digraph* is a digraph without loops (see DigraphHasLoops (6.1.1), then ChromaticNumber returns the least non-negative integer n such that there is a proper colouring of *digraph* with n colours. In other words, for a digraph with at least one vertex, ChromaticNumber returns the least number n such that DigraphColouring(*digraph*, n) does not return fail. See DigraphColouring (7.3.13).

Example

```
gap> ChromaticNumber(NullDigraph(10));
1
gap> ChromaticNumber(CompleteDigraph(10));
10
gap> ChromaticNumber(CompleteBipartiteDigraph(5, 5));
2
gap> ChromaticNumber(Digraph([[], [3], [5], [2, 3], [4]]));
3
gap> ChromaticNumber(NullDigraph(0));
0
```

Chapter 8

Finding cliques and independent sets

In Digraphs, a *clique* of a digraph is a set of mutually adjacent vertices of the digraph, and an *independent set* is a set of mutually non-adjacent vertices of the digraph. A *maximal clique* is a clique which is not properly contained in another clique, and a *maximal independent set* is an independent set which is not properly contained in another independent set. Using this definition in Digraphs, cliques and independent sets are both permitted, but not required, to contain vertices at which there is a loop. Another name for a clique is a *complete subgraph*.

Digraphs provides extensive functionality for computing cliques and independent sets of a digraph, whether maximal or not. The fundamental algorithm used in most of the methods in Digraphs to calculate cliques and independent sets is a version of the Bron-Kerbosch algorithm. Calculating the cliques and independent sets of a digraph is a well-known and hard problem, and searching for cliques or independent sets in a digraph can be very length, even for a digraph with a small number of vertices. Digraphs uses several strategies to increase the performance of these calculations.

From the definition of cliques and independent sets, it follows that the presence of loops and multiple edges in a digraph is irrelevant to the existence of cliques and independent sets in the digraph. See `DigraphHasLoops` (6.1.1) and `IsMultiDigraph` (6.1.8) for more information about these properties. Therefore given a digraph *`digraph`*, the cliques and independent sets of *`digraph`* are equal to the cliques and independent sets of the digraph:

- `DigraphRemoveLoops(DigraphRemoveAllMultipleEdges(`*`digraph`*`))`.

See `DigraphRemoveLoops` (3.3.23) and `DigraphRemoveAllMultipleEdges` (3.3.24) for more information about these attributes. Furthermore, the cliques of this digraph are equal to the cliques of the digraph formed by removing any edge `[u,v]` for which the corresponding reverse edge `[v,u]` is not present. Therefore, overall, the cliques of *`digraph`* are equal to the cliques of the symmetric digraph:

- `MaximalSymmetricSubdigraphWithoutLoops(`*`digraph`*`)`.

See `MaximalSymmetricSubdigraphWithoutLoops` (3.3.4) for more information about this attribute. The `AutomorphismGroup` (7.2.2) of this symmetric digraph contains the automorphism group of *`digraph`* as a subgroup. By performing the search for maximal cliques with the help of this larger automorphism group to reduce the search space, the computation time may be reduced. The functions and attributes which return representatives of cliques of *`digraph`* will return orbit representatives of cliques under the action of the automorphism group of the *maximal symmetric subdigraph without loops* on sets of vertices.

The independent sets of a digraph are equal to the independent sets of the DigraphSymmetricClosure (3.3.10). Therefore, overall, the independent sets of *digraph* are equal to the independent sets of the symmetric digraph:

- DigraphSymmetricClosure(DigraphRemoveLoops(DigraphRemoveAllMultipleEdges(*digraph*))).

Again, the automorphism group of this symmetric digraph contains the automorphism group of *digraph*. Since a search for independent sets is equal to a search for cliques in the DigraphDual (3.3.9), the methods used in Digraphs usually transform a search for independent sets into a search for cliques, as described above. The functions and attributes which return representatives of independent sets of *digraph* will return orbit representatives of independent sets under the action of the automorphism group of the *symmetric closure* of the digraph formed by removing loops and multiple edges.

Please note that in Digraphs, cliques and indepedent sets are not required to be maximal. Some authors use the word clique to mean *maximal* clique, and some authors use the phrase independent set to mean *maximal* independent set, but please note that Digraphs does not use this definition.

8.1 Finding cliques

8.1.1 IsClique

▷ IsClique(*digraph*, *l*) (operation)
▷ IsMaximalClique(*digraph*, *l*) (operation)

Returns: true or false.

If *digraph* is a digraph and *l* is a duplicate-free list of vertices of *digraph*, then IsClique(*digraph*,*l*) returns true if *l* is a *clique* of *digraph* and false if it is not. Similarly, IsMaximalClique(*digraph*,*l*) returns true if *l* is a *maximal clique* of *digraph* and false if it is not.

A *clique* of a digraph is a set of mutually adjacent vertices of the digraph. A *maximal clique* is a clique which is not properly contained in another clique. A clique is permitted, but not required, to contain vertices at which there is a loop.

Example

```
gap> gr := CompleteDigraph(4);;
gap> IsClique(gr, [1, 3, 2]);
true
gap> IsMaximalClique(gr, [1, 3, 2]);
false
gap> IsMaximalClique(gr, DigraphVertices(gr));
true
gap> gr := Digraph([[1, 2, 4, 4], [1, 3, 4], [2, 1], [1, 2]]);
<multidigraph with 4 vertices, 11 edges>
gap> IsClique(gr, [2, 3, 4]);
false
gap> IsMaximalClique(gr, [1, 2, 4]);
true
```

8.1.2 CliquesFinder

▷ CliquesFinder(*digraph, hook, user_param, limit, include, exclude, max, size, reps*) (function)

Returns: The argument *user_param*.

This function finds cliques of the digraph *digraph* subject to the conditions imposed by the other arguments as described below. Note that a clique is represented by a list of the vertices which it contains.

Let G denote the automorphism group of the maximal symmetric subdigraph of *digraph* without loops (see AutomorphismGroup (7.2.2) and MaximalSymmetricSubdigraphWithoutLoops (3.3.4)).

hook

This argument should be a function or fail.

If *hook* is a function, then it should have two arguments *user_param* (see below) and a clique c. The function *hook*(*user_param*, c) is called every time a new clique c is found by CliquesFinder.

If *hook* is fail, then a default function is used which simply adds every new clique found by CliquesFinder to *user_param*, which must be a list in this case.

user_param

If *hook* is a function, then *user_param* can be any GAP object. The object *user_param* is used as the first argument for the function *hook*. For example, *user_param* might be a list, and *hook*(*user_param*, c) might add the size of the clique c to the list *user_param*.

If the value of *hook* is fail, then the value of *user_param* must be a list.

limit

This argument should be a positive integer or infinity. CliquesFinder will return after it has found *limit* cliques or the search is complete.

include **and** *exclude*

These arguments should each be a (possibly empty) duplicate-free list of vertices of *digraph* (i.e. positive integers less than the number of vertices of *digraph*).

CliquesFinder will only look for cliques containing all of the vertices in *include* and containing none of the vertices in *exclude*.

Note that the search may be much more efficient if each of these lists is invariant under the action of G on sets of vertices.

max This argument should be true or false. If *max* is true then CliquesFinder will only search for *maximal* cliques. If max is false then non-maximal cliques may be found.

size

This argument should be fail or a positive integer. If *size* is a positive integer then CliquesFinder will only search for cliques which contain precisely *size* vertices. If *size* is fail then cliques of any size may be found.

reps

This argument should be true or false.

If *reps* is true then the arguments *include* and *exclude* are each required to be invariant under the action of G on sets of vertices. In this case, CliquesFinder will find representatives of the orbits of the desired cliques under the action of G, *although representatives may be returned which are in the same orbit*. If *reps* is false then CliquesFinder will not take this into consideration.

For a digraph such that G is non-trivial, the search for clique representatives can be much more efficient than the search for all cliques.

This function uses a version of the Bron-Kerbosch algorithm.

Example

```
gap> gr := CompleteDigraph(5);
<digraph with 5 vertices, 20 edges>
gap> user_param := [];;
gap> f := function(a, b)  # Calculate size of clique
>   AddSet(user_param, Size(b));
> end;;
gap> CliquesFinder(gr, f, user_param, infinity, [], [], false, fail,
>                  true);
[ 1, 2, 3, 4, 5 ]
gap> CliquesFinder(gr, fail, [], 5, [2, 4], [3], false, fail, false);
[ [ 2, 4 ], [ 1, 2, 4 ], [ 2, 4, 5 ], [ 1, 2, 4, 5 ] ]
gap> CliquesFinder(gr, fail, [], 2, [2, 4], [3], false, fail, false);
[ [ 2, 4 ], [ 1, 2, 4 ] ]
gap> CliquesFinder(gr, fail, [], infinity, [], [], true, 5, false);
[ [ 1, 2, 3, 4, 5 ] ]
gap> CliquesFinder(gr, fail, [], infinity, [1, 3], [], false, 3, false);
[ [ 1, 2, 3 ], [ 1, 3, 4 ], [ 1, 3, 5 ] ]
gap> CliquesFinder(gr, fail, [], infinity, [1, 3], [], true, 3, false);
[  ]
```

8.1.3 DigraphClique

▷ DigraphClique(*digraph[, include[, exclude[, size]]]*) (function)

▷ DigraphMaximalClique(*digraph[, include[, exclude[, size]]]*) (function)

Returns: A list of positive integers, or fail.

If *digraph* is a digraph, then these functions returns a clique of *digraph* if one exists which satisfies the arguments, else it returns fail. A clique is defined by the set of vertices which it contains; see IsClique (8.1.1) and IsMaximalClique (8.1.1).

The optional arguments *include* and *exclude* must each be a (possibly empty) duplicate-free list of vertices of *digraph*, and the optional argument *size* must be a positive integer. By default, *include* and *exclude* are empty. These functions will search for a clique of *digraph* which includes the vertices of *include* and which does not include any vertices in *exclude*; if the argument *size* is supplied, then additionally the clique will be required to contain precisely *size* vertices.

If *include* is not a clique, then these functions return fail. Otherwise, the functions behave in the following way, depending on the number of arguments:

One or two arguments

If one or two arguments are supplied, then DigraphClique and DigraphMaximalClique greedily enlarge the clique *include* until it can not continue. The result is guaranteed

to be a maximal clique. This may or may not return an answer more quickly than using DigraphMaximalCliques (8.1.4). with a limit of 1.

Three arguments

If three arguments are supplied, then DigraphClique greedily enlarges the clique *include* until it can not continue, although this clique may not be maximal.

Given three arguments, DigraphMaximalClique returns the maximal clique returned by DigraphMaximalCliques(*digraph*, *include*, *exclude*, 1) if one exists, else fail.

Four arguments

If four arguments are supplied, then DigraphClique returns the clique returned by DigraphCliques(*digraph*, *include*, *exclude*, 1, *size*) if one exists, else fail. This clique may not be maximal.

Given four arguments, DigraphMaximalClique returns the maximal clique returned by DigraphMaximalCliques(*digraph*, *include*, *exclude*, 1, *size*) if one exists, else fail.

Example

```
gap> gr := Digraph([[2, 3, 4], [1, 3], [1, 2], [1, 5], []]);
<digraph with 5 vertices, 9 edges>
gap> IsSymmetricDigraph(gr);
false
gap> DigraphClique(gr);
[ 5 ]
gap> DigraphMaximalClique(gr);
[ 5 ]
gap> DigraphClique(gr, [1, 2]);
[ 1, 2, 3 ]
gap> DigraphMaximalClique(gr, [1, 3]);
[ 1, 3, 2 ]
gap> DigraphClique(gr, [1], [2]);
[ 1, 4 ]
gap> DigraphMaximalClique(gr, [1], [3, 4]);
fail
gap> DigraphClique(gr, [1, 5]);
fail
gap> DigraphClique(gr, [], [], 2);
[ 1, 2 ]
```

8.1.4 DigraphMaximalCliques

▷ DigraphMaximalCliques(*digraph[, include[, exclude[, limit[, size]]]]*) (function)
▷ DigraphMaximalCliquesReps(*digraph[, include[, exclude[, limit[, size]]]]*) (function)
▷ DigraphCliques(*digraph[, include[, exclude[, limit[, size]]]]*) (function)
▷ DigraphCliquesReps(*digraph[, include[, exclude[, limit[, size]]]]*) (function)
▷ DigraphMaximalCliquesAttr(*digraph*) (attribute)
▷ DigraphMaximalCliquesRepsAttr(*digraph*) (attribute)

Returns: A list of lists of positive integers.

If *digraph* is digraph, then these functions and attributes use CliquesFinder (8.1.2) to return cliques of *digraph*. A clique is defined by the set of vertices which it contains; see IsClique (8.1.1) and IsMaximalClique (8.1.1).

The optional arguments *include* and *exclude* must each be a (possibly empty) list of vertices of *digraph*, the optional argument *limit* must be either a positive integer or infinity, and the optional argument *size* must be a positive integer. If not specified, then *include* and *exclude* are empty lists, and *limit* is infinity.

The functions will return as many suitable cliques as possible, up to the number *limit*. These functions will find cliques which contain all of the vertices of *include* and which do not contain any of the vertices of *exclude*. The argument *size* restricts the search to those cliques which contain precisely *size* vertices. If the function or attribute has Maximal in its name, then only maximal cliques will be returned; otherwise non-maximal cliques may be returned.

Let G denote the automorphism group of maximal symmetric subdigraph of *digraph* without loops (see AutomorphismGroup (7.2.2) and MaximalSymmetricSubdigraphWithoutLoops (3.3.4)).

Distinct cliques

DigraphMaximalCliques and DigraphCliques each return a duplicate-free list of at most *limit* cliques of *digraph* which satisfy the arguments.

The computation may be significantly faster if *include* and *exclude* are invariant under the action of G on sets of vertices.

Orbit representatives of cliques

To use DigraphMaximalCliquesReps or DigraphCliquesReps, the arguments *include* and *exclude* must each be invariant under the action of G on sets of vertices.

If this is the case, then DigraphMaximalCliquesReps and DigraphCliquesReps each return a duplicate-free list of at most *limit* orbits representatives (under the action of G on sets vertices) of cliques of *digraph* which satisfy the arguments.

The representatives are not guaranteed to be in distinct orbits. However, if *lim* is not specified, or fewer than *lim* results are returned, then there will be at least one representative from each orbit of maximal cliques.

Example

```
gap> gr := Digraph([
> [2, 3], [1, 3], [1, 2, 4], [3, 5, 6], [4, 6], [4, 5]]);
<digraph with 6 vertices, 14 edges>
gap> IsSymmetricDigraph(gr);
true
gap> G := AutomorphismGroup(gr);
Group([ (5,6), (1,2), (1,5)(2,6)(3,4) ])
gap> DigraphMaximalCliques(gr);
[ [ 1, 2, 3 ], [ 4, 5, 6 ], [ 3, 4 ] ]
gap> DigraphMaximalCliquesReps(gr);
[ [ 1, 2, 3 ], [ 3, 4 ] ]
gap> Orbit(G, [1, 2, 3], OnSets);
[ [ 1, 2, 3 ], [ 4, 5, 6 ] ]
gap> Orbit(G, [3, 4], OnSets);
[ [ 3, 4 ] ]
gap> DigraphMaximalCliquesReps(gr, [3, 4], [], 1);
```

```
[ [ 3, 4 ] ]
gap> DigraphMaximalCliques(gr, [1, 2], [5, 6], 1, 2);
[  ]
gap> DigraphCliques(gr, [1], [5, 6], infinity, 2);
[ [ 1, 2 ], [ 1, 3 ] ]
```

8.1.5 CliqueNumber

▷ `CliqueNumber(`*digraph*`)` (attribute)

Returns: A non-negative integer.

If *digraph* is a digraph, then `CliqueNumber(`*digraph*`)` returns the largest integer `n` such that *digraph* contains a clique with `n` vertices as an induced subdigraph.

A *clique* of a digraph is a set of mutually adjacent vertices of the digraph. Loops and multiple edges are ignored for the purpose of determining the clique number of a digraph.

Example

```
gap> gr := CompleteDigraph(4);;
gap> CliqueNumber(gr);
4
gap> gr := Digraph([[1, 2, 4, 4], [1, 3, 4], [2, 1], [1, 2]]);
<multidigraph with 4 vertices, 11 edges>
gap> CliqueNumber(gr);
3
```

8.2 Finding independent sets

8.2.1 IsIndependentSet

▷ `IsIndependentSet(`*digraph*`, `*l*`)` (operation)

▷ `IsMaximalIndependentSet(`*digraph*`, `*l*`)` (operation)

Returns: `true` or `false`.

If *digraph* is a digraph and *l* is a duplicate-free list of vertices of *digraph*, then `IsIndependentSet(`*digraph*`,`*l*`)` returns `true` if *l* is an *independent set* of *digraph* and `false` if it is not. Similarly, `IsMaximalIndependentSet(`*digraph*`,`*l*`)` returns `true` if *l* is a *maximal independent set* of *digraph* and `false` if it is not.

An *independent set* of a digraph is a set of mutually non-adjacent vertices of the digraph. A *maximal independent set* is an independent set which is not properly contained in another independent set. An independent set is permitted, but not required, to contain vertices at which there is a loop.

Example

```
gap> gr := CycleDigraph(4);;
gap> IsIndependentSet(gr, [1]);
true
gap> IsMaximalIndependentSet(gr, [1]);
false
gap> IsIndependentSet(gr, [1, 4, 3]);
false
gap> IsIndependentSet(gr, [2, 4]);
true
gap> IsMaximalIndependentSet(gr, [2, 4]);
true
```

8.2.2 DigraphIndependentSet

▷ DigraphIndependentSet(*digraph[, include[, exclude[, size]]]*) (function)
▷ DigraphMaximalIndependentSet(*digraph[, include[, exclude[, size]]]*) (function)

Returns: A lists of positive integers, or fail.

If *digraph* is a digraph, then these functions returns a independent set of *digraph* if one exists which satisfies the arguments, else it returns fail. A independent set is defined by the set of vertices which it contains; see IsIndependentSet (8.2.1) and IsMaximalIndependentSet (8.2.1).

The optional arguments *include* and *exclude* must each be a (possibly empty) duplicate-free list of vertices of *digraph*, and the optional argument *size* must be a positive integer. By default, *include* and *exclude* are empty. These functions will search for a independent set of *digraph* which includes the vertices of *include* and which does not include any vertices in *exclude*; if the argument *size* is supplied, then additionally the independent set will be required to contain precisely *size* vertices.

If *include* is not a independent set, then these functions return fail. Otherwise, the functions behave in the following way, depending on the number of arguments:

One or two arguments

If one or two arguments are supplied, then DigraphIndependentSet and DigraphMaximalIndependentSet greedily enlarge the independent set *include* until it can not continue. The result is guaranteed to be a maximal independent set. This may or may not return an answer more quickly than using DigraphMaximalIndependentSets (8.2.3). with a limit of 1.

Three arguments

If three arguments are supplied, then DigraphIndependentSet greedily enlarges the independent set *include* until it can not continue, although this independent set may not be maximal.

Given three arguments, DigraphMaximalIndependentSet returns the maximal independent set returned by DigraphMaximalIndependentSets(*digraph*, *include*, *exclude*, 1) if one exists, else fail.

Four arguments

If four arguments are supplied, then DigraphIndependentSet returns the independent set returned by DigraphIndependentSets(*digraph*, *include*, *exclude*, 1, *size*) if one exists, else fail. This independent set may not be maximal.

Given four arguments, DigraphMaximalIndependentSet returns the maximal independent set returned by DigraphMaximalIndependentSets(*digraph*, *include*, *exclude*, 1, *size*) if one exists, else fail.

Example

```
gap> gr := ChainDigraph(6);
<digraph with 6 vertices, 5 edges>
gap> DigraphIndependentSet(gr);
[ 6, 4, 2 ]
gap> DigraphMaximalIndependentSet(gr);
[ 6, 4, 2 ]
gap> DigraphIndependentSet(gr, [2, 4]);
[ 2, 4, 6 ]
gap> DigraphMaximalIndependentSet(gr, [1, 3]);
[ 1, 3, 6 ]
```

```
gap> DigraphIndependentSet(gr, [2, 4], [6]);
[ 2, 4 ]
gap> DigraphMaximalIndependentSet(gr, [2, 4], [6]);
fail
gap> DigraphIndependentSet(gr, [1], [], 2);
[ 1, 3 ]
gap> DigraphMaximalIndependentSet(gr, [1], [], 2);
fail
gap> DigraphMaximalIndependentSet(gr, [1], [], 3);
[ 1, 3, 5 ]
```

8.2.3 DigraphMaximalIndependentSets

▷ DigraphMaximalIndependentSets(*digraph[, include[, exclude[, limit[, size]]]]*) (function)

▷ DigraphMaximalIndependentSetsReps(*digraph[, include[, exclude[, limit[, size]]]]*) (function)

▷ DigraphIndependentSets(*digraph[, include[, exclude[, limit[, size]]]]*) (function)

▷ DigraphIndependentSetsReps(*digraph[, include[, exclude[, limit[, size]]]]*) (function)

▷ DigraphMaximalIndependentSetsAttr(*digraph*) (attribute)

▷ DigraphMaximalIndependentSetsRepsAttr(*digraph*) (attribute)

Returns: A list of lists of positive integers.

If *digraph* is digraph, then these functions and attributes use CliquesFinder (8.1.2) to return independent sets of *digraph*. An independent set is defined by the set of vertices which it contains; see IsMaximalIndependentSet (8.2.1) and IsIndependentSet (8.2.1).

The optional arguments *include* and *exclude* must each be a (possibly empty) list of vertices of *digraph*, the optional argument *limit* must be either a positive integer or infinity, and the optional argument *size* must be a positive integer. If not specified, then *include* and *exclude* are empty lists, and *limit* is infinity.

The functions will return as many suitable independent sets as possible, up to the number *limit*. These functions will find independent sets which contain all of the vertices of *include* and which do not contain any of the vertices of *exclude* The argument *size* restricts the search to those cliques which contain precisely *size* vertices. If the function or attribute has Maximal in its name, then only maximal independent sets will be returned; otherwise non-maximal independent sets may be returned.

Let G denote the AutomorphismGroup (7.2.2) of the DigraphSymmetricClosure (3.3.10) of the digraph formed from *digraph* by removing loops and ignoring the multiplicity of edges.

Distinct independent sets

DigraphMaximalIndependentSets and DigraphIndependentSets each return a duplicate-free list of at most *limit* independent sets of *digraph* which satisfy the arguments.

The computation may be significantly faster if *include* and *exclude* are invariant under the action of G on sets of vertices.

Representatives of distinct orbits of independent sets

To use DigraphMaximalIndependentSetsReps or DigraphIndependentSetsReps, the arguments *include* and *exclude* must each be invariant under the action of G on sets of vertices.

If this is the case, then DigraphMaximalIndependentSetsReps and DigraphIndependentSetsReps each return a list of at most *limit* orbits representatives (under the action of G on sets of vertices) of independent sets of *digraph* which satisfy the arguments.

The representatives are not guaranteed to be in distinct orbits. However, if *lim* is not specified, or fewer than *lim* results are returned, then there will be at least one representative from each orbit of maximal independent sets.

Example

```
gap> gr := CycleDigraph(5);
<digraph with 5 vertices, 5 edges>
gap> DigraphMaximalIndependentSetsReps(gr);
[ [ 1, 3 ] ]
gap> DigraphIndependentSetsReps(gr);
[ [ 1 ], [ 1, 3 ] ]
gap> Set(DigraphMaximalIndependentSets(gr));
[ [ 1, 3 ], [ 1, 4 ], [ 2, 4 ], [ 2, 5 ], [ 3, 5 ] ]
gap> DigraphMaximalIndependentSets(gr, [1]);
[ [ 1, 3 ], [ 1, 4 ] ]
gap> DigraphIndependentSets(gr, [], [4, 5]);
[ [ 1 ], [ 2 ], [ 3 ], [ 1, 3 ] ]
gap> DigraphIndependentSets(gr, [], [4, 5], 1, 2);
[ [ 1, 3 ] ]
```

Chapter 9

Visualising and IO

9.1 Visualising a digraph

9.1.1 Splash

▷ `Splash(str[, opts])` (function)

Returns: Nothing.

This function attempts to convert the string *str* into a pdf document and open this document, i.e. to splash it all over your monitor.

The string *str* must correspond to a valid `dot` or `LaTeX` text file and you must have have `GraphViz` and `pdflatex` installed on your computer. For details about these file formats, see `http://www.latex-project.org` and `http://www.graphviz.org`.

This function is provided to allow convenient, immediate viewing of the pictures produced by the function `DotDigraph` (9.1.2).

The optional second argument *opts* should be a record with components corresponding to various options, given below.

path this should be a string representing the path to the directory where you want `Splash` to do its work. The default value of this option is `"~/"`.

directory
this should be a string representing the name of the directory in `path` where you want `Splash` to do its work. This function will create this directory if does not already exist.

The default value of this option is `"tmp.viz"` if the option `path` is present, and the result of `DirectoryTemporary` (**Reference: DirectoryTemporary**) is used otherwise.

filename
this should be a string representing the name of the file where *str* will be written. The default value of this option is `"vizpicture"`.

viewer
this should be a string representing the name of the program which should open the files produced by `GraphViz` or `pdflatex`.

type this option can be used to specify that the string *str* contains a LaTeX or `dot` document. You can specify this option in *str* directly by making the first line `"%latex"` or `"//dot"`. There is no default value for this option, this option must be specified in *str* or in *opt.type*.

engine

this option can be used to specify the GraphViz engine to use to render a `dot` document. The valid choices are `"dot"`, `"neato"`, `"circo"`, `"twopi"`, `"fdp"`, `"sfdp"`, and `"patchwork"`. Please refer to the GraphViz documentation for details on these engines. The default value for this option is `"dot"`, and it must be specified in *`opt.engine`*.

filetype

this should be a string representing the type of file which `Splash` should produce. For LaTeX files, this option is ignored and the default value `"pdf"` is used.

This function was written by Attila Egri-Nagy and Manuel Delgado with some minor changes by J. D. Mitchell.

Example

```
gap> Splash(DotDigraph(RandomDigraph(4)));
```

9.1.2 DotDigraph

▷ `DotDigraph(`*`digraph`*`)` (attribute)
▷ `DotVertexLabelledDigraph(`*`digraph`*`)` (operation)

Returns: A string.

`DotDigraph` produces a graphical representation of the digraph *`digraph`*. Vertices are displayed as circles, numbered consistently with *`digraph`*. Edges are displayed as arrowed lines between vertices, with the arrowhead of each line pointing towards the range of the edge.

`DotVertexLabelledDigraph` differs from `DotDigraph` only in that the values in `DigraphVertexLabels` (5.1.9) are used to label the vertices in the produced picture rather than the numbers 1 to the number of vertices of the digraph.

The output is in `dot` format (also known as `GraphViz`) format. For details about this file format, and information about how to display or edit this format see `http://www.graphviz.org`.

The string returned by `DotDigraph` or `DotVertexLabelledDigraph` can be written to a file using the command `FileString` (**GAPDoc: FileString**).

Example

```
gap> adj := List([1 .. 4], x -> [1, 1, 1, 1]);
[ [ 1, 1, 1, 1 ], [ 1, 1, 1, 1 ], [ 1, 1, 1, 1 ], [ 1, 1, 1, 1 ] ]
gap> adj[1][3] := 0;
0
gap> gr := DigraphByAdjacencyMatrix(adj);
<digraph with 4 vertices, 15 edges>
gap> FileString("dot/k4.dot", DotDigraph(gr));
154
```

9.1.3 DotSymmetricDigraph

▷ `DotSymmetricDigraph(`*`digraph`*`)` (attribute)

Returns: A string.

This function produces a graphical representation of the symmetric digraph *`digraph`*. `DotSymmetricDigraph` will return an error if *`digraph`* is not a symmetric digraph. See `IsSymmetricDigraph` (6.1.10).

Vertices are displayed as circles, numbered consistently with *digraph*. Since *digraph* is symmetric, for every non-loop edge there is a complementary edge with opposite source and range. DotSymmetricDigraph displays each pair of complementary edges as a single line between the relevant vertices, with no arrowhead.

The output is in dot format (also known as GraphViz) format. For details about this file format, and information about how to display or edit this format see http://www.graphviz.org.

The string returned by DotSymmetricDigraph can be written to a file using the command FileString (**GAPDoc: FileString**).

Example

```
gap> star := Digraph([[2, 2, 3, 4], [1, 1], [1], [1, 4]]);
<multidigraph with 4 vertices, 9 edges>
gap> IsSymmetricDigraph(star);
true
gap> FileString("dot/star.dot", DotSymmetricDigraph(gr));
83
```

9.1.4 DotPartialOrderDigraph

▷ DotPartialOrderDigraph(*digraph*) (attribute)

Returns: A string.

This function produces a graphical representation of a partial order digraph *digraph*. DotPartialOrderDigraph will return an error if *digraph* is not a partial order digraph. See IsPartialOrderDigraph (6.1.14).

Since *digraph* is a partial order, it is both reflexive and transitive. The output of DotPartialOrderDigraph is the DotDigraph (9.1.2) of the DigraphReflexiveTransitiveReduction (3.3.12) of *digraph*.

The output is in dot format (also known as GraphViz) format. For details about this file format, and information about how to display or edit this format see http://www.graphviz.org.

The string returned by DotPartialOrderDigraph can be written to a file using the command FileString (**GAPDoc: FileString**).

Example

```
gap> poset := Digraph([[1, 4], [2], [2, 3, 4], [4]);
gap> IsPartialOrderDigraph(gr);
true
gap> FileString("dot/poset.dot", DotPartialOrderDigraph(gr));
83
```

9.1.5 DotPreorderDigraph

▷ DotPreorderDigraph(*digraph*) (attribute)

▷ DotQuasiorderDigraph(*digraph*) (attribute)

Returns: A string.

This function produces a graphical representation of a preorder digraph *digraph*. DotPreorderDigraph will return an error if *digraph* is not a preorder digraph. See IsPreorderDigraph (6.1.13).

A preorder digraph is reflexive and transitive but in general it is not anti-symmetric and may have strongly connected components containing more than one vertex. The QuotientDigraph (3.3.7) *Q*

obtained by forming the quotient of *digraph* by the partition of its vertices into the strongly connected components satisfies IsPartialOrderDigraph (6.1.14). Thus every vertex of *Q* corresponds to a strongly connected component of *digraph*. The output of DotPreorderDigraph displays the DigraphReflexiveTransitiveReduction (3.3.12) of *Q* with vertices displayed as rounded rectangles labelled by all of the vertices of *digraph* in the corresponding strongly connected component.

The output is in dot format (also known as GraphViz) format. For details about this file format, and information about how to display or edit this format see http://www.graphviz.org.

The string returned by DotPreorderDigraph can be written to a file using the command FileString (**GAPDoc: FileString**).

Example

```
gap> preset := Digraph([[1, 2, 4, 5], [1, 2, 4, 5], [3, 4], [4], [1, 2, 4, 5]);
gap> IsPreorderDigraph(gr);
true
gap> FileString("dot/preset.dot", DotProrderDigraph(gr));
83
```

9.2 Reading and writing graphs to a file

This section describes different ways to store and read graphs from a file in the Digraphs package.

Graph6

Graph6 is a graph data format for storing undirected graphs with no multiple edges nor loops of size up to $2^{36}-1$ in printable chracters. The format consists of two parts. The first part uses one to eight bytes to store the number of vertices. And the second part is the upper half of the adjacency matrix converted into ASCII characters. For a more detail description see Graph6.

Sparse6

Sparse6 is a graph data format for storing undirected graphs with possibly multiple edges or loops. The maximal number of vertices allowed is $2^{36}-1$. The format consists of two parts. The first part uses one to eight bytes to store the number of vertices. And the second part only stores information about the edges. Therefore, the *Sparse6* format return a more compact encoding then *Graph6* for sparse graph, i.e. graphs where the number of edges is much less than the number of vertices squared. For a more detail description see Sparse6.

Digraph6

Digraph6 is a new format based on *Graph6* , but designed for digraphs. The entire adjacency matrix is stored, and therefore there is support for directed edges and single-vertex loops. However, multiple edges are not supported.

DiSparse6

DiSparse6 is a new format based on *Sparse6* , but designed for digraphs. In this format the list of edges is partitioned into inceasing and decreasing edges, depending whether the edge has its source bigger than the range. Then both sets of edges are written separetly in *Sparse6* format with a separation symbol in between.

9.2.1 DigraphFromGraph6String

▷ DigraphFromGraph6String(*str*) (operation)

▷ DigraphFromDigraph6String(*str*) (operation)

▷ DigraphFromSparse6String(*str*) (operation)
▷ DigraphFromDiSparse6String(*str*) (operation)

Returns: A digraph.

If *str* is a string encoding a graph in Graph6, Digraph6, Sparse6 or DiSparse6 format, then the corresponding function returns a digraph. In the case of either Graph6 or Sparse6, formats which do not support directed edges, this will be a digraph such that for every edge, the edge going in the opposite direction is also present.

Example

```
gap> DigraphFromGraph6String("?");
<digraph with 0 vertices, 0 edges>
gap> DigraphFromGraph6String("C]");
<digraph with 4 vertices, 8 edges>
gap> DigraphFromGraph6String("H?AAEM{");
<digraph with 9 vertices, 22 edges>
gap> DigraphFromDigraph6String("&?");
<digraph with 0 vertices, 0 edges>
gap> DigraphFromDigraph6String("&CQFG");
<digraph with 4 vertices, 6 edges>
gap> DigraphFromDigraph6String("&IM[SrKLc~lhesbU[F_");
<digraph with 10 vertices, 51 edges>
gap> DigraphFromDiSparse6String(".CaWBGA?b");
<multidigraph with 4 vertices, 9 edges>
```

9.2.2 Graph6String

▷ Graph6String(*digraph*) (operation)
▷ Digraph6String(*digraph*) (operation)
▷ Sparse6String(*digraph*) (operation)
▷ DiSparse6String(*digraph*) (operation)

Returns: A string.

These four functions return a highly compressed string fully describing the digraph *digraph*.

Graph6 and Digraph6 are formats best used on small, dense graphs, if applicable. For larger, sparse graphs use *Sparse6* and *Disparse6* (this latter also preserves multiple edges).

See WriteDigraphs (9.2.5).

Example

```
gap> gr := Digraph([[2, 3], [1], [1]]);
<digraph with 3 vertices, 4 edges>
gap> Sparse6String(gr);
":Bc"
gap> DiSparse6String(gr);
".Bc{f"
```

9.2.3 DigraphFile

▷ DigraphFile(*filename[, coder][, mode]*) (function)

Returns: An IO file object.

If *filename* is a string representing the name of a file, then DigraphFile returns an IO package file object for that file.

If the optional argument *coder* is specified and is a function which either encodes a digraph as a string, or decodes a string into a digraph, then this function will be used when reading or writing to the returned file object. If the optional argument *coder* is not specified, then the encoding of the digraphs in the returned file object must be specified in the the file extension. The file extension must be one of: `.g6`, `.s6`, `.d6`, `.ds6`, `.txt`, `.p`, or `.pickle`; more details of these file formats is given below.

If the optional argument *mode* is specified, then it must be one of: `"w"` (for write), `"a"` (for append), or `"r"` (for read). If *mode* is not specified, then `"r"` is used by default.

If *filename* ends in one of: `.gz`, `.bz2`, or `.xz`, then the digraphs which are read from, or written to, the returned file object are decompressed, or compressed, appropriately.

The file object returned by `DigraphFile` can be given as the first argument for either of the functions `ReadDigraphs` (9.2.4) or `WriteDigraphs` (9.2.5). The purpose of this is to reduce the overhead of recreating the file object inside the functions `ReadDigraphs` (9.2.4) or `WriteDigraphs` (9.2.5) when, for example, reading or writing many digraphs in a loop.

The currently supported file formats, and associated filename extensions, are:

graph6 (.g6)
: A standard and widely-used format for undirected graphs, with no support for loops or multiple edges. Only symmetric graphs are allowed – each edge is combined with its converse edge to produce a single undirected edge. This format is best used for "dense" graphs – those with many edges per vertex.

sparse6 (.s6)
: Unlike graph6, sparse6 has support for loops and multiple edges. However, its use is still limited to symmetric graphs. This format is better-suited to "sparse" graphs – those with few edges per vertex.

digraph6 (.d6)
: This format is based on graph6, but stores direction information - therefore is not limited to symmetric graphs. Loops are allowed, but multiple edges are not. Best compression with "dense" graphs.

disparse6 (.ds6)
: Any type of digraph can be encoded in disparse6: directions, loops, and multiple edges are all allowed. Similar to sparse6, this has the best compression rate with "sparse" graphs.

plain text (.txt)
: This is a human-readable format which stores graphs in the form `0 7 0 8 1 7 2 8 3 8 4 8 5 8 6 8` i.e. pairs of vertices describing edges in a graph. More specifically, the vertices making up one edge must be separated by a single space, and pairs of vertices must be separated by two spaces.

  See `ReadPlainTextDigraph` (9.2.12) for a more flexible way to store digraphs in a plain text file.

pickled (`.p` or `.pickle`)
: Digraphs are pickled using the IO package. This is particularly good when the `DigraphGroup` (7.2.9) is non-trivial.

Example

```
gap> filename := Concatenation(DIGRAPHS_Dir(), "/tst/out/man.d6.gz");;
gap> file := DigraphFile(filename, "w");;
```

```
gap> for i in [1 .. 10] do
> WriteDigraphs(file, Digraph([[1, 3], [2], [1, 2]]));
> od;
gap> IO_Close(file);;
gap> file := DigraphFile(filename, "r");;
gap> ReadDigraphs(file, 9);
<digraph with 3 vertices, 5 edges>
```

9.2.4 ReadDigraphs

▷ `ReadDigraphs(`*`filename[, decoder][, n]`*`)` (function)

Returns: A digraph, or a list of digraphs.

If *`filename`* is a string containing the name of a file containing encoded digraphs or an IO file object created using `DigraphFile` (9.2.3), then `ReadDigraphs` returns the digraphs encoded in the file as a list. Note that if *`filename`* is a compressed file, which has been compressed appropriately to give a filename extension of `.gz`, `.bz2`, or `.xz`, then `ReadDigraphs` can read *`filename`* without it first needing to be decompressed.

If the optional argument *`decoder`* is specified and is a function which decodes a string into a digraph, then `ReadDigraphs` will use *`decoder`* to decode the digraphs contained in *`filename`*.

If the optional argument *`n`* is specified, then `ReadDigraphs` returns the *`n`*th digraph encoded in the file *`filename`*.

If the optional argument *`decoder`* is not specified, then `ReadDigraphs` will deduce which decoder to use based on the filename extension of *`filename`* (after removing the compression-related filename extensions `.gz`, `.bz2`, and `.xz`). For example, if the filename extension is `.g6`, then `ReadDigraphs` will use the graph6 decoder `DigraphFromGraph6String` (9.2.1).

The currently supported file formats, and associated filename extensions, are:

graph6 (.g6)
A standard and widely-used format for undirected graphs, with no support for loops or multiple edges. Only symmetric graphs are allowed – each edge is combined with its converse edge to produce a single undirected edge. This format is best used for "dense" graphs – those with many edges per vertex.

sparse6 (.s6)
Unlike graph6, sparse6 has support for loops and multiple edges. However, its use is still limited to symmetric graphs. This format is better-suited to "sparse" graphs – those with few edges per vertex.

digraph6 (.d6)
This format is based on graph6, but stores direction information - therefore is not limited to symmetric graphs. Loops are allowed, but multiple edges are not. Best compression with "dense" graphs.

disparse6 (.ds6)
Any type of digraph can be encoded in disparse6: directions, loops, and multiple edges are all allowed. Similar to sparse6, this has the best compression rate with "sparse" graphs.

plain text (.txt)
This is a human-readable format which stores graphs in the form `0 7 0 8 1 7 2 8 3 8 4`

`8 5 8 6 8` i.e. pairs of vertices describing edges in a graph. More specifically, the vertices making up one edge must be separated by a single space, and pairs of vertices must be separated by two spaces.

See `ReadPlainTextDigraph` (9.2.12) for a more flexible way to store digraphs in a plain text file.

pickled (`.p` or `.pickle`)

Digraphs are pickled using the IO package. This is particularly good when the `DigraphGroup` (7.2.9) is non-trivial.

Example

```
gap> ReadDigraphs(
> Concatenation(DIGRAPHS_Dir(), "/data/graph5.g6.gz"), 10);
<digraph with 5 vertices, 8 edges>
gap> ReadDigraphs(
> Concatenation(DIGRAPHS_Dir(), "/data/graph5.g6.gz"), 17);
<digraph with 5 vertices, 12 edges>
gap> ReadDigraphs(
> Concatenation(DIGRAPHS_Dir(), "/data/tree9.4.txt"));
[ <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges>,
  <digraph with 9 vertices, 8 edges> ]
```

9.2.5 WriteDigraphs

▷ `WriteDigraphs(`*`filename, digraphs[, encoder][, mode]`*`)` (function)

If *`digraphs`* is a list of digraphs or a digraph and *`filename`* is a string or an IO file object created using `DigraphFile` (9.2.3), then `WriteDigraphs` writes the digraphs to the file represented by *`filename`*. If the supplied filename ends in one of the extensions `.gz`, `.bz2`, or `.xz`, then the file will be compressed appropriately. Excluding these extensions, if the file ends with an extension in the list below, the corresponding graph format will be used to encode it. If such an extension is not included, an appropriate format will be chosen intelligently, and an extension appended, to minimise file size.

For more verbose information on the progress of the function, set the info level of *`InfoDigraphs`* to 1 or higher, using `SetInfoLevel`.

The currently supported file formats are:

graph6 (.g6)

A standard and widely-used format for undirected graphs, with no support for loops or multiple

edges. Only symmetric graphs are allowed – each edge is combined with its converse edge to produce a single undirected edge. This format is best used for "dense" graphs – those with many edges per vertex.

sparse6 (.s6)

Unlike graph6, sparse6 has support for loops and multiple edges. However, its use is still limited to symmetric graphs. This format is better-suited to "sparse" graphs – those with few edges per vertex.

digraph6 (.d6)

This format is based on graph6, but stores direction information - therefore is not limited to symmetric graphs. Loops are allowed, but multiple edges are not. Best compression with "dense" graphs.

disparse6 (.ds6)

Any type of digraph can be encoded in disparse6: directions, loops, and multiple edges are all allowed. Similar to sparse6, this has the best compression rate with "sparse" graphs.

plain text (.txt)

This is a human-readable format which stores graphs in the form `0 7 0 8 1 7 2 8 3 8 4 8 5 8 6 8` i.e. pairs of vertices describing edges in a graph. More specifically, the vertices making up one edge must be separated by a single space, and pairs of vertices must be separated by two spaces.

See `ReadPlainTextDigraph` (9.2.12) for a more flexible way to store digraphs in a plain text file.

pickled (`.p` or `.pickle`)

Digraphs are pickled using the IO package. This is particularly good when the `DigraphGroup` (7.2.9) is non-trivial.

Example

```
gap> grs := [];;
gap> grs[1] := Digraph([]);
<digraph with 0 vertices, 0 edges>
gap> grs[2] := Digraph([[1, 3], [2], [1, 2]]);
<digraph with 3 vertices, 5 edges>
gap> grs[3] := Digraph([
> [6, 7], [6, 9], [1, 3, 4, 5, 8, 9],
> [1, 2, 3, 4, 5, 6, 7, 10], [1, 5, 6, 7, 10], [2, 4, 5, 9, 10],
> [3, 4, 5, 6, 7, 8, 9, 10], [1, 3, 5, 7, 8, 9], [1, 2, 5],
> [1, 2, 4, 6, 7, 8]]);
<digraph with 10 vertices, 51 edges>
gap> filename := Concatenation(DIGRAPHS_Dir(), "/tst/out/man.d6.gz");;
gap> WriteDigraphs(filename, grs, "w");
IO_OK
gap> ReadDigraphs(filename);
[ <digraph with 0 vertices, 0 edges>,
  <digraph with 3 vertices, 5 edges>,
  <digraph with 10 vertices, 51 edges> ]
```

9.2.6 IteratorFromDigraphFile

▷ IteratorFromDigraphFile(*filename[, decoder]*) (function)

Returns: An iterator.

If *filename* is a string representing the name of a file containing encoded digraphs, then IteratorFromDigraphFile returns an iterator for which the value of NextIterator (**Reference: NextIterator**) is the next digraph encoded in the file.

If the optional argument *decoder* is specified and is a function which decodes a string into a digraph, then IteratorFromDigraphFile will use *decoder* to decode the digraphs contained in *filename*.

The purpose of this function is to easily allow looping over digraphs encoded in a file when loading all of the encoded digraphs would require too much memory.

To see what file types are available, see WriteDigraphs (9.2.5).

Example

```
gap> filename := Concatenation(DIGRAPHS_Dir(), "/tst/out/man.d6.gz");;
gap> file := DigraphFile(filename, "w");;
gap> for i in [1 .. 10] do
>   WriteDigraphs(file, Digraph([[1, 3], [2], [1, 2]]));
> od;
gap> IO_Close(file);;
gap> iter := IteratorFromDigraphFile(filename);
<iterator>
gap> for x in iter do od;
```

9.2.7 DigraphPlainTextLineEncoder

▷ DigraphPlainTextLineEncoder(*delimiter1[, delimiter2], offset*) (function)

▷ DigraphPlainTextLineDecoder(*delimiter1[, delimiter2], offset*) (function)

Returns: A string.

These two functions return a function which encodes or decodes a digraph in a plain text format.

DigraphPlainTextLineEncoder returns a function which takes a single digraph as an argument. The function returns a string describing the edges of that digraph; each edge is written as a pair of integers separated by the string *delimiter2*, and the edges themselves are separated by the string *delimiter1*. *DigraphPlainTextLineDecoder* returns the corresponding decoder function, which takes a string argument in this format and returns a digraph.

If only one delimiter is passed as an argument to *DigraphPlainTextLineDecoder*, it will return a function which decodes a single edge, returning its contents as a list of integers.

The argument *offset* should be an integer, which will describe a number to be added to each vertex before it is encoded, or after it is decoded. This may be used, for example, to label vertices starting at 0 instead of 1.

Note that the number of vertices of a digraph is not stored, and so vertices which are not connected to any edge may be lost.

Example

```
gap> gr := Digraph([[2, 3], [1], [1]]);
<digraph with 3 vertices, 4 edges>
gap> enc := DigraphPlainTextLineEncoder("  ", " ", -1);;
gap> dec := DigraphPlainTextLineDecoder("  ", " ", 1);;
gap> enc(gr);
"0 1  0 2  1 0  2 0"
```

```
gap> dec(last);
<digraph with 3 vertices, 4 edges>
```

9.2.8 TournamentLineDecoder

▷ `TournamentLineDecoder(`*str*`)` (function)

Returns: A digraph.

This function takes a string *str*, decodes it, and then returns the tournament [see `IsTournament` (6.1.11)] which it defines, according to the following rules.

The characters of the string *str* represent the entries in the upper triangle of a tournament's adjacency matrix. The number of vertices `n` will be detected from the length of the string and will be as large as possible.

The first character represents the possible edge `1 -> 2`, the second represents `1 -> 3` and so on until `1 -> n`; then the following character represents `2 -> 3`, and so on up to the character which represents the edge `n-1 -> n`.

If a character of the string with corresponding edge `i -> j` is equal to `1`, then the edge `i -> j` is present in the tournament. Otherwise, the edge `i -> j` is present instead. In this way, all the possible edges are encoded one-by-one.

Example

```
gap> gr := TournamentLineDecoder("100001");
<digraph with 4 vertices, 6 edges>
gap> OutNeighbours(gr);
[ [ 2 ], [  ], [ 1, 2, 4 ], [ 1, 2 ] ]
```

9.2.9 AdjacencyMatrixUpperTriangleLineDecoder

▷ `AdjacencyMatrixUpperTriangleLineDecoder(`*str*`)` (function)

Returns: A digraph.

This function takes a string *str*, decodes it, and then returns the topologically sorted digraph [see `DigraphTopologicalSort` (5.1.7)] which it defines, according to the following rules.

The characters of the string *str* represent the entries in the upper triangle of a digraph's adjacency matrix. The number of vertices `n` will be detected from the length of the string and will be as large as possible.

The first character represents the possible edge `1 -> 2`, the second represents `1 -> 3` and so on until `1 -> n`; then the following character represents `2 -> 3`, and so on up to the character which represents the edge `n-1 -> n`. If a character of the string with corresponding edge `i -> j` is equal to `1`, then this edge is present in the digraph. Otherwise, it is not present. In this way, all the possible edges are encoded one-by-one.

In particular, note that there exists no edge `[i, j]` if $j \leq i$. In order words, the digraph will be topologically sorted.

Example

```
gap> gr := AdjacencyMatrixUpperTriangleLineDecoder("100001");
<digraph with 4 vertices, 2 edges>
gap> OutNeighbours(gr);
[ [ 2 ], [  ], [ 4 ], [  ] ]
gap> gr := AdjacencyMatrixUpperTriangleLineDecoder("111111x111");
<digraph with 5 vertices, 9 edges>
```

```
gap> OutNeighbours(gr);
[ [ 2, 3, 4, 5 ], [ 3, 4 ], [ 4, 5 ], [ 5 ], [  ] ]
```

9.2.10 TCodeDecoder

▷ TCodeDecoder(*str*) (function)

Returns: A digraph.

If *str* is a string consisting of at least two non-negative integers separated by spaces, then this function will attempt to return the digraph which it defines as a TCode string.

The first integer of the string defines the number of vertices v in the digraph, and the second defines the number of edges e. The following 2e integers should be vertex numbers in the range [0 .. v-1]. These integers are read in pairs and define the digraph's edges. This function will return an error if *str* has fewer than 2e+2 entries.

Note that the vertex numbers will be incremented by 1 in the digraph returned. Hence the string fragment 0 6 will describe the edge [1,7].

Example

```
gap> gr := TCodeDecoder("3 2 0 2 2 1");
<digraph with 3 vertices, 2 edges>
gap> OutNeighbours(gr);
[ [ 3 ], [  ], [ 2 ] ]
gap> gr := TCodeDecoder("12 3 0 10 5 2 8 8");
<digraph with 12 vertices, 3 edges>
gap> OutNeighbours(gr);
[ [ 11 ], [  ], [  ], [  ], [  ], [ 3 ], [  ], [  ], [ 9 ], [  ],
  [  ], [  ] ]
```

9.2.11 PlainTextString

▷ PlainTextString(*digraph*) (operation)

▷ DigraphFromPlainTextString(*s*) (operation)

Returns: A string.

PlainTextString takes a single digraph, and returns a string describing the edges of that digraph. *DigraphFromPlainTextString* takes such a string and returns the digraph which it describes. Each edge is written as a pair of integers separated by a single space. The edges themselves are separated by a double space. Vertex numbers are reduced by 1 when they are encoded, so that vertices in the string are labelled starting at 0.

Note that the number of vertices of a digraph is not stored, and so vertices which are not connected to any edge may be lost.

Example

```
gap> gr := Digraph([[2, 3], [1], [1]]);
<digraph with 3 vertices, 4 edges>
gap> PlainTextString(gr);
"0 1  0 2  1 0  2 0"
gap> DigraphFromPlainTextString(last);
<digraph with 3 vertices, 4 edges>
```

9.2.12 WritePlainTextDigraph

▷ WritePlainTextDigraph(*filename, digraph, delimiter, offset*) (function)
▷ ReadPlainTextDigraph(*filename, delimiter, offset, ignore*) (function)

These functions write and read a single digraph in a human-readable plain text format as follows: each line contains a single edge, and each edge is written as a pair of integers separated by the string *delimiter*.

filename should be the name of a file which will be written to or read from, and *offset* should be an integer which is added to each vertex number as it is written or read. For example, if WritePlainTextDigraph is called with *offset* -1, then the vertices will be numbered in the file starting from 0 instead of 1 - ReadPlainTextDigraph would then need to be called with *offset* 1 to convert back to the original graph.

ignore should be a list of characters which will be ignored when reading the graph.

Example

```
gap> gr := Digraph([[1, 2, 3], [1, 1], [2]]);
<multidigraph with 3 vertices, 6 edges>
gap> filename := Concatenation(DIGRAPHS_Dir(), "/tst/out/plain.txt");;
gap> WritePlainTextDigraph(filename, gr, ",", -1);
gap> ReadPlainTextDigraph(filename, ",", 1, ['/', '%']);
<multidigraph with 3 vertices, 6 edges>
```

9.2.13 WriteDIMACSDigraph

▷ WriteDIMACSDigraph(*filename, digraph*) (operation)
▷ ReadDIMACSDigraph(*filename*) (operation)

These operations write or read the single symmetric digraph *digraph* to or from a file in DIMACS format, as appropriate. The operation WriteDIMACSDigraph records the vertices and edges of *digraph*. The vertex labels of *digraph* will be recorded only if they are integers. See IsSymmetricDigraph (6.1.10) and DigraphVertexLabels (5.1.9).

The first argument *filename* should be the name of the file which will be written to or read from. A file can contain one symmetric digraph in DIMACS format. If *filename* ends in one of .gz, .bz2, or .xz, then the file is compressed, or decompressed, appropriately.

The DIMACS format is described as follows. Each line in the DIMACS file has one of four types:

- A line beginning with c and followed by any number of characters is a comment line, and is ignored.
- A line beginning with p defines the numbers of vertices and edges the digraph. This line has the format p edge <nr_vertices> <nr_edges>, where <nr_vertices> and <nr_edges> are replaced by the relevant integers. There must be exactly one such line in the file, and it must occur before any of the following kinds of line.

  Although it is required to be present, the value of <nr_edges> will be ignored. The correct number of edges will be deduced from the rest of the information in the file.
- A line of the form e <v> <w>, where <v> and <w> are integers in the range [1 .. <nr_vertices>], specifies that there is a (symmetric) edge in the digraph between the ver-

tices <v> and <w>. A symmetric edge only needs to be defined once; an additional line e <v> <w>, or e <w> <v>, will be interpreted as an additional, multiple, edge. Loops are permitted.

- A line of the form n <v> <label>, where <v> is an integer in the range [1 .. <nr_vertices>] and <label> is an integer, signifies that the vertex <v> has the label <label> in the digraph. If a label is not specified for a vertex, then ReadDIMACSDigraph will assign the label 1, according to the DIMACS specification.

A detailed definition of the DIMACS format can be found at http://mat.gsia.cmu.edu/COLOR/general/ccformat.ps, in Section 2.1. Note that optional descriptor lines, as described in Section 2.1, will be ignored.

Example

```
gap> gr := Digraph([[2], [1, 3, 4], [2, 4], [2, 3]]);
<digraph with 4 vertices, 8 edges>
gap> filename := Concatenation(DIGRAPHS_Dir(),
>                              "/tst/out/dimacs.dimacs");;
gap> WriteDIMACSDigraph(filename, gr);;
gap> ReadDIMACSDigraph(filename);
<digraph with 4 vertices, 8 edges>
```

Appendix A

Grape to Digraphs Command Map

Below is a table of Grape commands with the Digraphs counterparts. The sections in this chapter correspond to the chapters in the Grape manual.

A.1 Functions to construct and modify graphs

The table in this section contains more information when viewed in html format.

Grape command	Digraphs command	
`Graph`	`Digraph` (3.1.5)	
`EdgeOrbitsGraph`	`EdgeOrbitsDigraph` (3.1.8)	
`NullGraph`	`NullDigraph` (3.5.6)	
`CompleteGraph`	`CompleteDigraph` (3.5.2)	
`JohnsonGraph`	`JohnsonDigraph` (3.5.7)	
`CayleyGraph`	`CayleyDigraph` (3.1.10)	
`AddEdgeOrbit`	`DigraphAddEdgeOrbit` (3.3.16)	
`RemoveEdgeOrbit`	`DigraphRemoveEdgeOrbit` (3.3.21)	
`AssignVertexNames`	`SetDigraphVertexLabels` (5.1.9)	

A.2 Functions to inspect graphs, vertices and edges

The table in this section contains more information when viewed in html format.

Grape command	Digraphs command	
IsGraph	IsDigraph (3.1.1)	
OrderGraph	DigraphNrVertices (5.1.2)	
IsVertex(*graph*, *v*)	*v* in DigraphVertices(*digraph*)	
VertexName	DigraphVertexLabel (5.1.8)	
VertexNames	DigraphVertexLabels (5.1.9)	
Vertices	DigraphVertices (5.1.1)	
VertexDegree	OutDegreeOfVertex (5.2.10)	
VertexDegrees	OutDegreeSet (5.2.8)	
IsLoopy	DigraphHasLoops (6.1.1)	
IsSimpleGraph	IsSymmetricDigraph (6.1.10)	
Adjacency	OutNeighboursOfVertex (5.2.11)	
IsEdge	IsDigraphEdge (5.1.14)	
DirectedEdges	DigraphEdges (5.1.3)	
UndirectedEdges	None	
Distance	DigraphShortestDistance (5.3.2)	
Diameter	DigraphDiameter (5.3.1)	
Girth	DigraphUndirectedGirth (5.3.7)	
IsConnectedGraph	IsStronglyConnectedDigraph (6.3.5)	
IsBipartite	IsBipartiteDigraph (6.1.3)	
IsNullGraph	IsNullDigraph (6.1.6)	
IsCompleteGraph	IsCompleteDigraph (6.1.5)	

A.3 Functions to determine regularity properties of graphs

The table in this section contains more information when viewed in html format.

Grape command	Digraphs command	
IsRegularGraph	IsOutRegularDigraph (6.2.2)	
LocalParameters	None	
GlobalParameters	None	
IsDistanceRegular	IsDistanceRegularDigraph (6.2.4)	
CollapsedAdjacencyMat	None	
OrbitalGraphColadjMats	None	
VertexTransitiveDRGs	None	

A.4 Some special vertex subsets of a graph

The table in this section contains more information when viewed in html format.

Grape command	Digraphs command	
ConnectedComponent	DigraphConnectedComponent (5.3.9)	
ConnectedComponents	DigraphConnectedComponents (5.3.8)	
Bicomponents	DigraphBicomponents (5.3.12)	
DistanceSet	DigraphDistanceSet (5.3.5)	
Layers	DigraphLayers (5.3.22)	
IndependentSet	DigraphIndependentSet (8.2.2)	

A.5 Functions to construct new graphs from old

The table in this section contains more information when viewed in html format.

Grape command	Digraphs command	
InducedSubgraph	InducedSubdigraph (3.3.2)	
DistanceSetInduced	None	
DistanceGraph	DistanceDigraph (3.3.34)	
ComplementGraph	DigraphDual (3.3.9)	
PointGraph	None	
EdgeGraph	EdgeUndirectedDigraph (3.3.30)	
SwitchedGraph	None	
UnderlyingGraph	DigraphSymmetricClosure (3.3.10)	
QuotientGraph	QuotientDigraph (3.3.7)	
BipartiteDouble	BipartiteDoubleDigraph (3.3.32)	
GeodesicsGraph	None	
CollapsedIndependentOrbitsGraph	None	
CollapsedCompleteOrbitsGraph	None	
NewGroupGraph	None	

A.6 Vertex-Colouring and Complete Subgraphs

The table in this section contains more information when viewed in html format.

Grape command	Digraphs command	
VertexColouring	DigraphGreedyColouring (7.3.14)	
CompleteSubgraphs	DigraphCliques (8.1.4)	
CompleteSubgraphsOfGivenSize	DigraphCliques (8.1.4)	

A.7 Automorphism groups and isomorphism testing for graphs

The table in this section contains more information when viewed in html format.

Grape command	Digraphs command	
AutGroupGraph	AutomorphismGroup (7.2.2)	
GraphIsomorphism	IsomorphismDigraphs (7.2.16)	
IsIsomorphicGraph	IsIsomorphicDigraph (7.2.14)	
GraphIsomorphismClassRepresentatives	None	

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